

18-660: Numerical Methods for Engineering Design and Optimization

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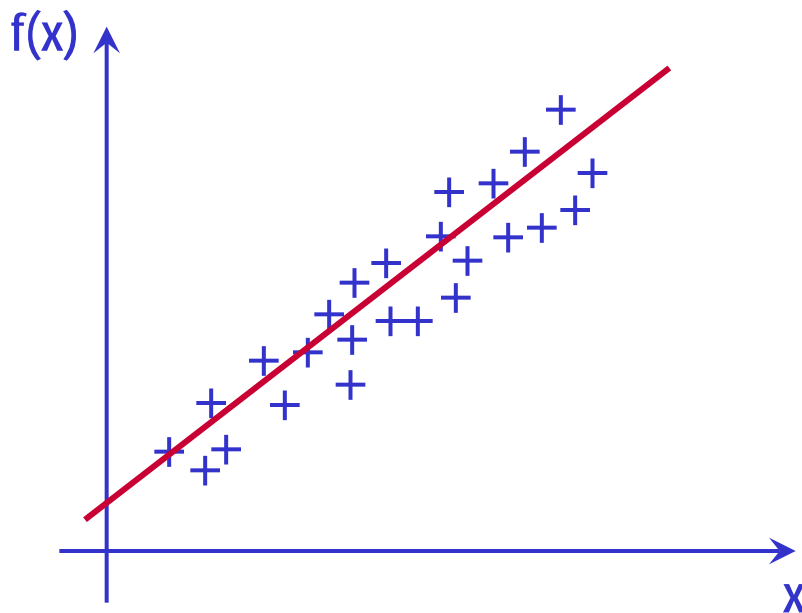
Overview

■ Linear Regression

- ▼ Ordinary least-squares regression
- ▼ Minimax optimization
- ▼ Design of experiments

Linear Regression

- Linear regression (also referred to as response surface modeling) is widely used for many engineering problems
 - ▼ We do not know the analytical form of $f(x)$
 - ▼ But we can generate a set of sampling points for $f(x)$
 - ▼ Fit an approximate function for $f(x)$ from these sampling points



$$f(x) \approx \alpha_1 \cdot b_1(x) + \alpha_2 \cdot b_2(x) + \dots$$

Model coefficients

Basis functions

$f(x)$ is approximated as the linear combination of multiple basis functions

Linear Regression

■ Major steps of linear regression

- ▼ Select a model template (e.g., polynomial function)
- ▼ Generate a number of sampling points
- ▼ Compute performance values at these sampling points
- ▼ Create a set of linear equations to solve model coefficients

■ A simple example

- ▼ $f(x) = \exp(x)$, $x \in [-1, 1]$
- ▼ We will use this simple example to show how we can generally build a regression model from sampling data

Linear Regression Example

- Step 1: select a model template

$$f(x) \approx bx + c$$

- Step 2: generate a number of sampling points

Samples	1	2	3	4	5
x	-1	-0.5	0	0.5	1

- Step 3: compute performance values at these sampling points

Samples	1	2	3	4	5
f(x)	0.3679	0.6065	1.0000	1.6487	2.7183

Linear Regression Example

- Step 4: create linear equations for model coefficients

$$f(x) \approx bx + c$$

Samples	1	2	3	4	5
x	-1	-0.5	0	0.5	1
f(x)	0.3679	0.6065	1.0000	1.6487	2.7183

$$\begin{bmatrix} -1 & 1 \\ -0.5 & 1 \\ 0 & 1 \\ 0.5 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} b \\ c \end{bmatrix} = \begin{bmatrix} 0.3679 \\ 0.6065 \\ 1.0000 \\ 1.6487 \\ 2.7183 \end{bmatrix}$$

← i-th sampling point


x values f(x) values

Linear Regression Example

■ Step 5: solve over-determined linear equations

- ▼ # of equations is greater than # of coefficients – **over-determined**
- ▼ No exact solution exists to satisfy all equations, but we can find the least-squares solution:

$$A \cdot \alpha = B$$



$$\min_{\alpha} \underbrace{\|A \cdot \alpha - B\|_2^2}_{\text{Vector}}$$

Ordinary least-squares (OLS) regression

- ▼ For a vector $\varepsilon \in \mathbb{R}^M$, $\|\varepsilon\|_2$ is defined as:

$$\|\varepsilon\|_2 = \sqrt{\sum_{i=1}^M \varepsilon_i^2}$$

Linear Regression Example

$$A \cdot \alpha = B$$

$\left[\begin{array}{c} \vdots \\ \text{i-th row} \\ \vdots \end{array} \right] \cdot \alpha - \left[\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] = \left[\begin{array}{c} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \vdots \\ \varepsilon_M \end{array} \right]$

