

# Formalizing and Enforcing Purpose Restrictions in Privacy Policies

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18734: Foundations of Privacy

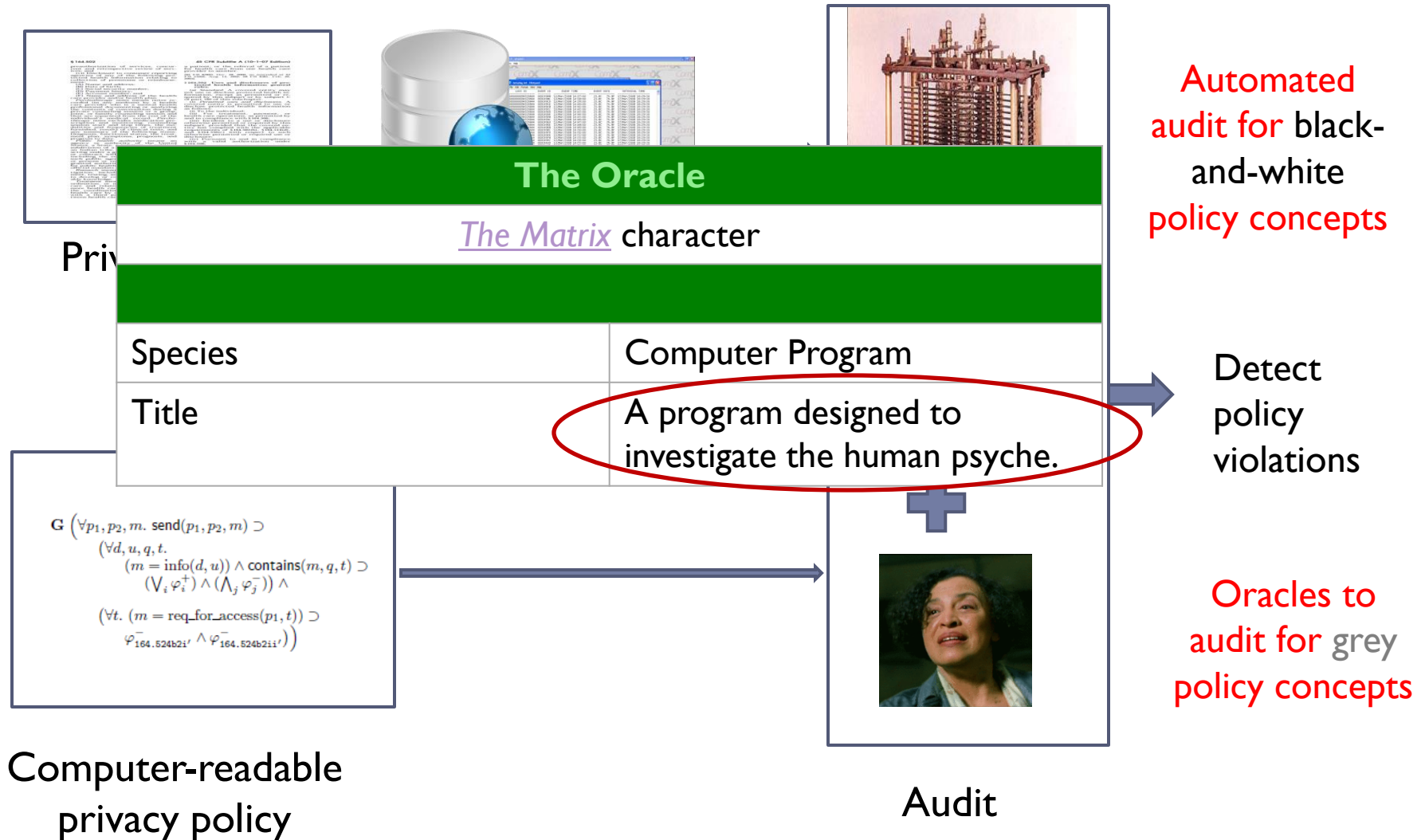
Fall 2014

# Logistics

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- ▶ Homework is out
  - ▶ Claim account on possibility and get started

# Detecting Policy Violations



# Purpose Restrictions in Privacy Policies

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Not  
for

- ▶ Yahoo!'s practice is **not** to use the content of messages [...] **for** marketing **purposes**.

Only  
for

- ▶ By providing your personal information, you give [Social Security Administration] consent to use the information **only for** the **purpose** for which it was collected.

# Purpose Restrictions are Ubiquitous

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- ▶ OECD's Privacy Guidelines
- ▶ US Privacy Laws
  - ▶ HIPAA, GLBA, FERPA, COPPA,...
- ▶ EU Privacy Directive
- ▶ Organizational Privacy Policies
  - ▶ Google, Facebook, Yahoo,...
  - ▶ Hospitals, banks, educational institutions, govt
  - ▶ Defense: Mission-based information access

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# Purpose Restrictions on Actions

With M. C. Tschantz (CMU → Berkeley) and  
J. M. Wing (CMU → MSR)

2012 IEEE Symposium on Security & Privacy

# Goal

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- ▶ Give a semantics to
  - ▶ **“Not for”** purpose restrictions
  - ▶ **“Only for”** purpose restrictionsthat is parametric in the purpose
- Provide automated enforcement of purpose restrictions for that semantics

