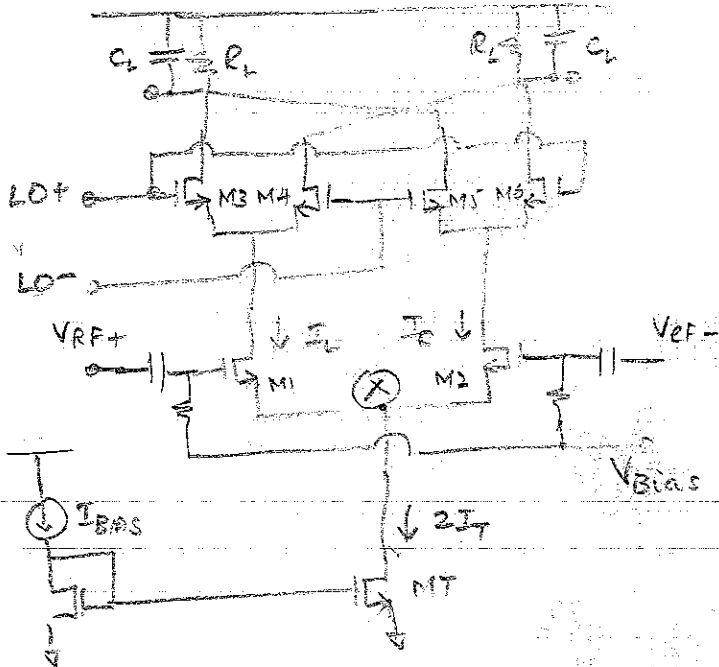


Gilbert-cell double balanced mixer:

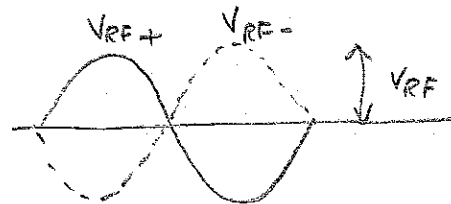


- Two cross-connected single balanced mixers.
- The differential pair formed by M1, M2 and MT acts as a simple transconductor.
- M3, M4, M5 and M6 form a Gilbert quad.

- The LO inputs are made large enough to commutate the currents I_L (and I_R) periodically from M3 and M4 (and M5 and M6)
- The LO must not be made just large enough to switch I_L and I_R completely, but not so large as to drive M3/M4/M5 and M6 out of saturation (ie. they should either be in cut-off or saturation)
- For small signal input

$$I_L = I_T + g_m V_{RF} \cos \omega_{RF} t$$

$$I_R = I_T - g_m V_{RF} \cos \omega_{RF} t$$



Differential output current

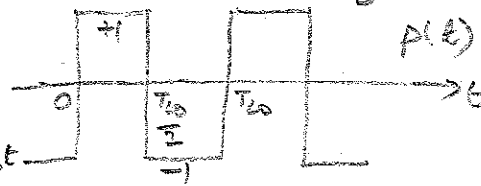
$$I_{out} = (I_3 + I_5) - (I_4 + I_6) = (I_3 - I_4) + (I_5 - I_6)$$

$$= I_L p(t) - I_R p(t)$$

$p(t) \rightarrow$ switching function

$$\Rightarrow I_{out} = 2g_m V_{RF} \cos \omega_{RF} t p(t)$$

$$= 2g_m V_{RF} \cos \omega_{RF} t \cdot \frac{4}{\pi} \left[\sin \omega_{LO} t + \frac{1}{3} \sin 3\omega_{LO} t + \dots \right]$$



$$\Rightarrow I_{out} = \frac{g_m V_{RF}}{\pi} \left[\sin(\omega_{LO} - \omega_{RF})t + \sin(\omega_{LO} + \omega_{RF})t + \frac{1}{3} \sin(3\omega_{LO} - \omega_{RF})t + \frac{1}{3} \sin(3\omega_{LO} + \omega_{RF})t + \dots \right]$$

Conversion gain $G_c = \frac{g_m R_L V_{RF} / \pi}{2V_{RF}} = \frac{4}{\pi} g_m R_L$

(We need to filter off un-desired components)

- LO-to-IF port isolation much better in double-balanced mixers. Port isolation is limited by mismatch between (M1) and (M2) and (M3, M4, M5, M6).