→ Error at the i-th sampling point

$$\min_{\alpha} \|A \cdot \alpha - B\|_2^2 \quad \Rightarrow \quad \min_{\alpha} \sum_{i=1}^M \varepsilon_i^2(\alpha)$$

Linear Regression Example

$$\begin{array}{c} \text{M samples} \\ \left\{ \begin{array}{c} \left[\begin{array}{c} \\ \\ \\ \\ \end{array} \right] \cdot \alpha = \left[\begin{array}{c} \\ \\ \\ \\ \end{array} \right] \\ \\ \\ \\ \\ \end{array} \right. \end{array} \quad (M > N)$$

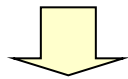
N coefficients

- There are several possible ways to solve over-determined linear equations for linear regression
 - ▼ We will explain these algorithms in detail in future lectures
 - ▼ For now, you can simply use “ $\alpha = A \setminus B$ ” in MATLAB

Linear Regression Example

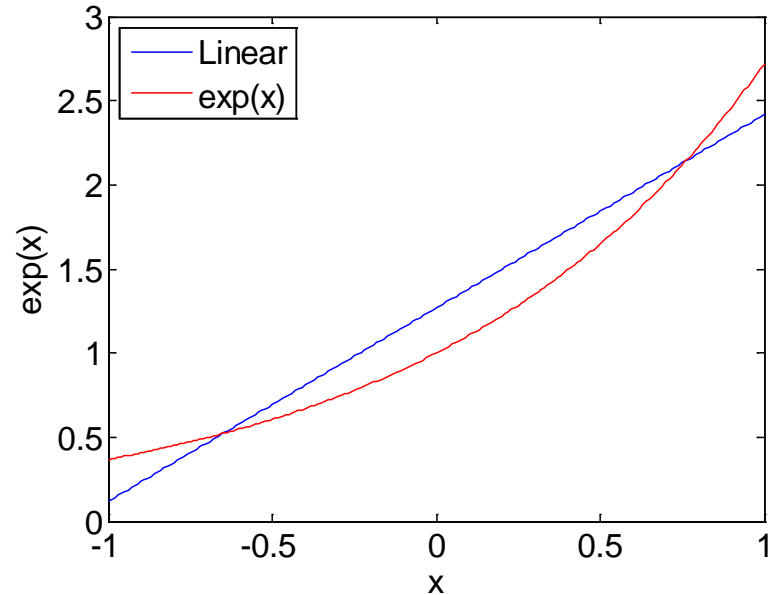
- Step 5: solve over-determined linear equations

$$\begin{bmatrix} -1 & 1 \\ -0.5 & 1 \\ 0 & 1 \\ 0.5 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} b \\ c \end{bmatrix} = \begin{bmatrix} 0.3679 \\ 0.6065 \\ 1.0000 \\ 1.6487 \\ 2.7183 \end{bmatrix}$$



$$b = 1.1486$$

$$c = 1.2683$$



Linear model results in large error

Quadratic Model Example

■ What if we build a quadratic model for $y = \exp(x)$?

- ▼ Select a model template

$$f(x) \approx ax^2 + bx + c$$

- ▼ Generate a number of sampling points

Samples	1	2	3	4	5
x	-1	-0.5	0	0.5	1

- ▼ Compute performance values at these sampling points

Samples	1	2	3	4	5
f(x)	0.3679	0.6065	1.0000	1.6487	2.7183

Quadratic Model Example

- Create a set of linear equations to solve model coefficients

$$f(x) \approx ax^2 + bx + c$$

Samples	1	2	3	4	5
x	-1	-0.5	0	0.5	1
f(x)	0.3679	0.6065	1.0000	1.6487	2.7183

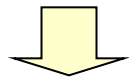
$$\begin{bmatrix} 1 & -1 & 1 \\ 0.25 & -0.5 & 1 \\ 0 & 0 & 1 \\ 0.25 & 0.5 & 1 \\ 1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0.3679 \\ 0.6065 \\ 1.0000 \\ 1.6487 \\ 2.7183 \end{bmatrix}$$