X-ray taken

Send record

No diagnosis  
by drug company



Add X-ray



Medical  
Record

Med records  
used only for  
diagnosis

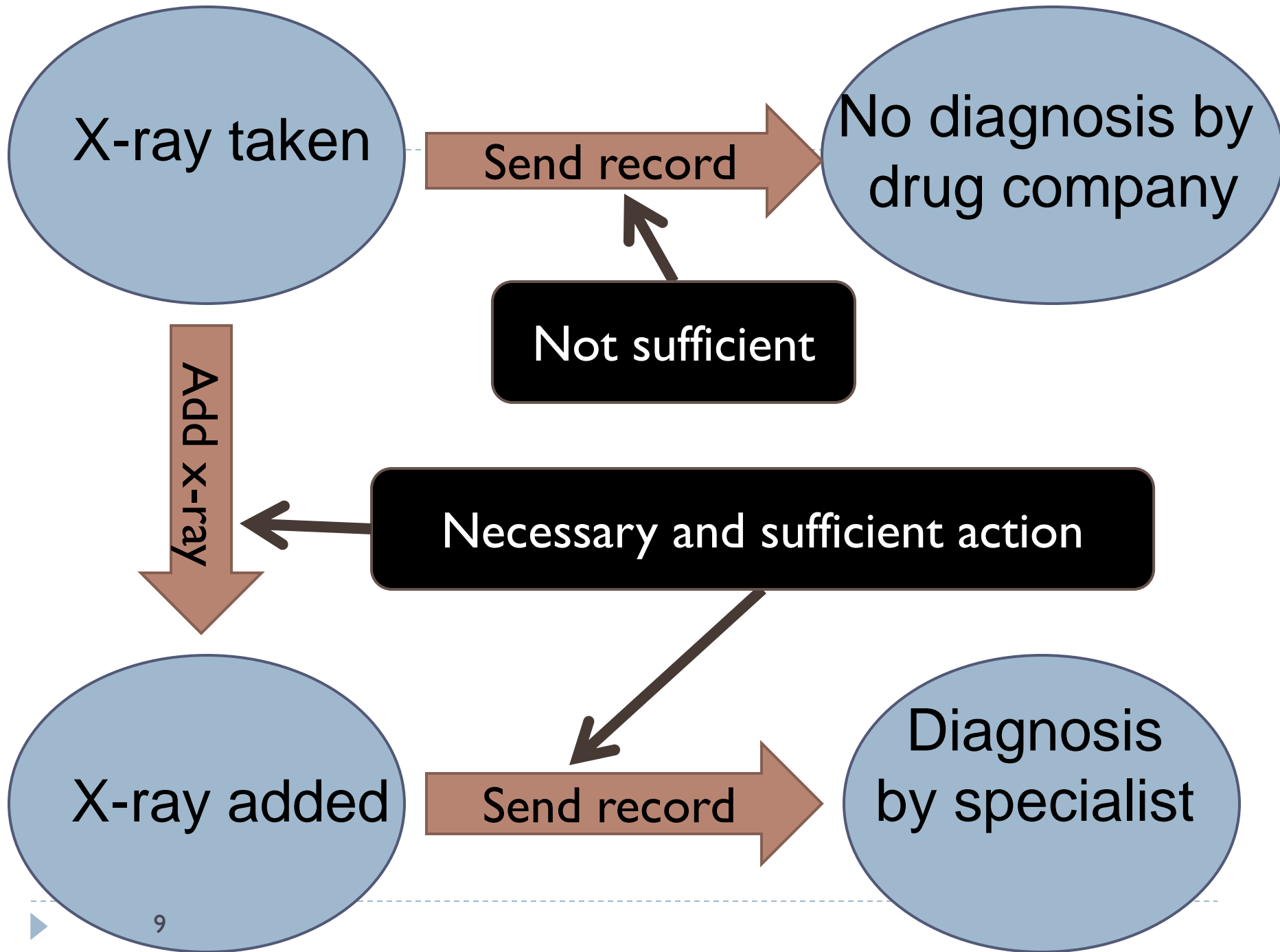


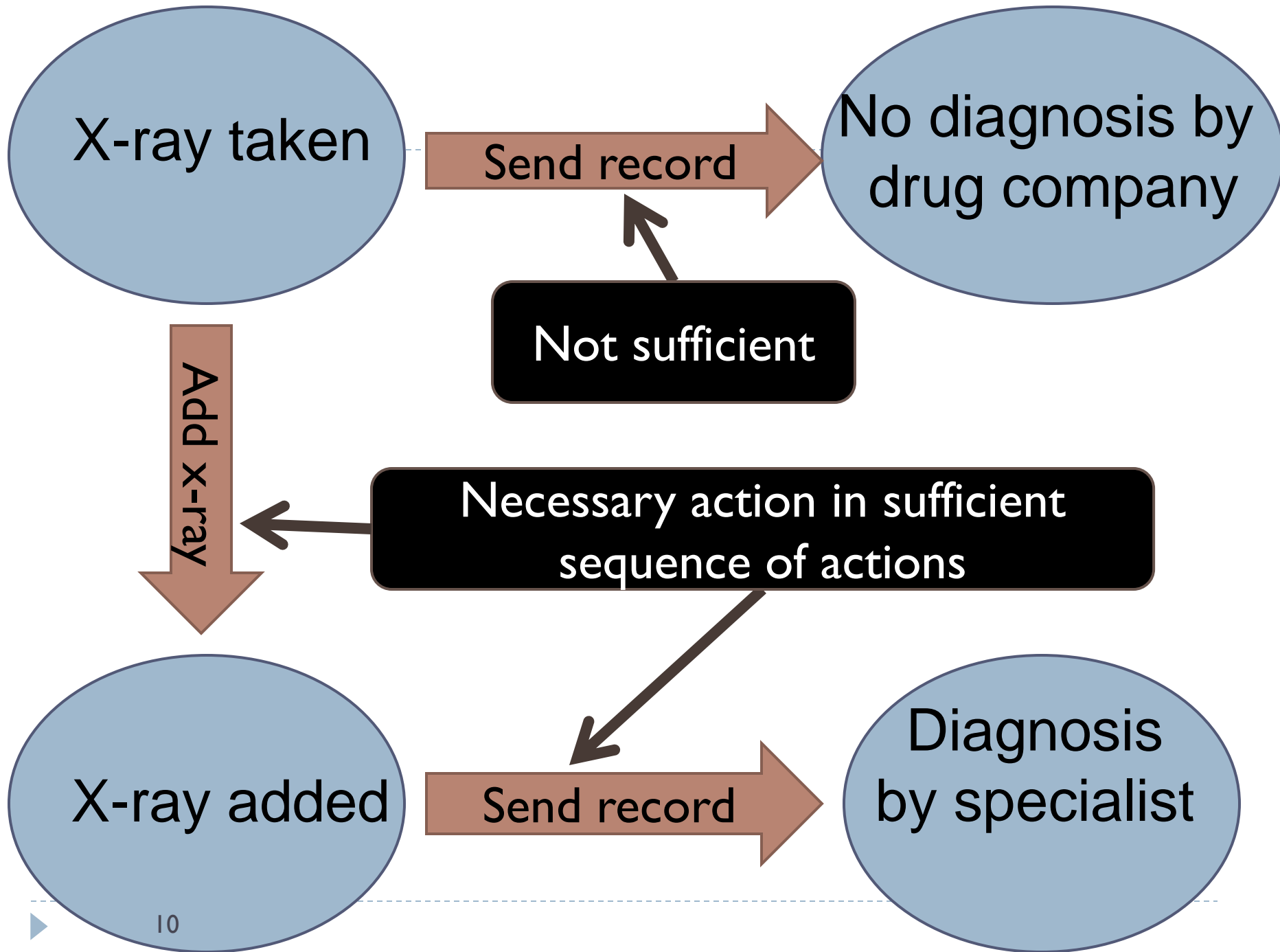
X-ray added

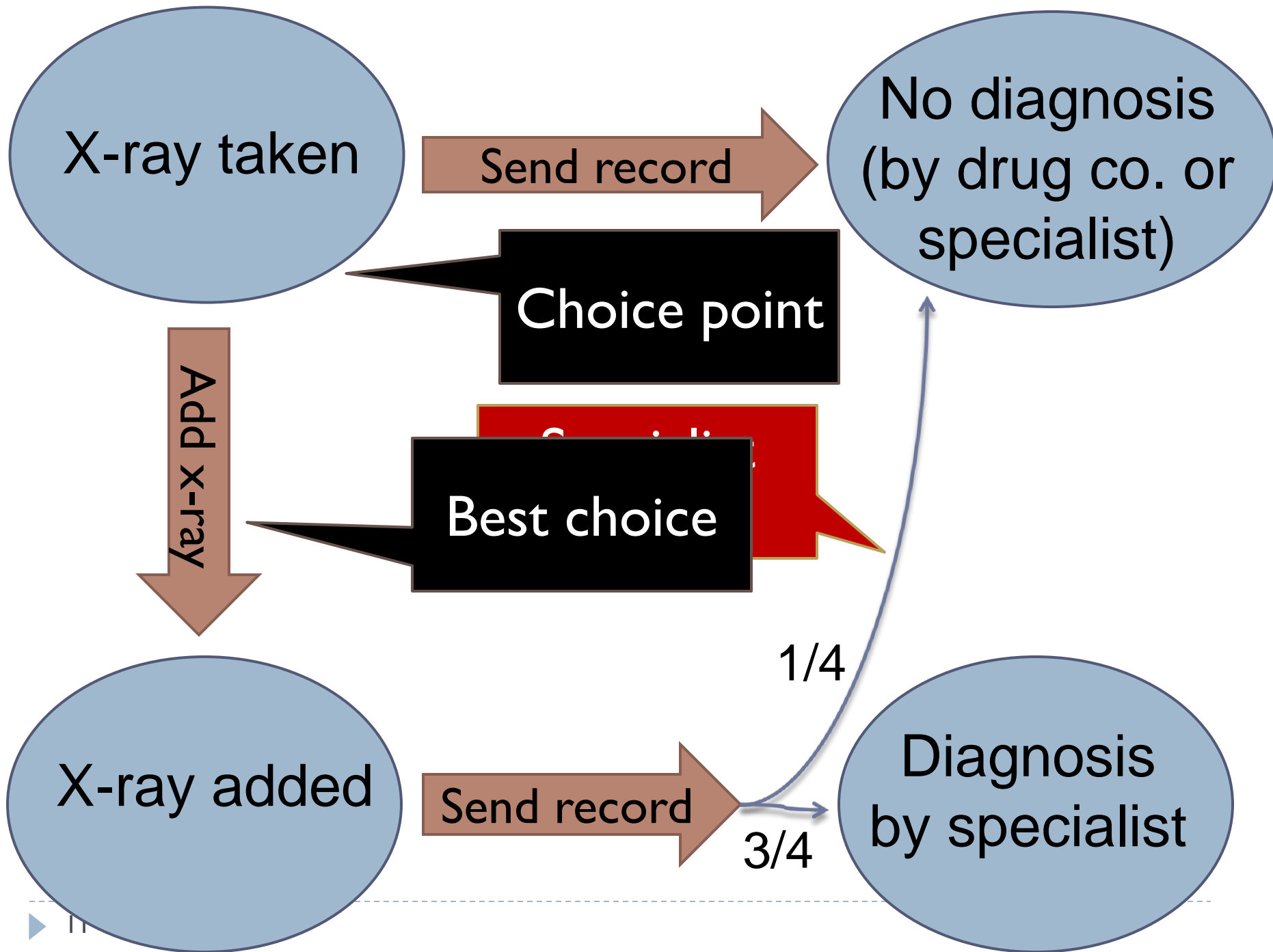
Send record

Diagnosis  
by specialist







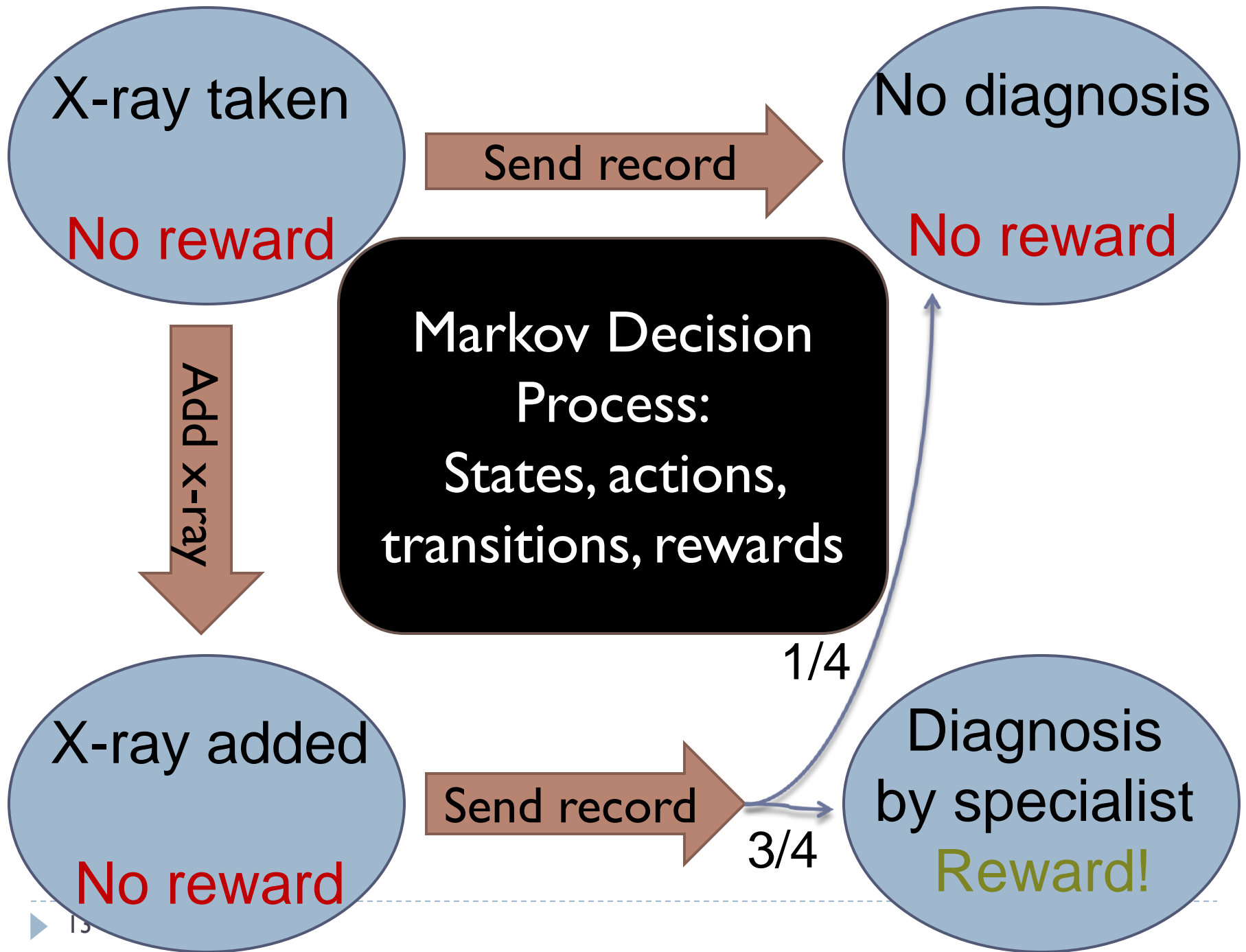


# Planning

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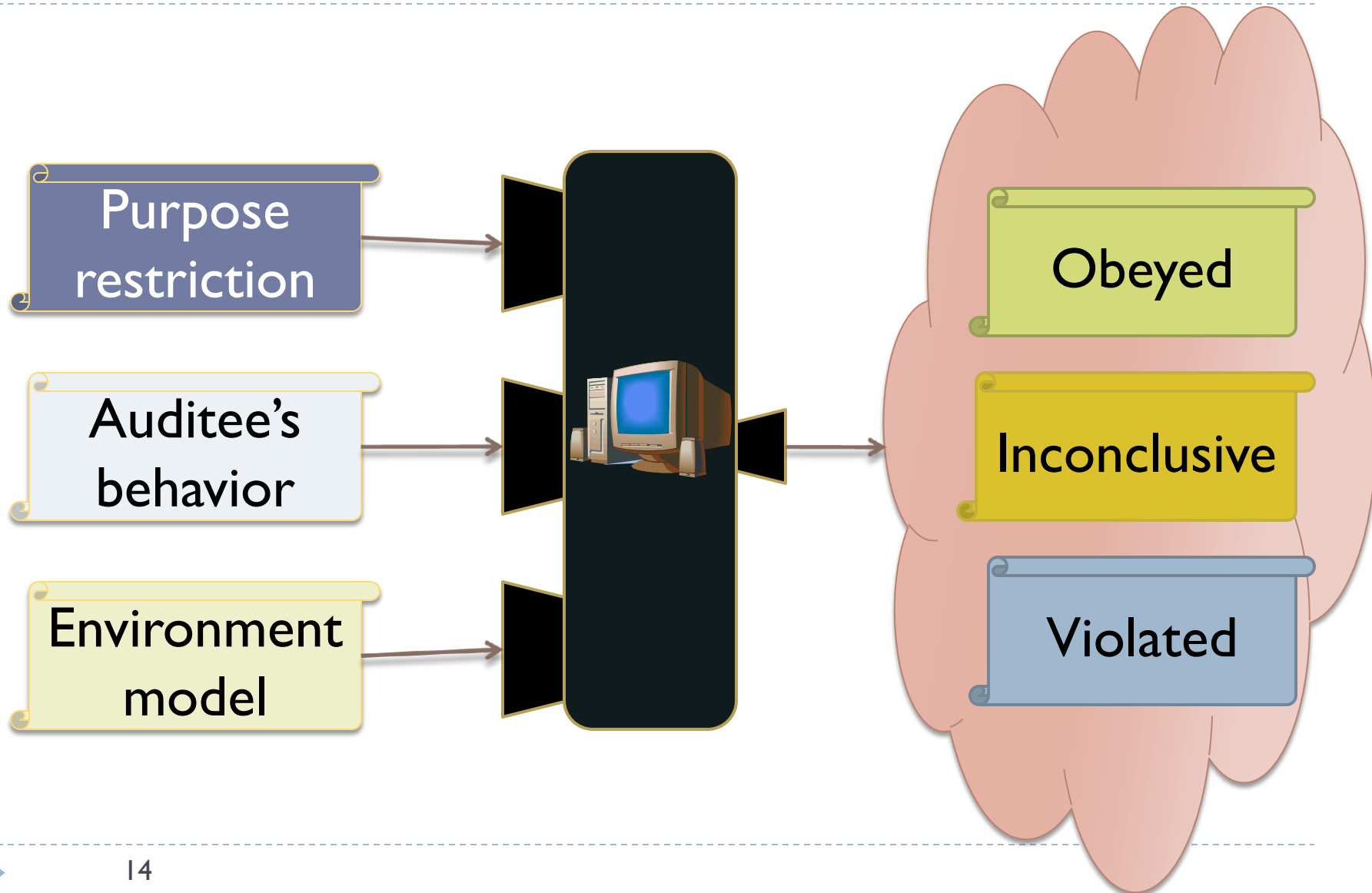
**Thesis:** An action is for a purpose iff that action is part of a plan for furthering the purpose

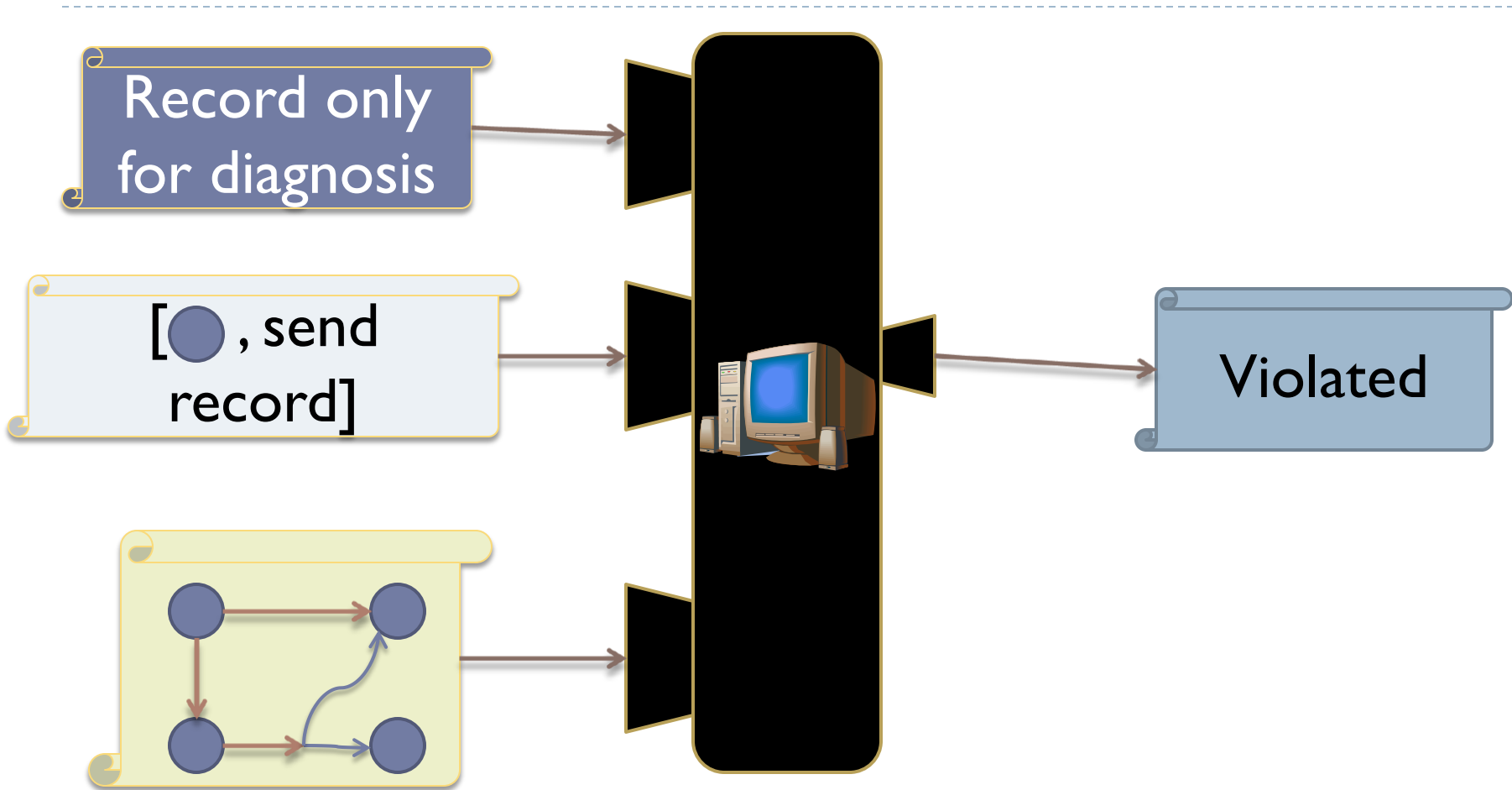
i.e., always makes the best choice for furthering the purpose

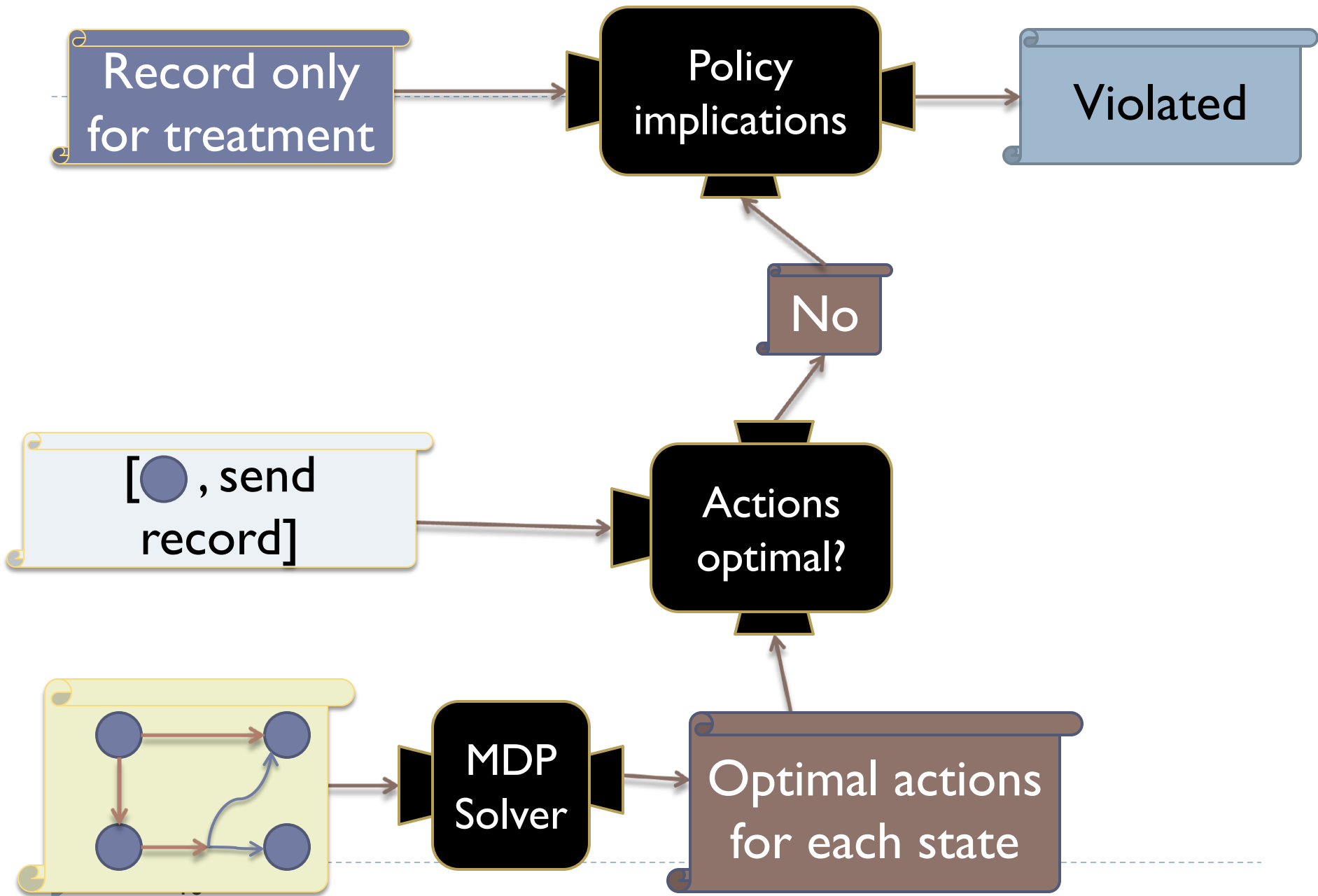


# Auditing

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# No False Positives

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- ▶ Theorem (Soundness):

If the algorithm returns “violation”, then the actions recorded in the log are not only for the purpose

# Utility + Privacy

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- ▶ Learn MDPs from large audit logs
  - ▶ E.g., using reinforcement learning techniques
- ▶ Compute optimal plans in MDP
  - ▶ Improve functional outcomes (e.g, healthcare outcomes, corporate/defense mission)
  - ▶ Improve privacy/security (e.g., detect inappropriate accesses to sensitive information by authorized insiders)

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# Purpose Restrictions on Information Use

With M. C. Tschantz (CMU → Berkeley) and  
J. M. Wing (CMU → MSR)

2013 European Symposium on Research in Computer  
Security





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Visit For Treatment Info & Facts.