Sources of random mismatch:

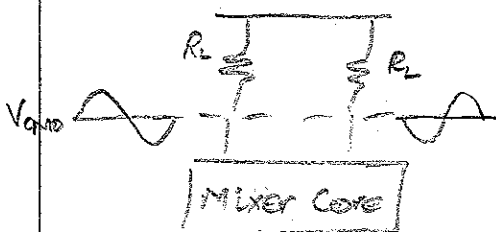
- $\Delta W, \Delta L$, minimized by careful layout, ultimately limited by accuracy of photolithography
- ΔV_t mismatch
- ΔL_x mismatch (due to variations in L_{ox} and E_{ox})
- can routinely achieve 40+ dB of port isolation.

Noise in current commutating mixers:

Ref: H. Darabi and A. Abidi, "Noise in RF-CMOS Mixers: A Simple Physical Model", IEEE Journal of Solid State Circuits, Vol. 35, No. 1, Jan 2000, pp. 15-25

Load Noise:

(i) Resistive loads:

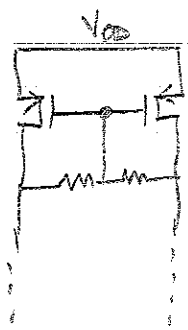


- Thermal noise from resistors competes with output signal.
- No $1/f$ noise in typical resistors available in CMOS (i.e. poly-si or metal)

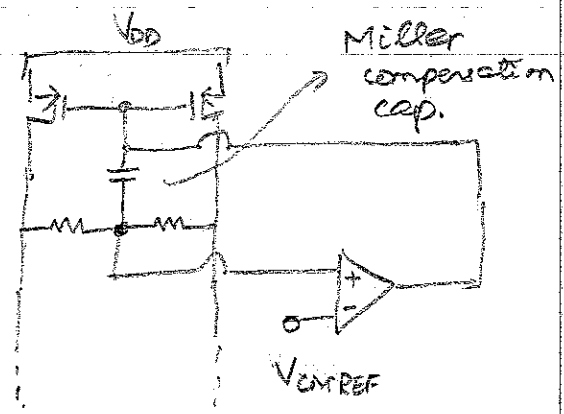
The disadvantage with resistive loads is the loss of voltage headroom: The common-mode voltage at the output is set by the bias current in the mixer core: $V_{CMO} = V_{DD} - I_T R_L$ (total tail current = $2I_T$)

But $C_{cc} \propto R_L \Rightarrow$ want large R_L for high gain, but V_{CMO} decreases which degrades voltage headroom available for the mixer core:

(ii) PMOS loads:



or



Somewhat better, but headroom still limited by V_{GS} of PMOS devices

Common-mode feedback loop \Rightarrow Best headroom

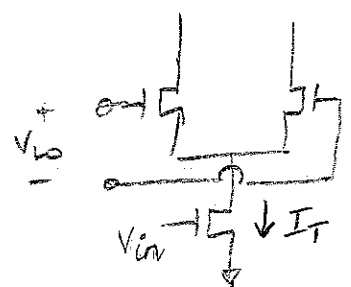
$V_{CMO} \leq V_{DD} - V_{GS}$

$V_{CMO} \leq V_{DD} - V_{GSAT}$

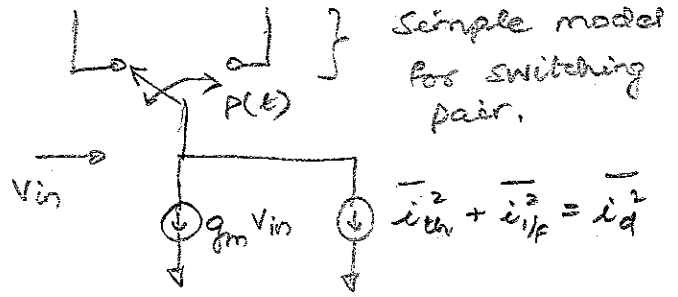
- Thermal noise of PMOS competes with output signal
- $1/f$ noise is important in direct conversion or low-IF receivers. \Rightarrow use PMOS loads with large area.