\downarrow \downarrow \downarrow
 x^2 x f(x) values

Quadratic Model Example

- Build quadratic model for $y = \exp(x)$

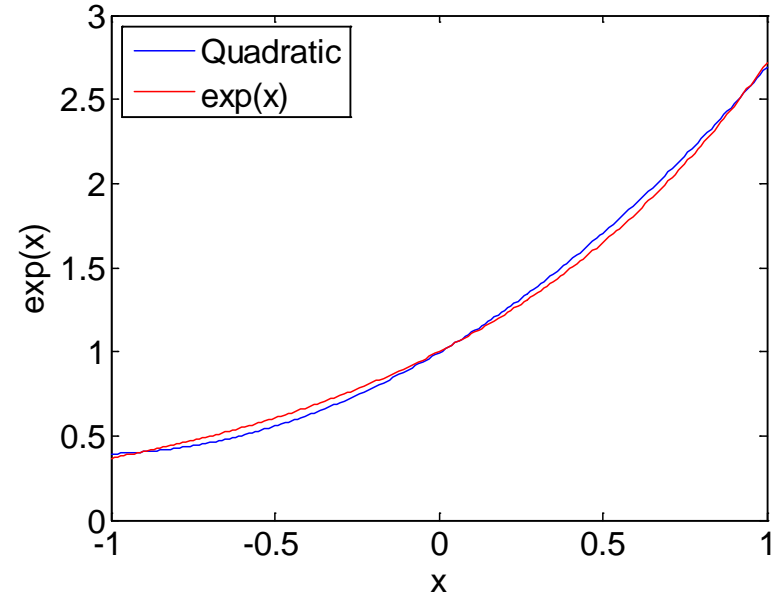
$$\begin{bmatrix} 1 & -1 & 1 \\ 0.25 & -0.5 & 1 \\ 0 & 0 & 1 \\ 0.25 & 0.5 & 1 \\ 1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0.3679 \\ 0.6065 \\ 1.0000 \\ 1.6487 \\ 2.7183 \end{bmatrix}$$



$$a = 0.5477$$

$$b = 1.1486$$

$$c = 0.9944$$



Quadratic model results in much better accuracy in this example

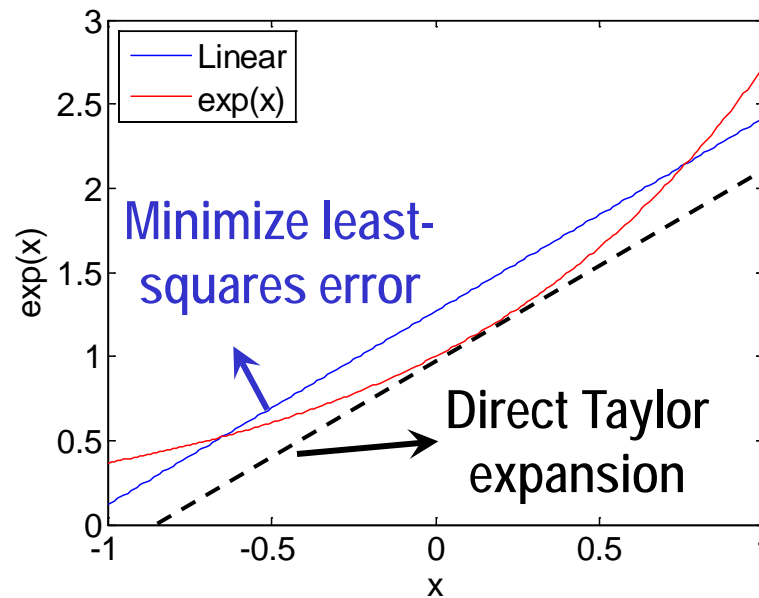
Linear Model vs. Quadratic Model

Linear RSM $\exp(x) \approx 1.1486x + 1.2683$

Quadratic RSM $\exp(x) \approx 0.5477x^2 + 1.1486x + 0.9944$

■ Regression model is different from direct Taylor expansion

- ▼ E.g., different constant terms in linear and quadratic models – they are selected to minimize the least-squares error

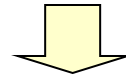


Linear model for $\exp(x)$

Minimax Optimization

- We can also solve over-determined linear equations to satisfy other optimality criteria (i.e., not ordinary least-squares)

$$A \cdot \alpha = B$$



i-th row of A

$$\min_{\alpha} \max_i |A(i,:) \cdot \alpha - B_i|$$

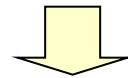
Minimize the maximal
absolute error

$$\begin{bmatrix} \text{i-th row} \\ \vdots \\ A \\ \vdots \end{bmatrix} \cdot \alpha - \begin{bmatrix} \vdots \\ B \\ \vdots \end{bmatrix} \rightarrow \text{Error at the i-th sampling point}$$