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Party Favors Sale

Party Decorations

Birthday Party Supplies

Halloween Party Supplies

# Google's Privacy Policy

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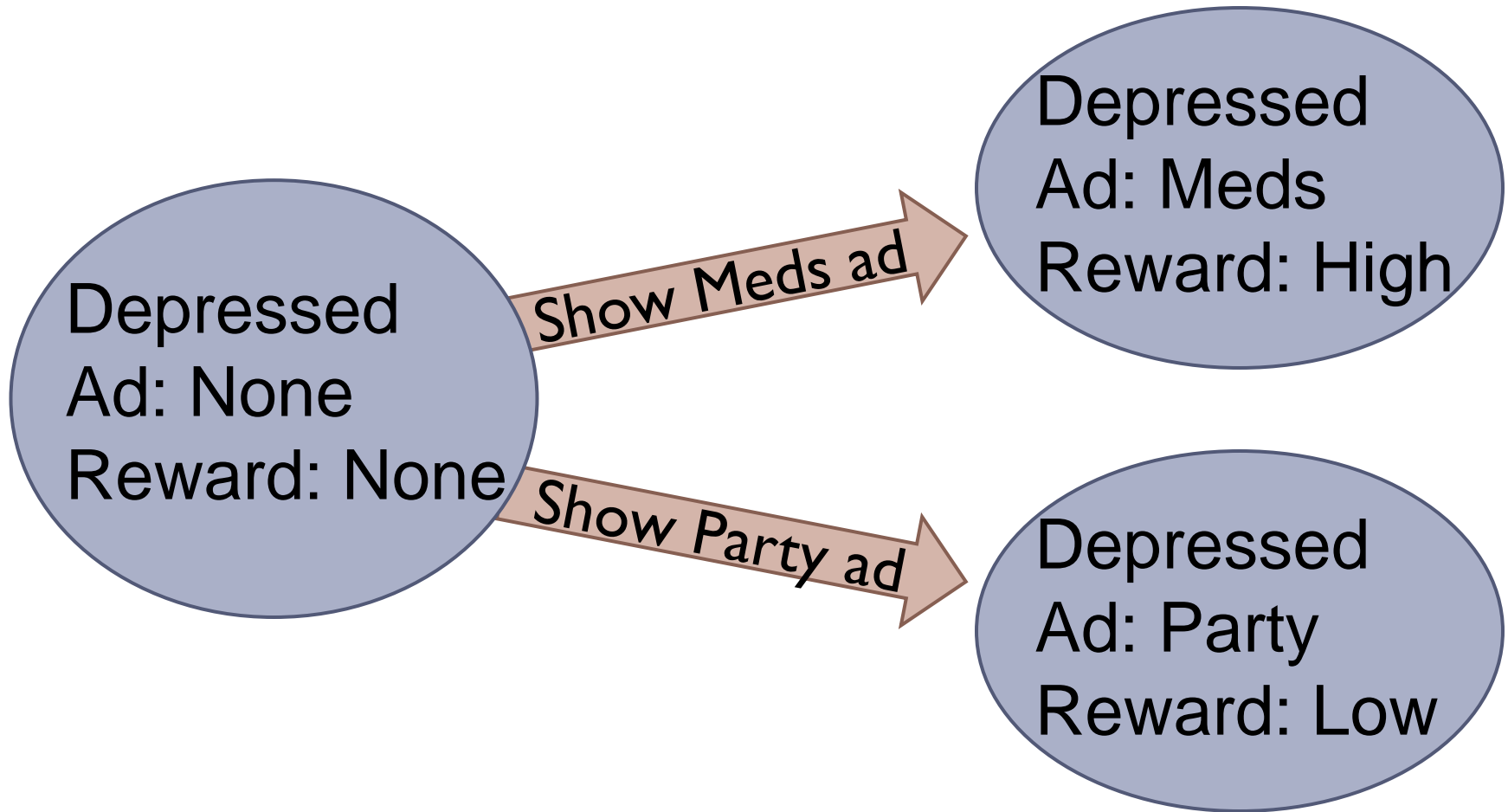
When showing you tailored ads, we will not associate a cookie or anonymous identifier with sensitive categories, such as those based on race, religion, sexual orientation or health.

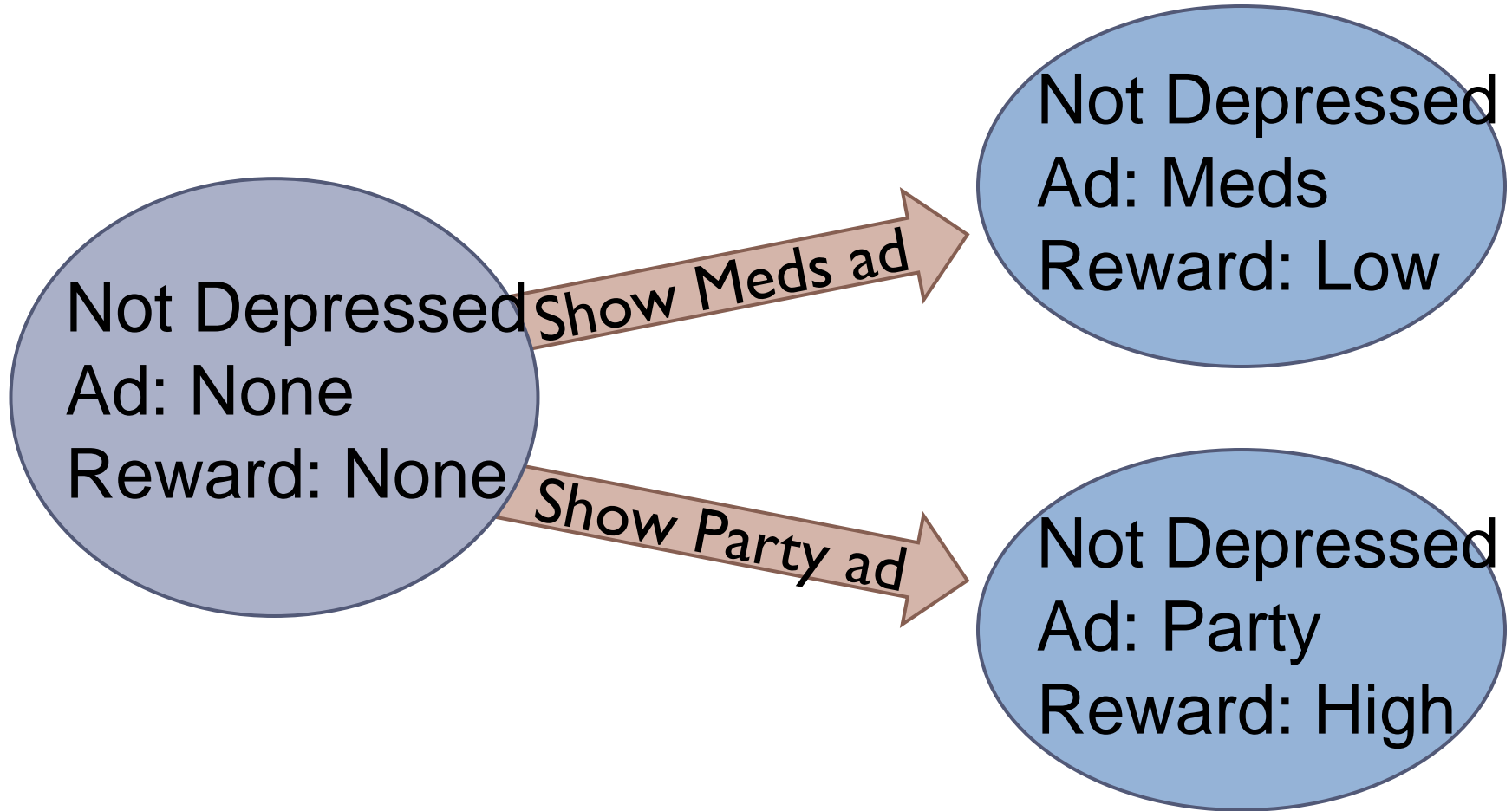
# Rewards from ads

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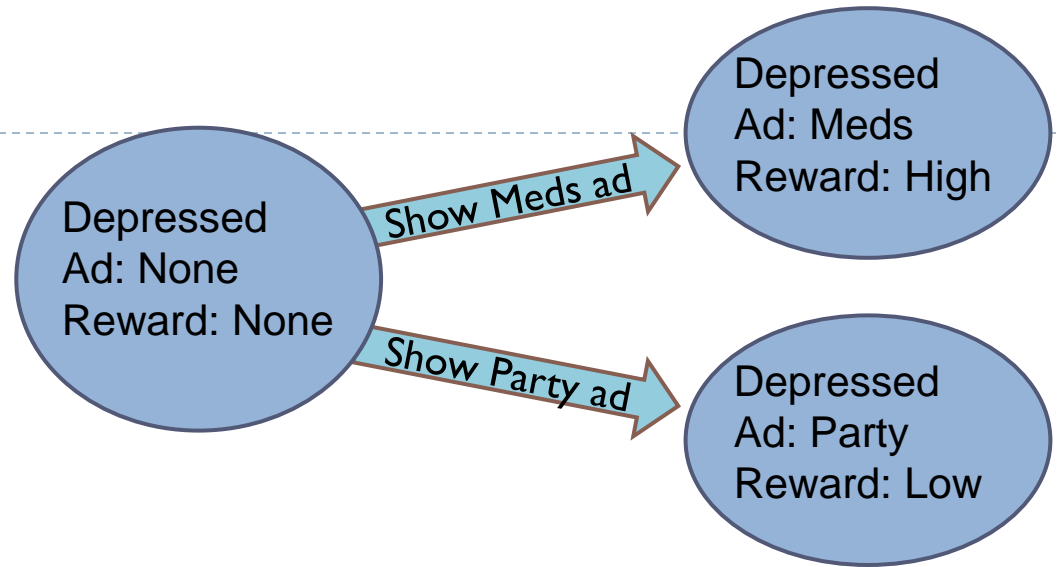
	<b>Depressed</b>	<b>Not Depressed</b>
<b>Meds</b>	High	Low
<b>Party</b>	Low	High