(b) Noise from transconductor stage:

(i) Consider a single-balanced mixer:



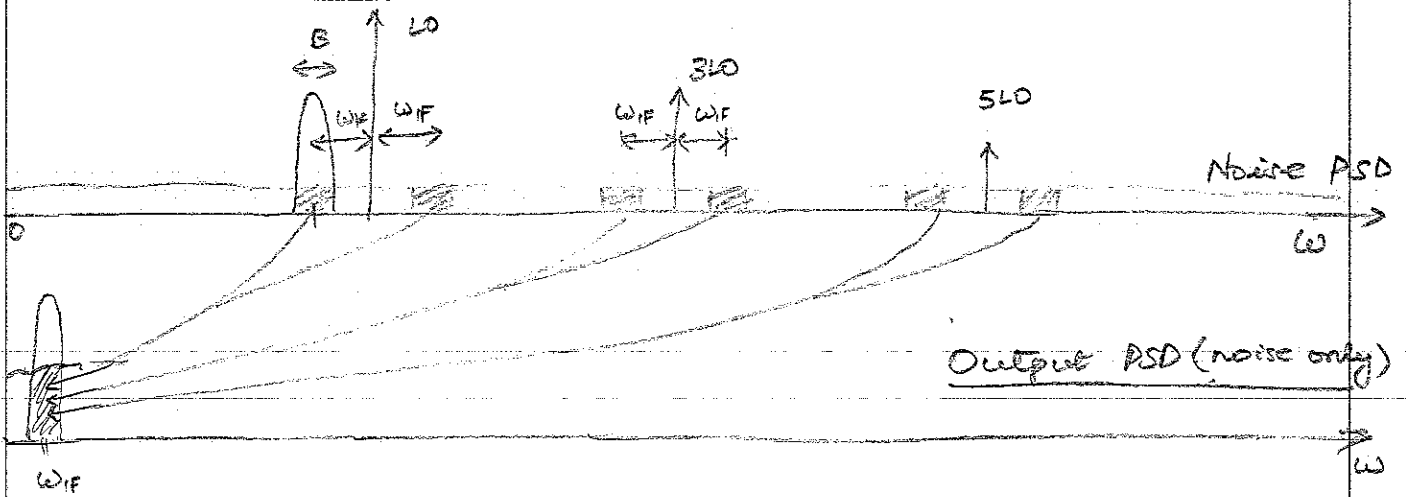
\Rightarrow



• i_{i0}^2 gets amplitude modulated by $p(t)$

⇒ Need to find noise frequency bands which fold down to the IF output after downconversion

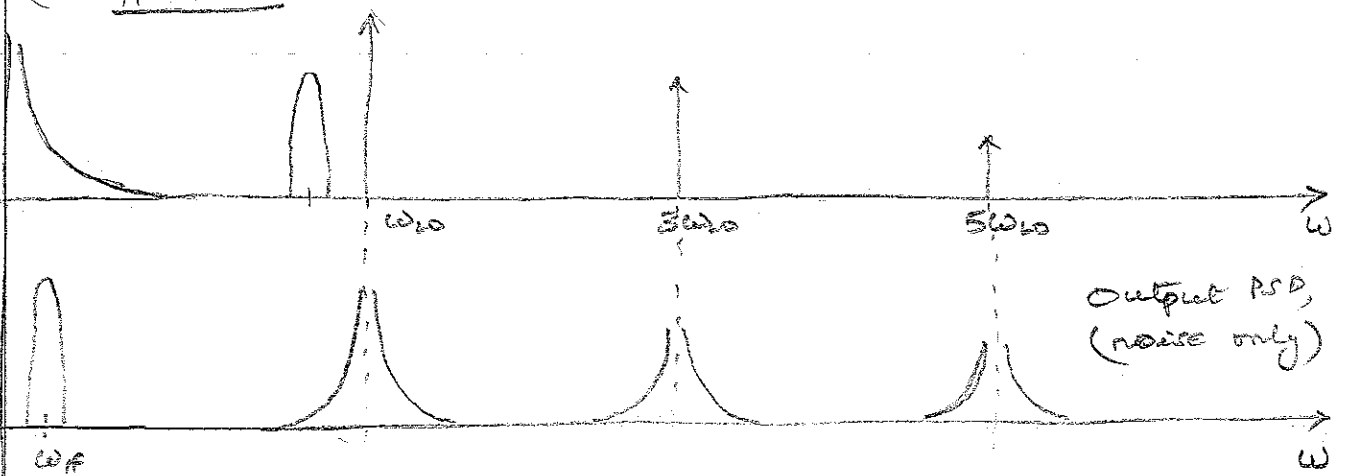
(i) Thermal noise:



Approximate mean-square noise contribution

$$\frac{1}{2} \omega_{0gm}^2 = \underbrace{\frac{4kTY}{g_m}}_{\text{PSD}} \times \underbrace{\left(\frac{2}{\pi} g_m R_L\right)^2}_{G_c^2} \times \underbrace{\left(1 + \frac{1}{3^2} + \frac{1}{5^2} + \dots\right)}_{=\pi^2/4}$$

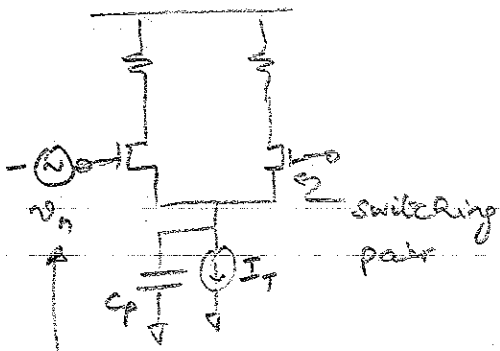
(ii) 1/f noise



- Downconversion mixer: $1/2$ noise from g_m -stage does not have a big impact on o/p noise. However, if the switching pair has mismatches, some $1/2$ noise remains at Baseband and degrades the signal at the output
- Upconversion mixer: Since input signal and $1/2$ noise both get upconverted, $1/2$ noise from the g_m -stage can have a significant impact. → manage $1/2$ noise by using large g_m -devices

(c) Noise from switching pair:

- Relatively complicated to analyze. See above ref. for details
- Switching devices do not contribute noise when tail current is completely switched.

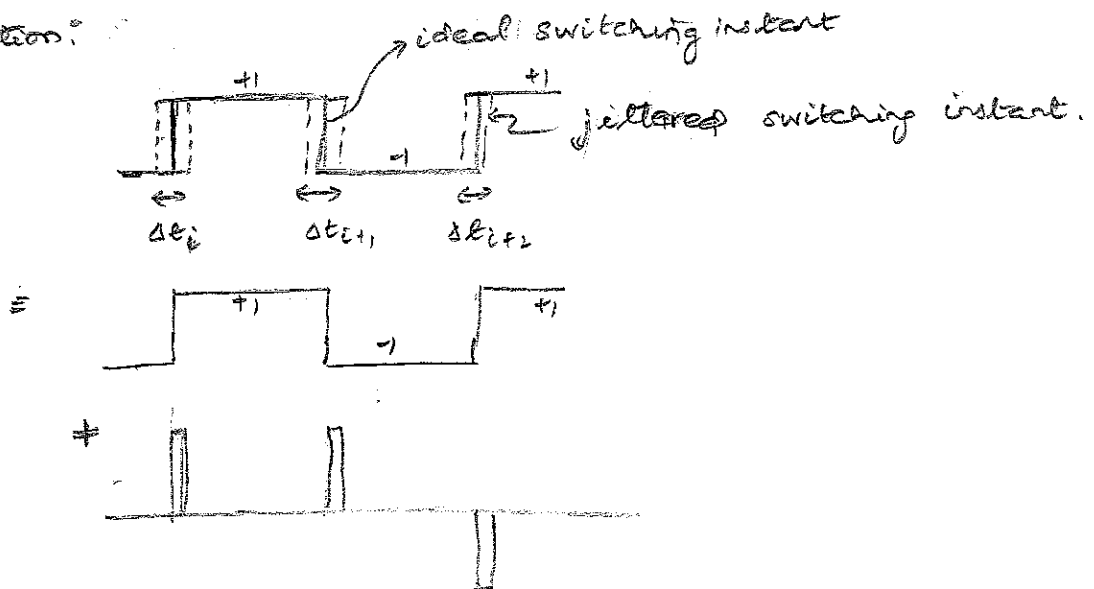


- If C_p is large, switching devices contribute noise to the output even when completely switched.

- Both devices contribute noise directly during the switching phase

single input-referred noise source captures effect of noise from both devices.

In the simple model above, v_n modulates the switching function:



→ Approximate the real switching function as the sum of the ideal switching function and a train of pulses.