Minimax Optimization

- Other optimality criteria can be similarly formulated

$$A \cdot \alpha = B$$



i-th row of A

$$\min_{\alpha} \max_i \left| \frac{A(i,:) \cdot \alpha - B_i}{B_i} \right|$$

Minimize the maximal
relative error

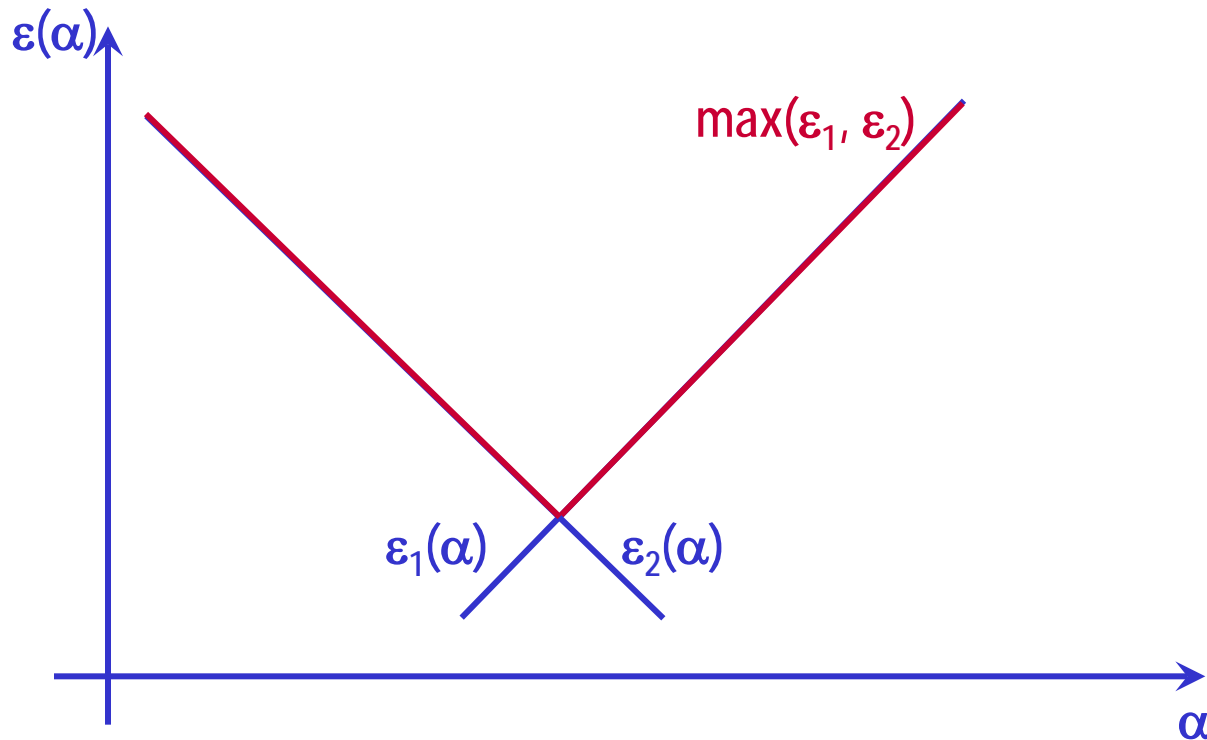
$$\begin{bmatrix} \text{i-th row} \\ \vdots \\ A \\ \vdots \end{bmatrix} \cdot \alpha - \begin{bmatrix} \vdots \\ B \\ \vdots \end{bmatrix}$$

Error at the i-th sampling point

These formulations are **minimax optimization** problems

Minimax Optimization

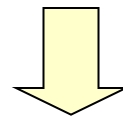
- General minimax problems are difficult to solve
 - ▼ Cost function does not have continuous derivative



Minimax Optimization

- However, our minimax problem for regression modeling can be re-formulated into a special form
- Consider the example of absolute error minimization

$$\min_{\alpha} \max_i |A(i,:) \cdot \alpha - B_i|$$



Introduce a slack variable t

$$\begin{array}{l} \min_{\alpha, t} \quad t \\ \text{S.T.} \quad \left\{ \begin{array}{l} |A(1,:) \cdot \alpha - B_1| \leq t \\ |A(2,:) \cdot \alpha - B_2| \leq t \\ \vdots \\ |A(M,:) \cdot \alpha - B_M| \leq t \end{array} \right. \end{array}$$