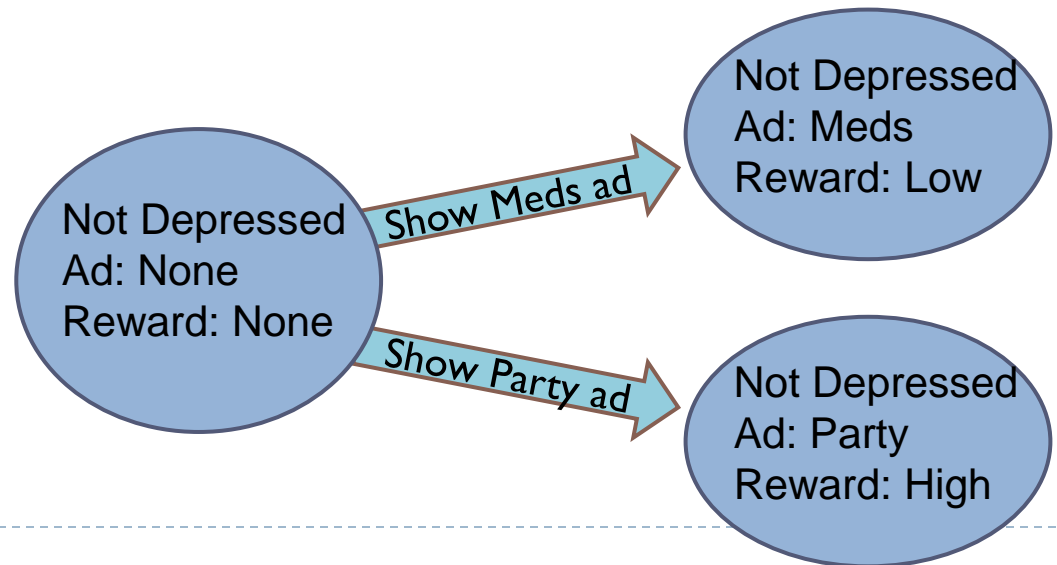


# Depressed Case

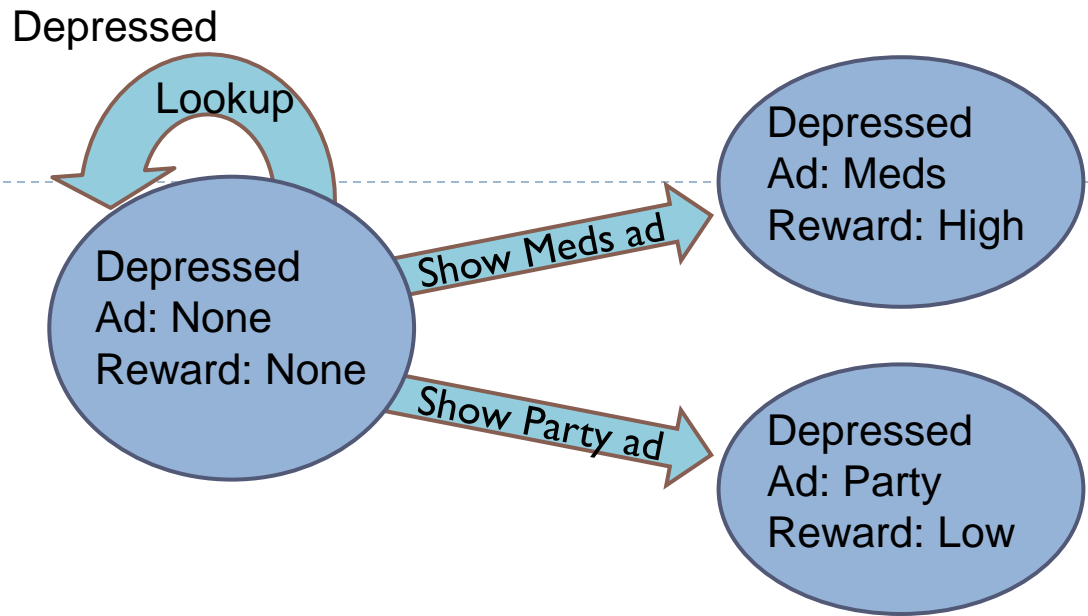


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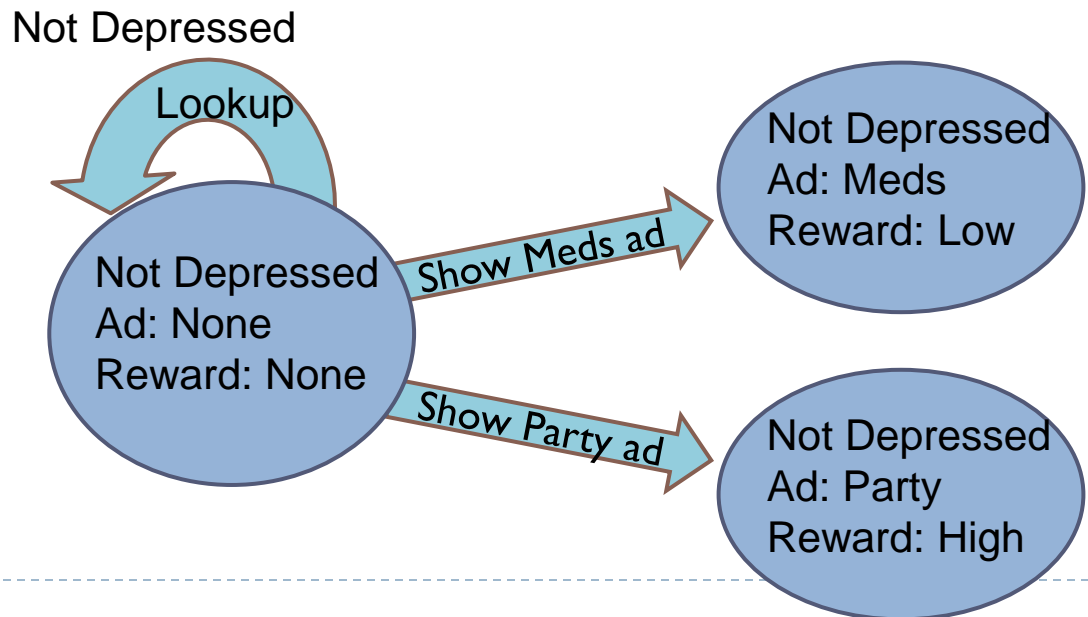
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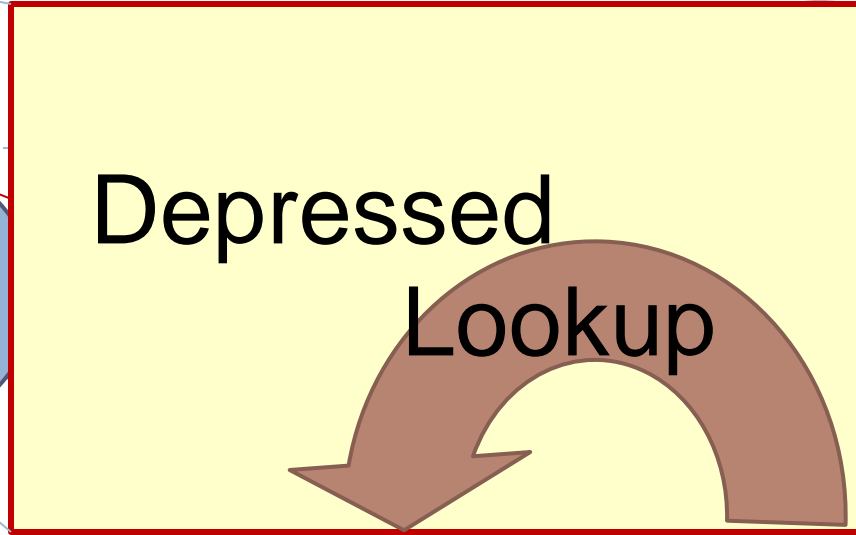
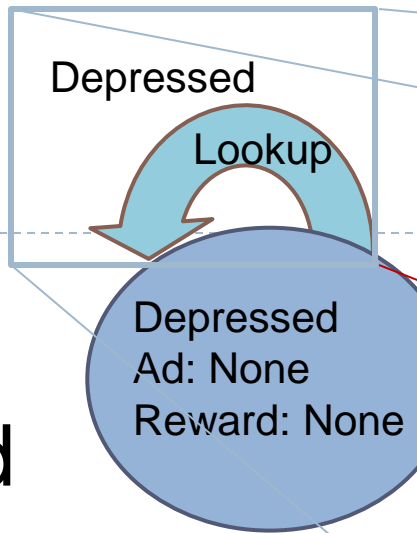
# Depressed Case



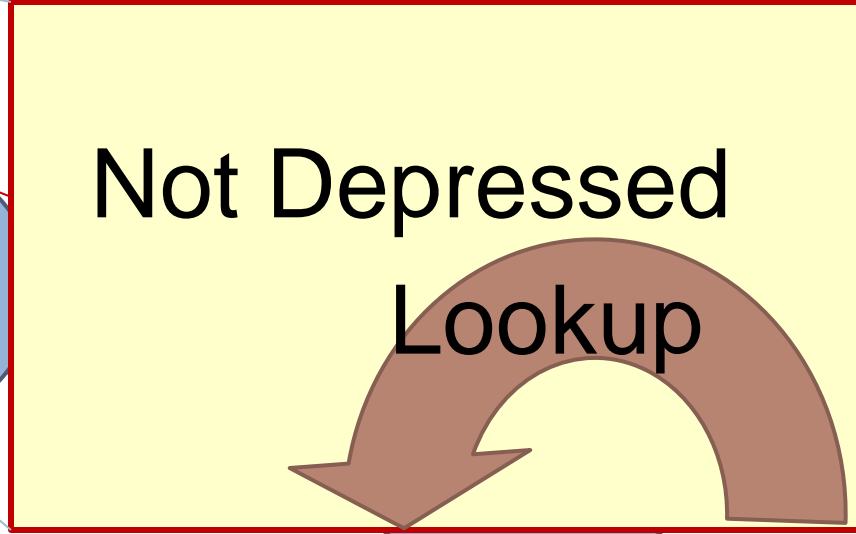
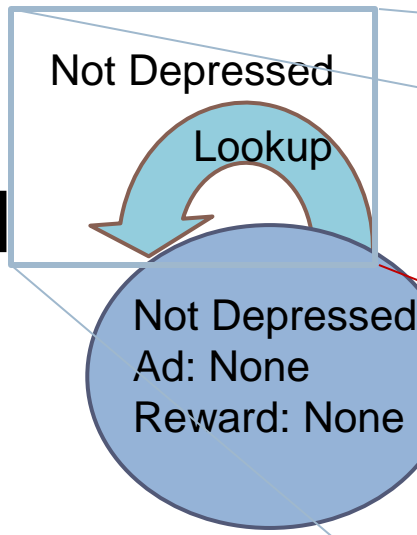
# Not Depressed Case