- The height of each pulse is constant, but its sign can be +1 or -1
- The width of each pulse $\Delta t = \frac{V_n(t_i)}{S}$ where S is the

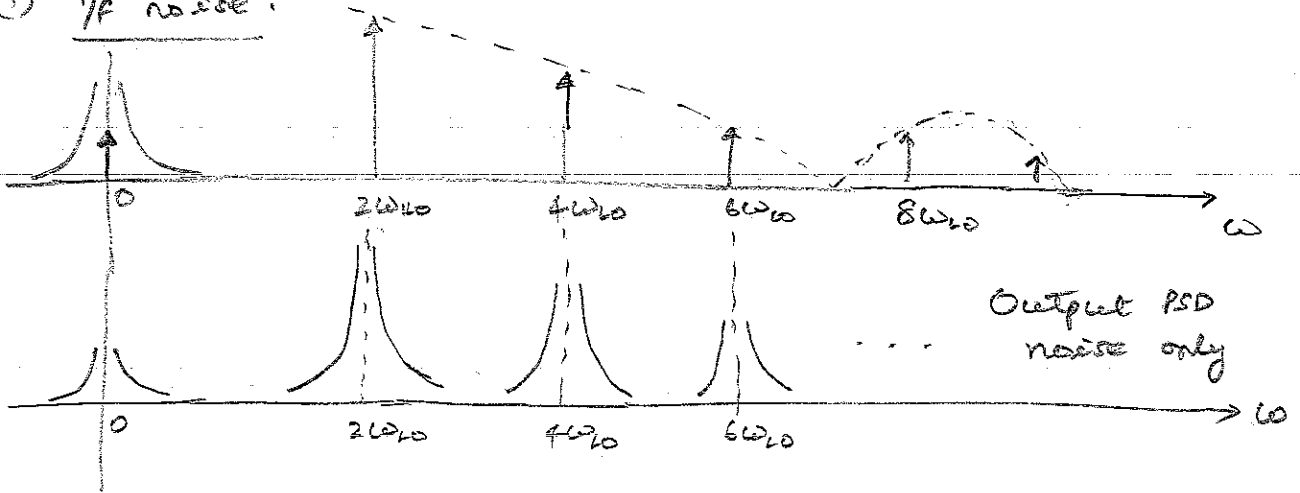
slope of the edge.

- The pulse rate is $2\omega_{LO}$

⇒ Noise from switching devices get modulated by even LO harmonics (ie $2\omega_{LO}$, $4\omega_{LO}$, etc. and possibly DC)

In cartoon form:

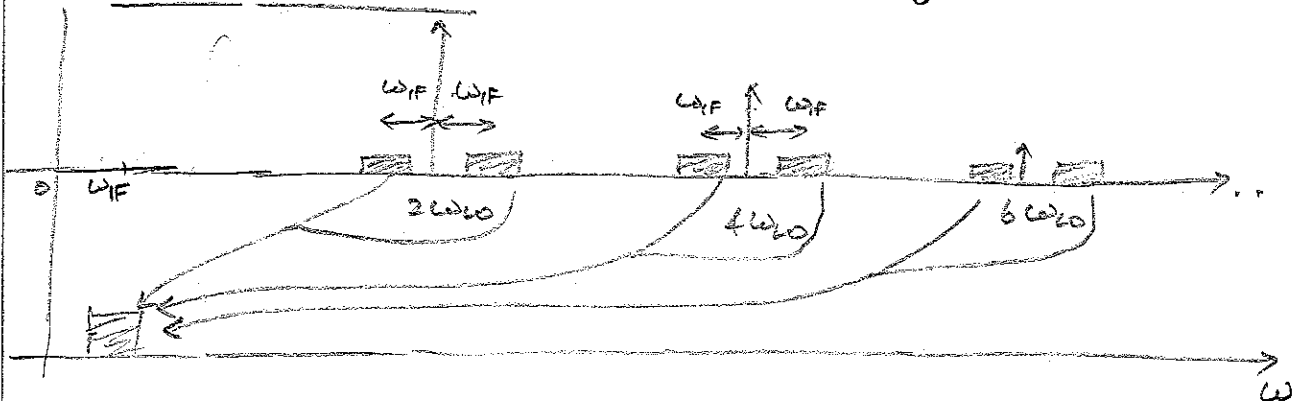
(i) 1/f noise:



- If C_p is neglected, $1/f$ noise can be minimized by extremely fast edge rates.