Subject to

} Cost function

} Constraints

Minimax Optimization

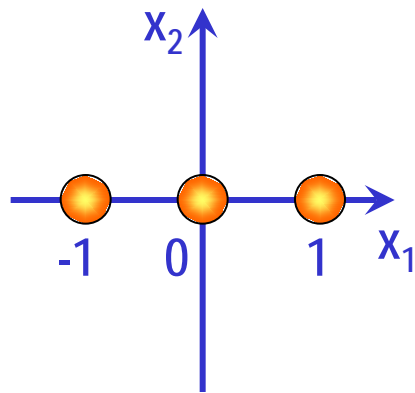
$$\begin{array}{l} \min_{\alpha, t} \quad t \\ \text{S.T.} \quad \left\{ \begin{array}{l} |A(1,:) \cdot \alpha - B_1| \leq t \\ |A(2,:) \cdot \alpha - B_2| \leq t \\ \vdots \\ |A(M,:) \cdot \alpha - B_M| \leq t \end{array} \right. \end{array} \quad \Rightarrow \quad \begin{array}{l} \min_{\alpha, t} \quad t \\ \text{S.T.} \quad \left\{ \begin{array}{l} -t \leq A(1,:) \cdot \alpha - B_1 \leq t \\ -t \leq A(2,:) \cdot \alpha - B_2 \leq t \\ \vdots \\ -t \leq A(M,:) \cdot \alpha - B_M \leq t \end{array} \right. \end{array}$$

■ Re-written as a **linear programming** (LP) problem

- ▼ Both cost function and constraints are linear
- ▼ No closed-form solution exists for LP
- ▼ Can be numerically solved by an efficient (i.e., low complexity) and robust (i.e., global convergence) algorithm

Design of Experiments (DOE)

- We already know the basics for linear regression
- Open problem:
 - ▼ How can we select **few** samples to achieve **good** accuracy?
- A **bad** linear model example: $f(x_1, x_2) = a \cdot x_1 + b \cdot x_2 + c$



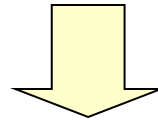
$$\begin{pmatrix} x_1 = -1 & x_2 = 0 & f_1 \end{pmatrix}$$
$$\begin{pmatrix} x_1 = 0 & x_2 = 0 & f_2 \end{pmatrix}$$
$$\begin{pmatrix} x_1 = 1 & x_2 = 0 & f_3 \end{pmatrix}$$

Sampling points for linear model

Design of Experiments (DOE)

■ Linear model example (continued)

$$f(x_1, x_2) = a \cdot x_1 + b \cdot x_2 + c$$
$$\begin{array}{l} (x_1 = -1 \quad x_2 = 0 \quad f_1) \\ (x_1 = 0 \quad x_2 = 0 \quad f_2) \\ (x_1 = 1 \quad x_2 = 0 \quad f_3) \end{array}$$

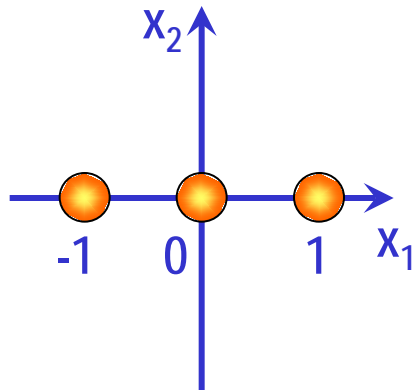


$$\begin{array}{ccc} x_1 & x_2 & 1 \\ \begin{bmatrix} -1 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix} \end{array}$$

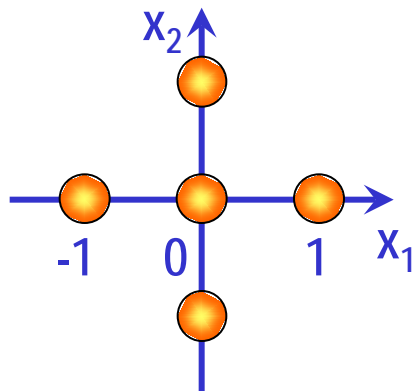
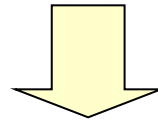
Singular matrix (cannot solve the coefficient b)

Design of Experiments (DOE)

■ Linear model example (continued)