Depressed  
Case



Not  
Depressed  
Case



Initial Beliefs

Depressed Case: 10%

Not Depressed Case: 90%

Lookup

Depressed

Updated Beliefs

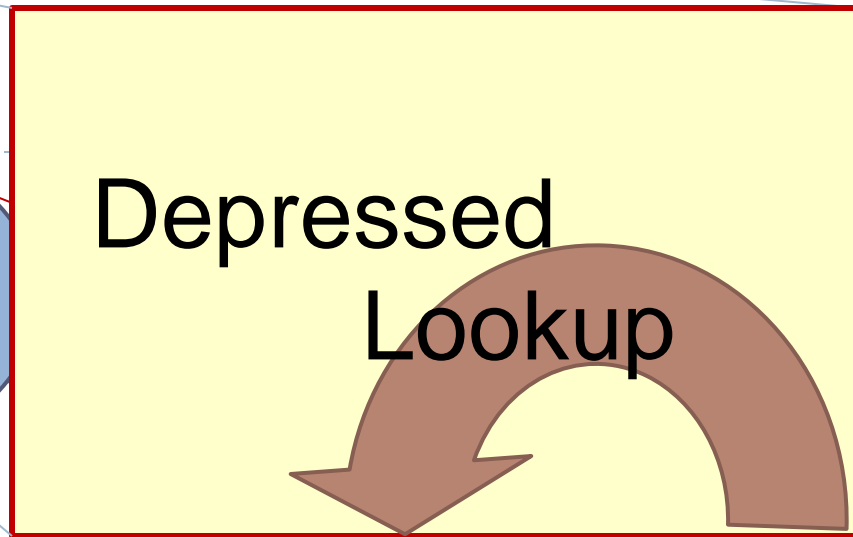
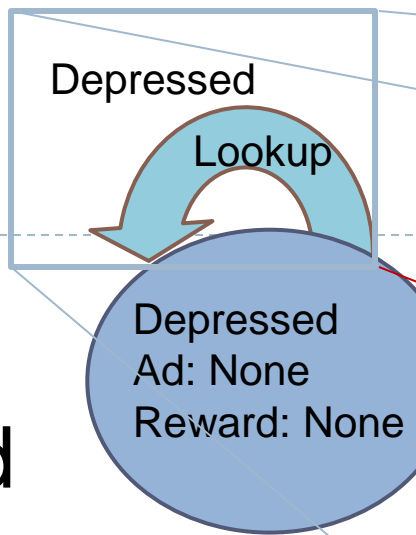
Depressed Case: 100%

Not Depressed Case: 0%

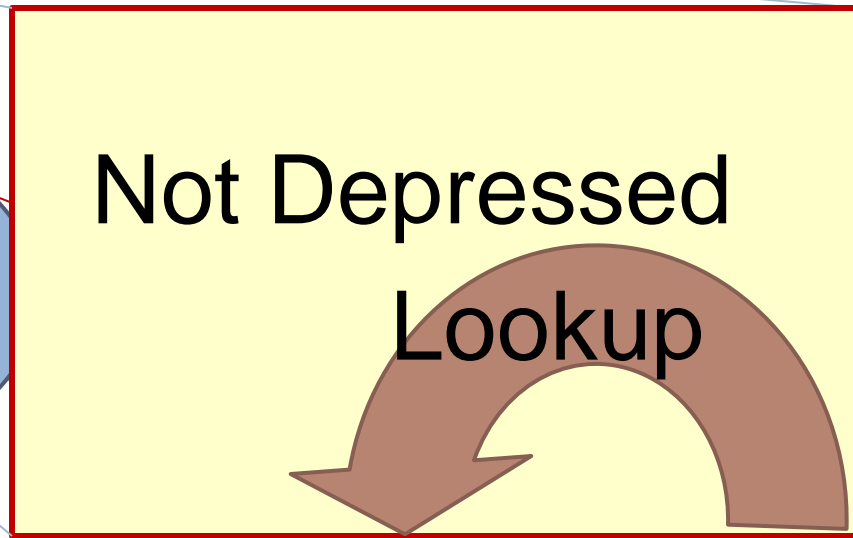
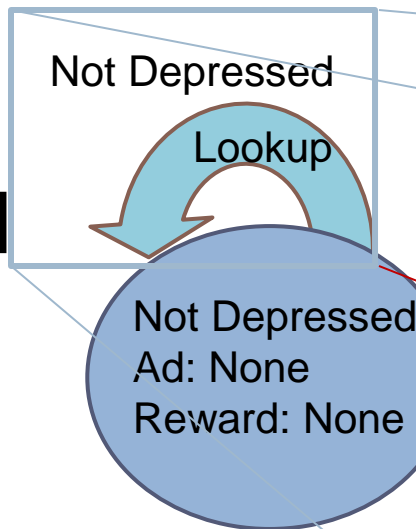
Meds

30

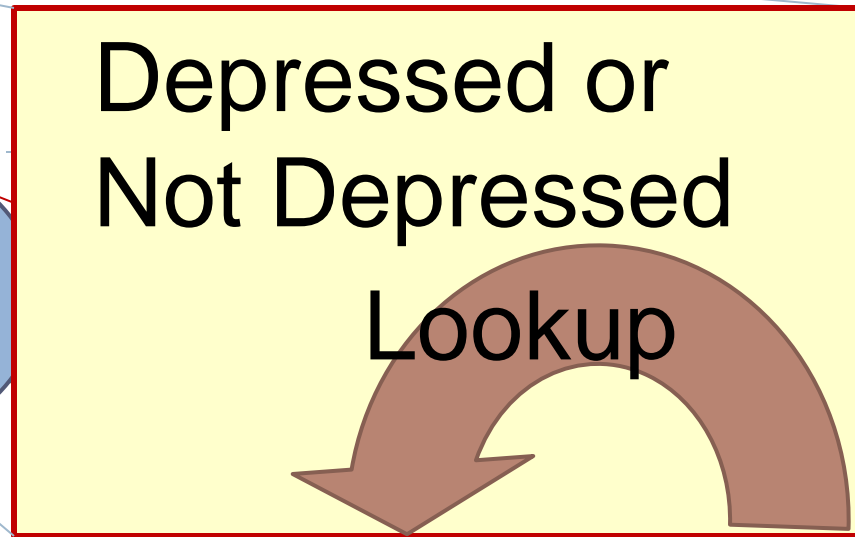
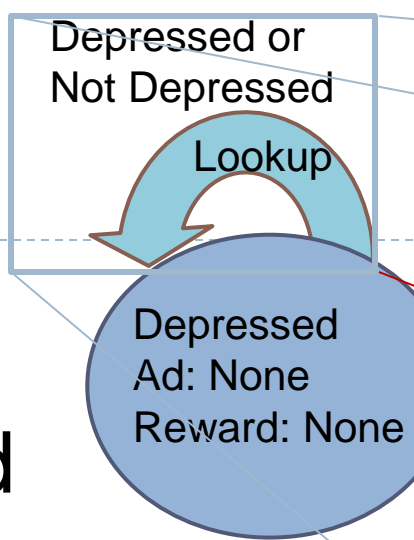
Depressed  
Case



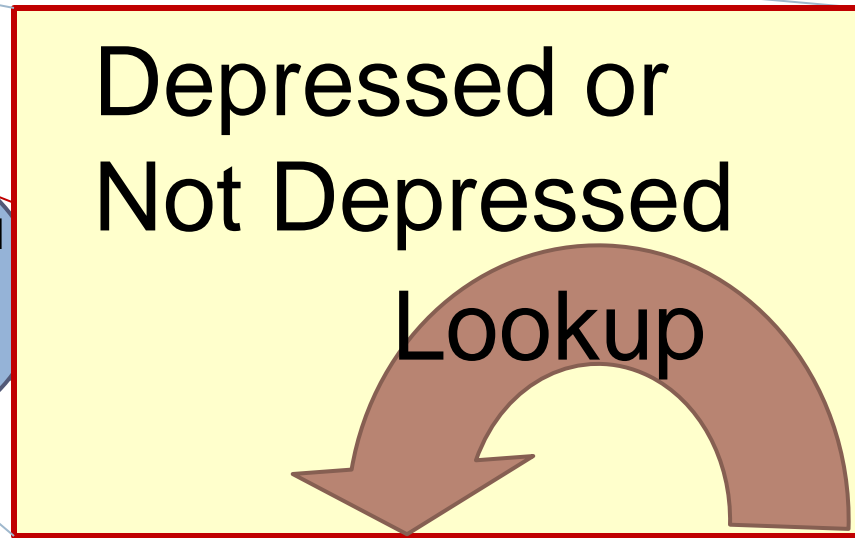
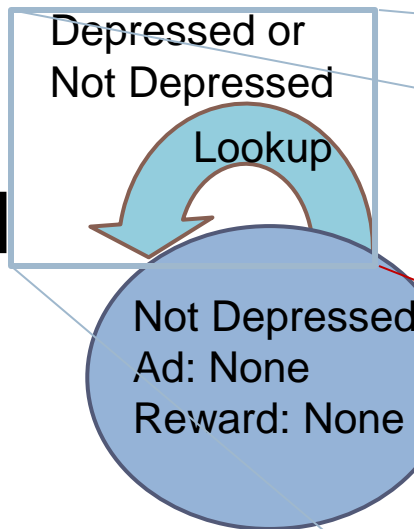
Not  
Depressed  
Case