⇒ Want small LO devices along with square-wave LO drive.

(ii) Thermal noise: Also modulated by $2\omega_{LO}$ pulse train



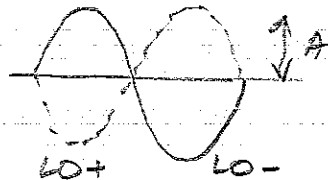
Mean-square voltage noise at output due to thermal noise in switches is:

$$\overline{V_{OSW,th}^2} = 4kTY \frac{I_T}{TA}$$

where I_T = tail (bias current)

A = amplitude of LO \rightarrow

(assuming sine-wave LO)



- \Rightarrow Thermal noise contribution from switching devices does not depend on their size \rightarrow depends only on bias current & LO amplitude.
- \Rightarrow Want large LO drive.

Total noise for single-balanced mixer with resistive loads:

$$\overline{v_{n,out}^2} = 8kTR_L \left(1 + \gamma \frac{R_L I}{\pi A} + \gamma \frac{g_m R_L}{2} \right)$$

Linearity of Gilbert mixer:

Overall linearity limited by:

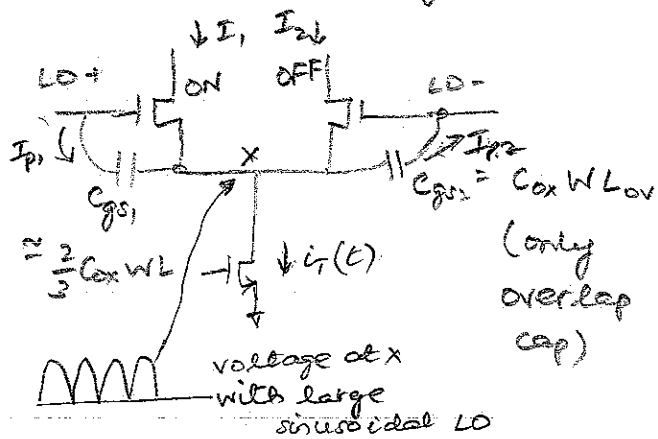
(i) linearity of transconductor:

$$I = I_{DC} + g_{m0} V_{RF} + g_{m1} V_{RF}^2 + g_{m2} V_{RF}^3 + \dots$$

$V_{DC} + V_{RF}$

More on transconductor linearization techniques later.

(ii) Non-linearity due to switches:



- Gate-source caps are vastly different between on & off states
- If $C_{gs1} \neq C_{gs2}$ then $I_{p1} \neq I_{p2}$
- ⇒ difference in displacement current flows into node x

$$KCL @ x: I_1 + I_{p1} = I_{p2} + i_T$$

$$\Rightarrow I_1 = i_T + I_{p2} - I_{p1}$$

$$\approx i_T - C_{gs1} \frac{d(V_{LO} - V_x)}{dt}$$

⇒ I_1 is modulated by the LO

→ sharp LO edges & high LO amplitudes

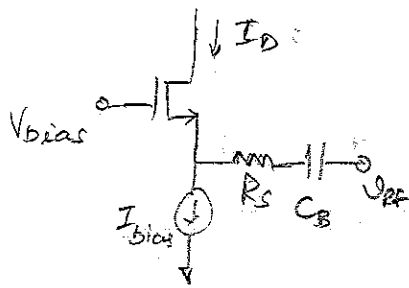
hurt linearity !!

(exact opposite of LO drive requirements

for low-noise)

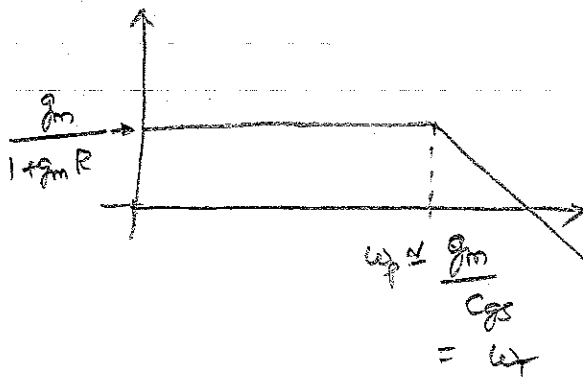
More on transconductors:

1) Common gate:



- C_B = blocking cap, short circuit at high frequencies
- Neglect back-gate effects
- $\Rightarrow G_m$ = effective transconductance

$$G_m = \frac{i_o}{v_{RF}} = \frac{g_m}{1 + g_m R + s C_B R}$$

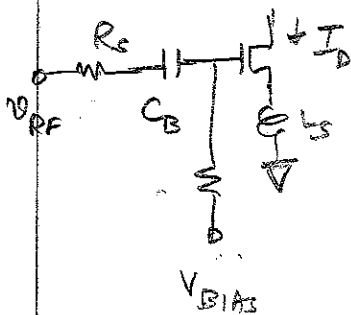


\Rightarrow Very wideband stage

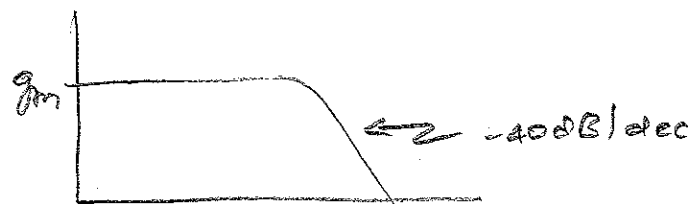
- Useful if matching is required at mixer input
- good linearity because R_S gives source degeneration
- Can use without a degeneration resistor (i.e. $R_S = 0$)

2) Common-source stage:

— Use inductive degeneration for linearity (better than resistor).



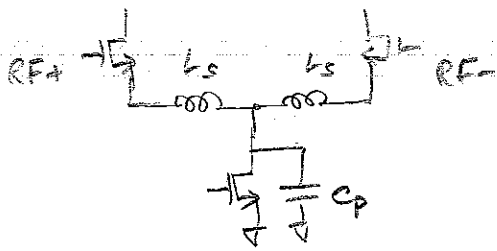
$$G_m = \frac{g_m}{s^2 L_S C_B + s(g_m L_S + C_B R_S) + 1}$$



- Some high-frequency filtering at input.
- Matching to 50Ω not required if input comes from on-chip LNA

3) Differential transconductors:

(i)



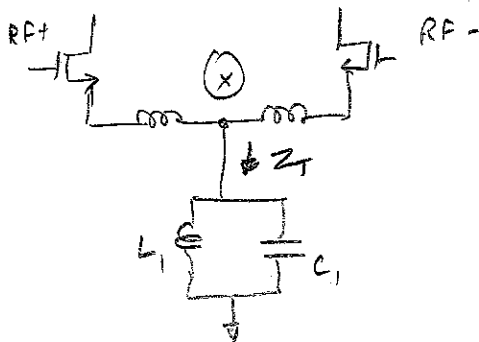
- Fully differential g_m -stage, degeneration optional.
- Good CMRR at low frequencies
- CMRR becomes poor at high frequencies due to C_p .

- Large-signal transfer characteristic is (for $L_s = 0$)

$$I_d = g_m V_{id} \sqrt{1 - \left(\frac{V_{id}}{2V_{dsat}}\right)^2} \equiv V_{id} \left[g_{m0} + g_{m1} V_{id} + g_{m3} V_{id}^3 + g_{m5} V_{id}^5 + \dots \right]$$

- no even harmonics
- significant 3rd order non-linearity
- ⇒ 3rd order intermodulation
- tail current source uses up voltage headroom.

(ii)



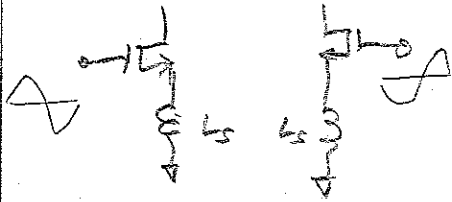
- Voltage at node X has a number of even order harmonics (for a balanced input)

- For high CMRR, want high Z_T at some frequency of interest (e.g. $2\omega_{RF}$)

- LC tank effectively creates a zero-headroom AC current source.

