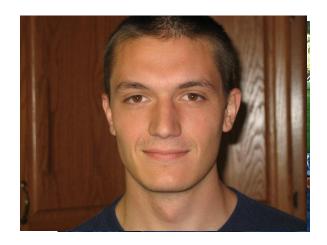
## WonkaBot 3D Chocolate Printer











#### **Project Concept & Motivation**

#### Concept:

- 3 Axis (XYZ) CNC Machine w/ Chocolate Extruder
- Design chocolate treats on your computer
- Print edible chocolate treats quickly

#### Motivation

- 3D printing is becoming more affordable
  - The next step is to print edible treats
    - Chocolate anyone?

### **Competitive Analysis**

Product	3-axis motion (XYZ)	In Production	Solid Chocolate	Open Source
Cornucopia (MIT)	No	No	No	Yes
Imagine (Essential Dynamics)	Yes	Yes	No	No
WonkaBot	Yes!	Yes!	Yes!	Yes!

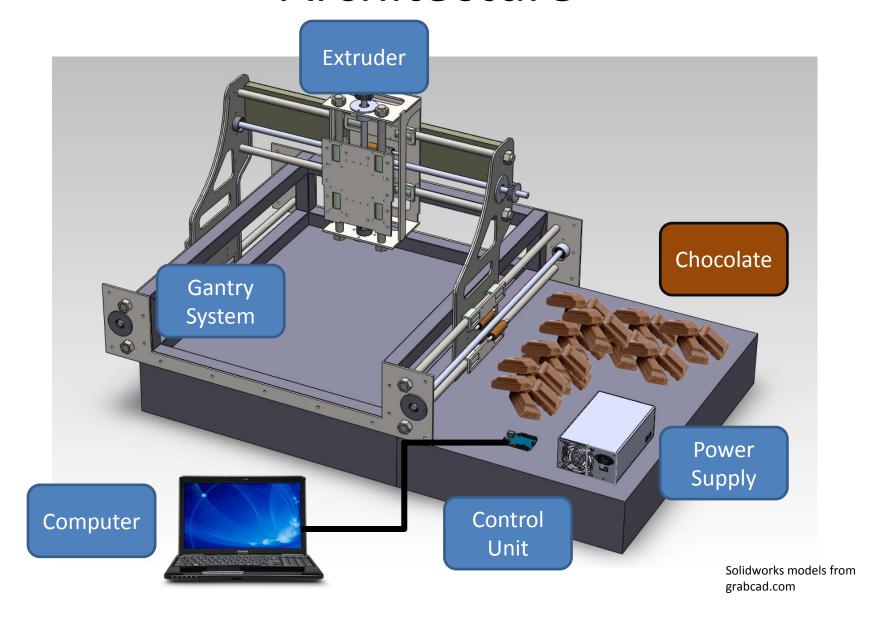
## Requirements

Extruder	Software	Gantry (XYZ)
Accurately control temperature of chocolate	<ul> <li>Interface with both extruder and gantry subsystems</li> </ul>	Accurately position extruder over build area
Create thin (<2mm)     chocolate extrusion	Convert 3D models to stepper motor commands	Cool and harden     chocolate as it exits the     extruder
<ul> <li>Accurately control extruder flow rate</li> <li>Hold and melt enough chocolate for at least</li> </ul>	PID control all temperature-related tasks	Utilize limit switches to prevent destruction or run-off outside of build area
one print	Prevent unnecessary     waste of chocolate	Contain all subsystems     and electronics for easy     transportation

#### **Technical Specifications**

- Design and build heated chocolate extruder
  - Nichrome hot wire
  - Archimedes screw to extrude chocolate filament
- Cooled platform (Peltier unit) to harden chocolate
- CAD to GCODE conversion software
  - May use off-the-shelf solution (ReplicatorG/Skeinforge)
- 3-axis (XYZ) gantry system
  - Stepper motors for precise control

#### Architecture



# Anticipated Risks and Mitigations Strategies

Chocolate may burn in extruder	Keep chocolate barely above melting temperature keep chocolate moving
Chocolate doesn't come out in small extrusion	<ul><li>Reduce nozzle size</li><li>Rework nozzle shape</li></ul>
Chocolate flows too quickly out of extruder	<ul> <li>Slow down or back-drive Archimedes screw</li> <li>Reduce nozzle size</li> </ul>
Chocolate flows out too slowly	<ul><li>Increase nozzle size</li><li>Increase torque of drive motor</li></ul>
Basin doesn't hold enough chocolate	<ul><li>Use larger basin</li><li>Supplement basin during build</li></ul>
3D objects are difficult to model	Support multiple modeling programs     (SolidWorks, SketchUp, etc.)
3D file to GCODE conversion is non-trivial	Use off the shelf conversion program     (Skeinforge)
GCODE to stepper motor command conversion is non-trivial	Use off the shelf conversion program     (ReplicatorG)
Stepper motors are difficult to control	Use pre-built stepper motor drivers (EasyDriver)
Gantry system is hard to implement	Look at open-source CNC implementations for inspiration (or get one donated)