Depressed  
Case



Not  
Depressed  
Case





Initial Beliefs

Depressed Case: 10%

Not Depressed Case: 90%

Lookup

Depressed or  
Not Depressed

Updated Beliefs

Depressed Case: 10%

Not Depressed Case: 90%

Party

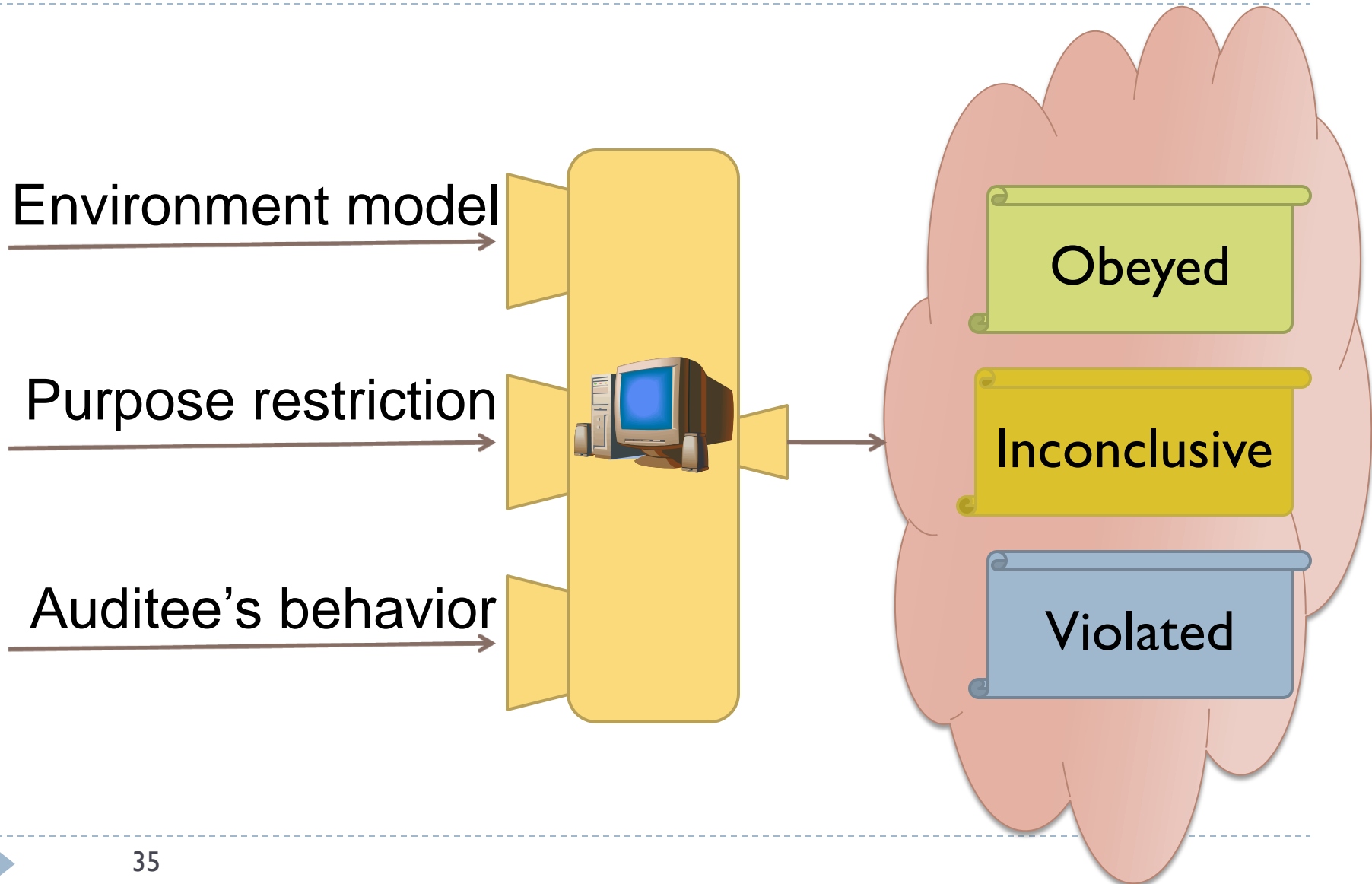
# Planning + Information Flow

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- ▶ **Cognitive:** Actions are for a purpose without using some information if they came from a plan selected by optimizing a model with disallowed information conflated.
  - ▶ Requires mind reading for enforcement
- ▶ **Behaviorist:** Actions are for a purpose without using some information if they are consistent with a plan optimizing a model with disallowed information conflated.
  - ▶ Could be consistent by coincidence and actually be for another purpose using the information

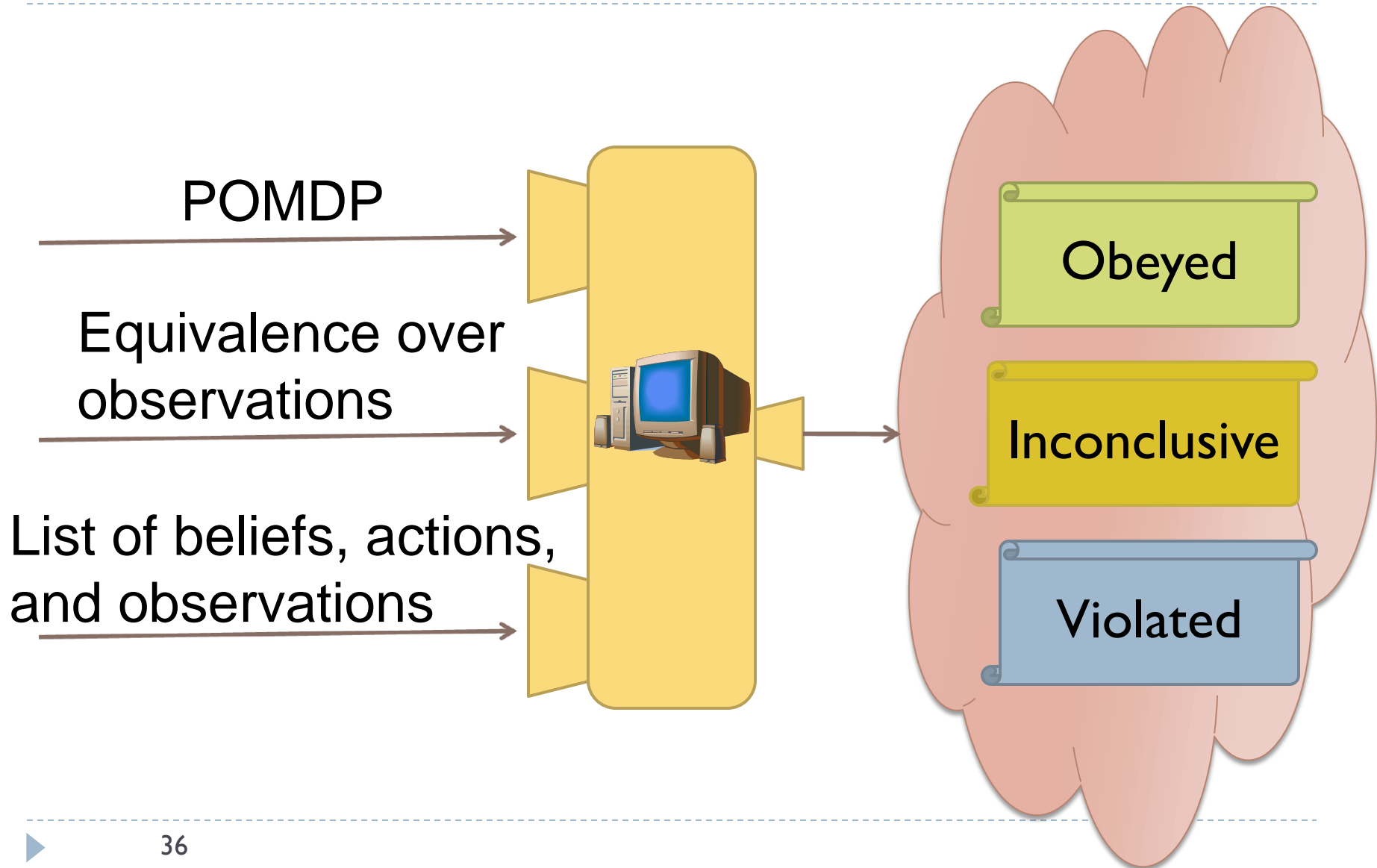
# Auditing

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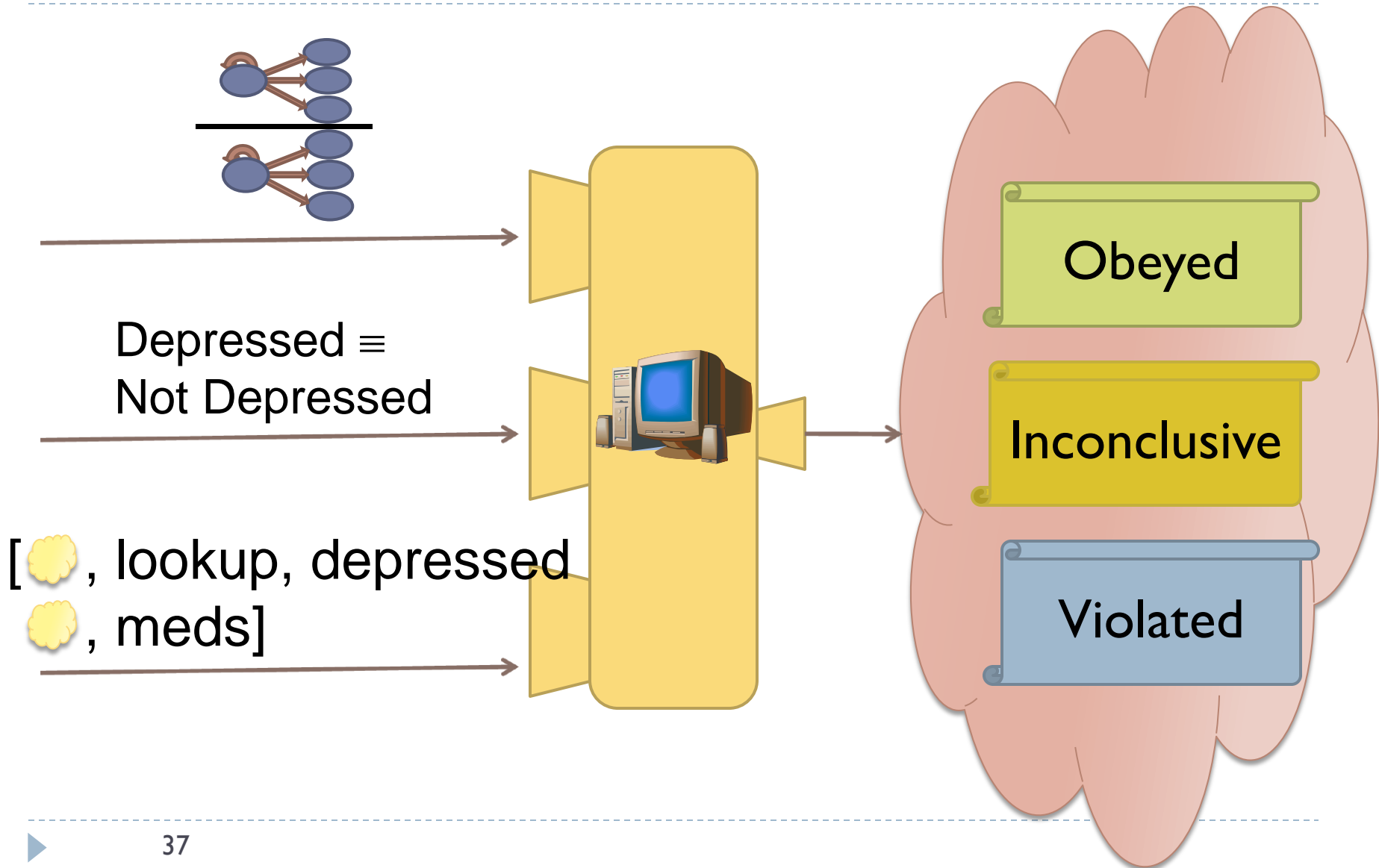