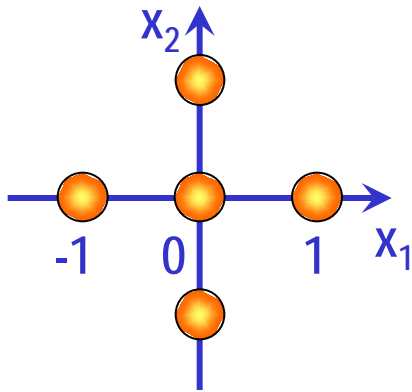
No variation is applied to x_2



Add additional sampling points for x_2

Design of Experiments (DOE)

- A **bad** quadratic model example: $f(x_1, x_2) = a_{11} \cdot x_1^2 + a_{12} \cdot x_1 \cdot x_2 + a_{22} \cdot x_2^2 + b_1 \cdot x_1 + b_2 \cdot x_2 + c$



$$\begin{aligned} & (x_1 = 0 \quad x_2 = 0 \quad f_1) \\ & (x_1 = 0 \quad x_2 = -1 \quad f_2) \\ & (x_1 = 0 \quad x_2 = 1 \quad f_3) \\ & (x_1 = -1 \quad x_2 = 0 \quad f_4) \\ & (x_1 = 1 \quad x_2 = 0 \quad f_5) \end{aligned}$$

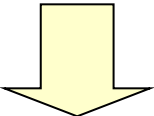

Sampling points for quadratic model

Design of Experiments (DOE)

■ Quadratic model example (continued)

$$f(x_1, x_2) = a_{11} \cdot x_1^2 + a_{12} \cdot x_1 \cdot x_2 + a_{22} \cdot x_2^2 + b_1 \cdot x_1 + b_2 \cdot x_2 + c$$

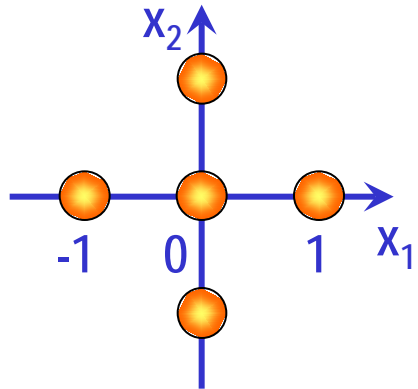
$$\begin{array}{lll} (x_1 = 0 & x_2 = 0 & f_1) \\ (x_1 = 0 & x_2 = -1 & f_2) \\ (x_1 = 0 & x_2 = 1 & f_3) \\ (x_1 = -1 & x_2 = 0 & f_4) \\ (x_1 = 1 & x_2 = 0 & f_5) \end{array}$$


$$\begin{array}{cccccc} x_1^2 & x_1 x_2 & x_2^2 & x_1 & x_2 & 1 \\ \left[\begin{array}{cccccc} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & -1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & -1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 & 1 \end{array} \right] \cdot \begin{bmatrix} a_{11} \\ a_{12} \\ a_{22} \\ b_1 \\ b_2 \\ c \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \end{bmatrix} \end{array}$$


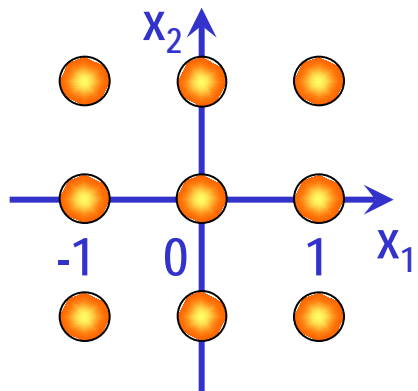
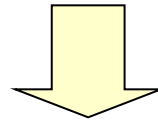
Singular matrix (cannot solve the coefficient a_{12})

Design of Experiments (DOE)

■ Quadratic model example (continued)



Cross-product terms cannot be captured



Add additional sampling points for x_1x_2

Design of Experiments (DOE)

- Design of experiments (DOE) is a research area that studies how to optimally select sampling points for modeling
- Given a model template (e.g., linear or quadratic function), optimize sampling points for certain optimal criterion
 - ▼ E.g., maximize modeling accuracy
- Numerical optimization may be required to find the optimal sampling scheme

D. Montgomery, *Design and Analysis of Experiments*, John Wiley & Sons, 2004

Summary

- Linear regression
 - ▼ Ordinary least-squares regression
 - ▼ Minimax optimization
 - ▼ Design of experiments