(ii) Balanced c-s transistor:

(or pseudo-differential)



- No current source \Rightarrow zero CMRR at all frequencies (i.e. CMRR is obtained through the perfectly balance)

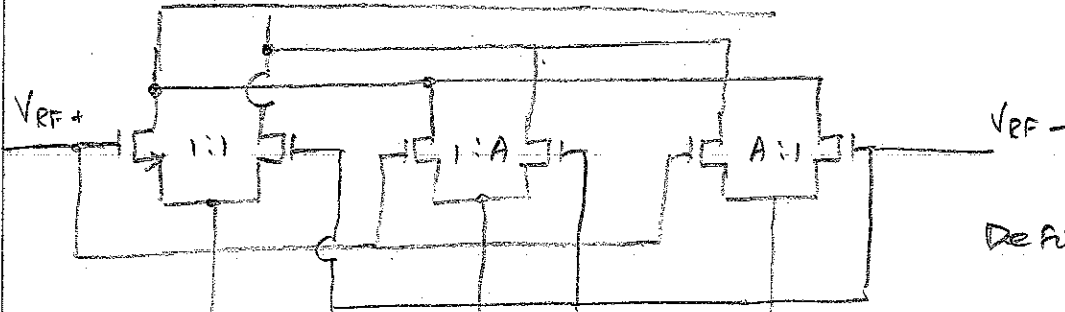
- If we make long-channel assumption,

$$I_D = \frac{K_D}{2} \left(\frac{W}{L} \right) (V_{GS} - V_T)^2 \Rightarrow \text{no 3rd order component}$$

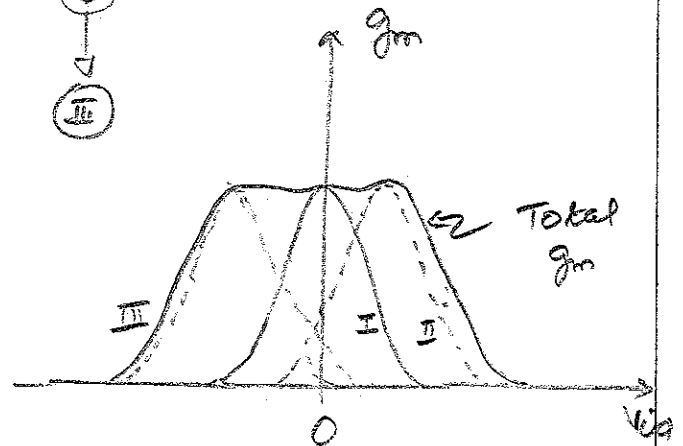
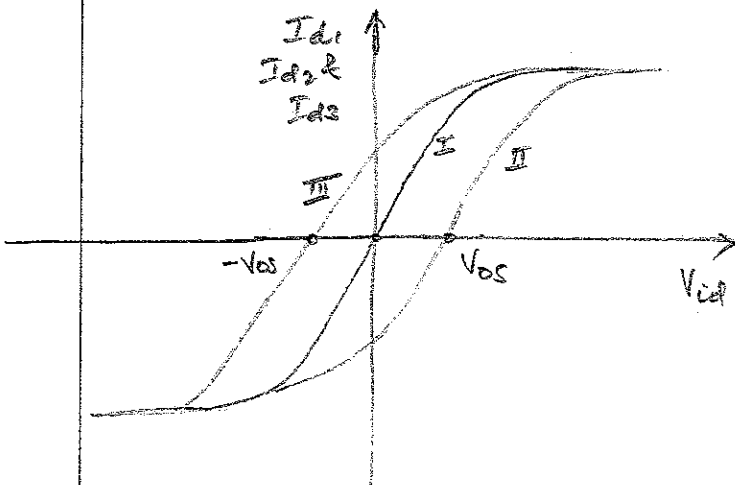
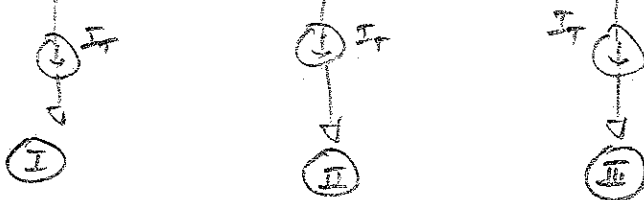
\Rightarrow excellent IIP3.

- Highest voltage headroom

(iv) "Multi-bank" transconductors:



Define $V_{id} = V_{RF+} - V_{RF-}$



$g_{m,eff}$ flat over much wider input signal range \Rightarrow better linearity