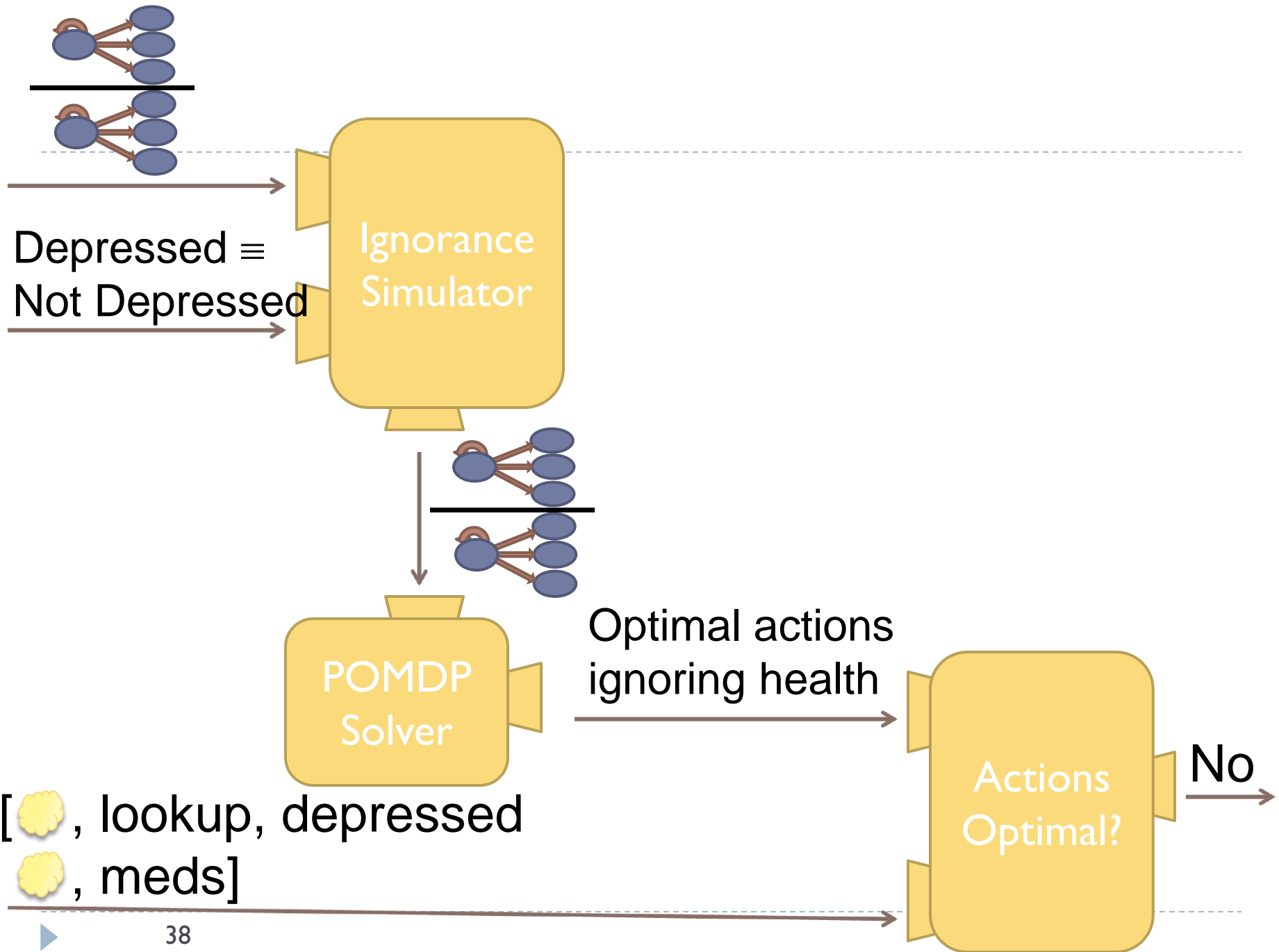
# Auditing

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# Auditing





# Implications

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- ▶ The actions were not for the purpose of marketing without using health data
  - ▶ Violates: “marketing without using health data”
- ▶ Either (1) used health data for marketing or (2) performed actions for some other purpose
  - ▶ In case (1) violates: “health data not for marketing”

# Prior Approaches

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- ▶ **Prior approaches:**
  - ▶ Labeling actions (industry practice)
  - ▶ Labeling sequences of actions (Al-Fedaghi 07, Jafari et al. 09)
  - ▶ Labeling roles (Byun et al. 05, 08, 10)
  - ▶ Labeling code (Hayati and Abadi 05)
- ▶ **Our work provides a semantic foundation**
- ▶ **Shows the expressiveness of each approach**



# Related Work

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- ▶ **Goal inference**
  - ▶ Baker, Tenenbaum, and Saxe 2006
  - ▶ Ramirez and Geffner 2011
- ▶ **Taylor's philosophical work 1966**

# Interesting Points

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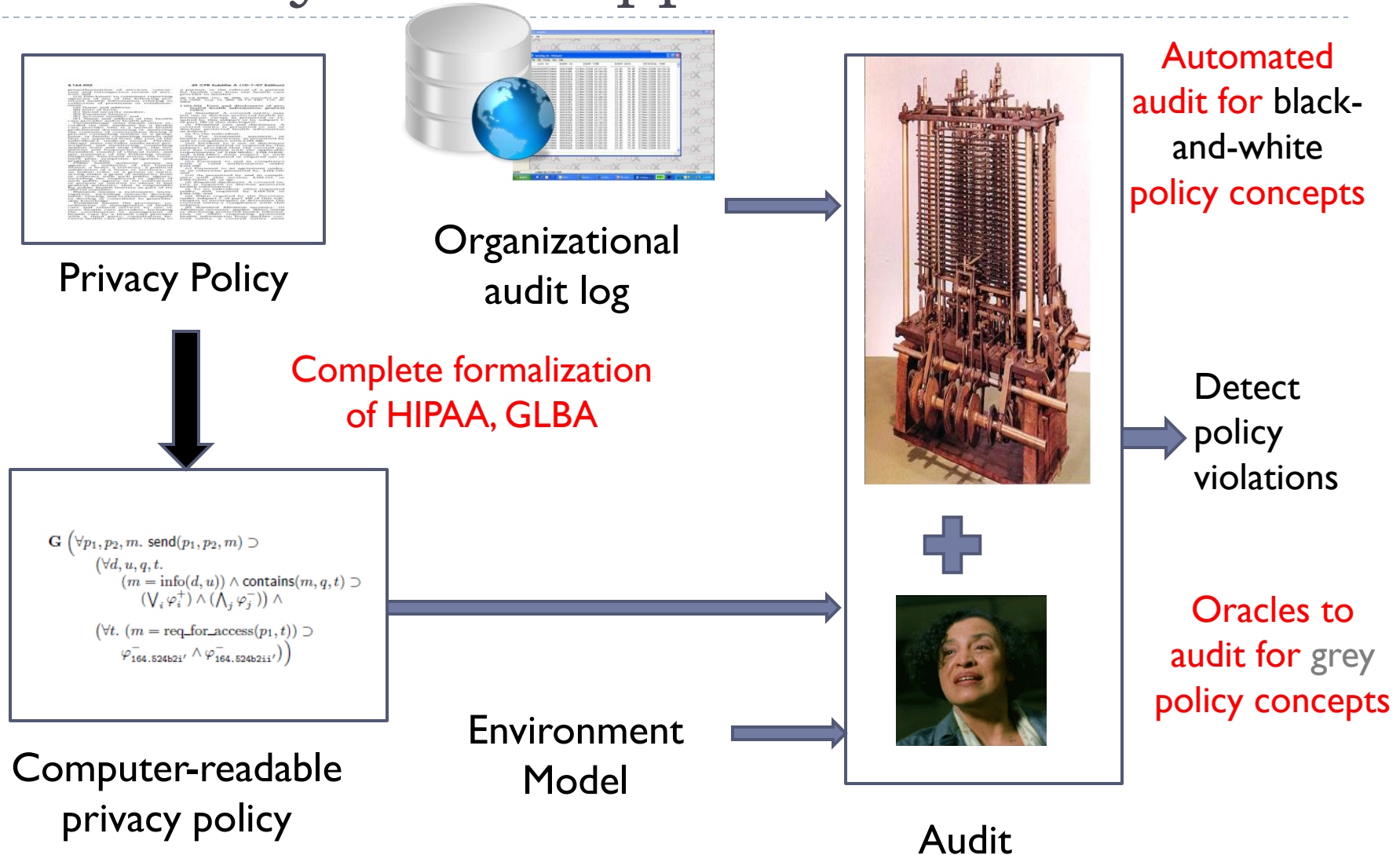
- ▶ **Cannot catch all violations of only-for rules**
  - ▶ Coincidences provide tenable deniability
- ▶ **Not-for rules restrict very little**
  - ▶ May still perform actions for very similar purposes
- ▶ **Enforcing only-for rules can improve both privacy and utility**
  - ▶ Keeps auditees on task

# Future Work

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- ▶ **Improving accuracy**
  - ▶ Human models of planning
- ▶ **Furthering practicality**
  - ▶ Automated creation of environment models
- ▶ **Applications**
  - ▶ Minimum necessary disclosure
- ▶ **Generalizations**
  - ▶ Multiple purposes

# Summary: Audit Approach



# POMDP: Formal Definition

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**POMDPs.** To define POMDPs, let  $\text{Dist}(X)$  denote the space of all distributions over the set  $X$  and let  $\mathbb{R}$  be the set of real numbers. A POMDP is a tuple  $\langle \mathcal{Q}, \mathcal{A}, \tau, \rho, \mathcal{O}, \nu, \gamma \rangle$  where

- $\mathcal{Q}$  is a finite state space representing the states of the agent's environment;
- $\mathcal{A}$ , a finite set of actions;
- $\tau : \mathcal{Q} \times \mathcal{A} \rightarrow \text{Dist}(\mathcal{Q})$ , a transition function from a state and an action to a distribution over states representing the possible outcomes of the action;
- $\rho : \mathcal{Q} \times \mathcal{A} \rightarrow \mathbb{R}$ , a reward function measuring the immediate impact on the satisfaction of the purpose when the agent takes the given action in the given state;
- $\mathcal{O}$ , a finite observation space containing any observations the agent may perceive while performing actions;
- $\nu : \mathcal{A} \times \mathcal{Q} \rightarrow \text{Dist}(\mathcal{O})$ , a distribution over observations given an action and the state resulting from performing that action; and
- $\gamma$ , a discount factor such that  $0 \leq \gamma < 1$ .

# POMDP and Purpose

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We say that a POMDP *models a purpose* if  $\rho$  measures the degree to which the purpose is satisfied. To select actions for that purpose, the agent should select those that maximizes its expected total discounted reward,  $\mathbb{E} [\sum_{i=0}^{\infty} \gamma^i u_i]$  where  $i$  represents time and  $u_i$ , the reward from the agent's  $i$ th action.

# Belief States

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This goal is complicated by the agent not knowing *a priori* which of the possible states of the POMDP is the current state of its environment. Rather it holds beliefs about which state is the current state. In particular, the agent assigns a probability to each state  $q$  according to how likely the agent believes that the current state is the state  $q$ . A *belief state*  $\beta$  captures these beliefs as a distribution over states of  $\mathcal{Q}$  (i.e.,  $\beta \in \text{Dist}(\mathcal{Q})$ ). An agent updates its belief state as it performs actions and makes observations. When an agent takes the action  $a$  and makes the observation  $o$  starting with the beliefs  $\beta$ , the agent develops the new beliefs  $\beta'$  where  $\beta'(q')$  is the probability that  $q'$  is the next state.

# Optimal Strategy

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To maximize its expected total discounted reward, the agent does not need to track its history of actions and observations independently of its beliefs as such beliefs are a sufficient statistic. Thus, the agent need only consider for each possible belief  $\beta$  it can have, what action it would perform. That is, the agent can plan by selecting a *strategy*: a function from the space of beliefs  $\text{Dist}(\mathcal{Q})$  to the space of actions  $\mathcal{A}$ . (We use the word “strategy” instead of the more common “policy” to avoid confusion with privacy policies.)