



# A Graceful Degradation Framework for Distributed Embedded Systems

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**BOSCH** 

The Bosch logo, featuring the word "BOSCH" in red, bold, sans-serif font, followed by the Bosch logo symbol (a circle with a stylized "H" inside).

Electrical & Computer  
**ENGINEERING**

- ◆ **Robust Self-configuring Embedded Systems (RoSES)**
- ◆ **Robustness gained with automatic graceful degradation**
  - Must not require human intervention to specify or guide
- ◆ **First shot → automated reconfiguration when fault detected**
  
- ◆ **Domain -- Distributed Embedded Systems**
  - Distributed – functionality remains after most failures
  - Smart sensors – general compute capability
  - Most functionality is optimization
  
- ◆ **Examples: elevators, autos, copiers, plant control, ...**
  - Not Internet toasters

## ◆ System-level customization

- “Customize a system to maximize the functionality of given H/W”

## ◆ 3 step, iterative framework for algorithm

- Feature selection – find features to implement
- S/W selection – determine which software components necessary
- Allocation – fit the software to the hardware

- ◆ “Customize a system so as to maximize the functionality of given H/W”
  - Isn’t this just like:
    - Hardware-software co-design? I’m given H/W, not given functionality
    - Reconfigurable computing? I’m not using special purpose H/W, different time constraints
    - Load balancing? I select/allocate S/W for robustness/functionality, not performance
  
- ◆ **Example Scenario: Automotive**
  - Not run-time (yet)
    - Exploit *ground states*
  - May require external assistance
    - Or fault tolerant subsystem (using standard techniques)



# The Algorithm from 30,000 feet



Given: Hardware Spec  
*Product Family* Software Spec



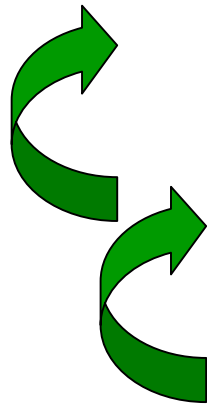
1: Choose *Features* to implement



2: Choose *S/W Adapters* to form features



3: Allocate Adapters to hardware



Iterate on failure



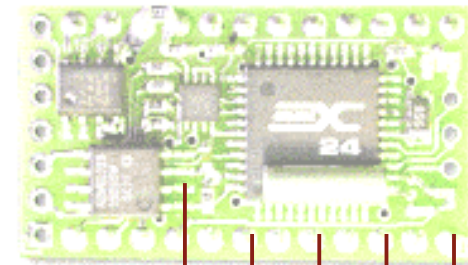
Produce: Adapter  $\leftrightarrow$  PE mapping

## ◆ List of Processing Elements (PEs)

- Vector of available resources
  - CPU cycles, Flash, RAM, ...
- Operational sensors and actuators (attached to PEs)

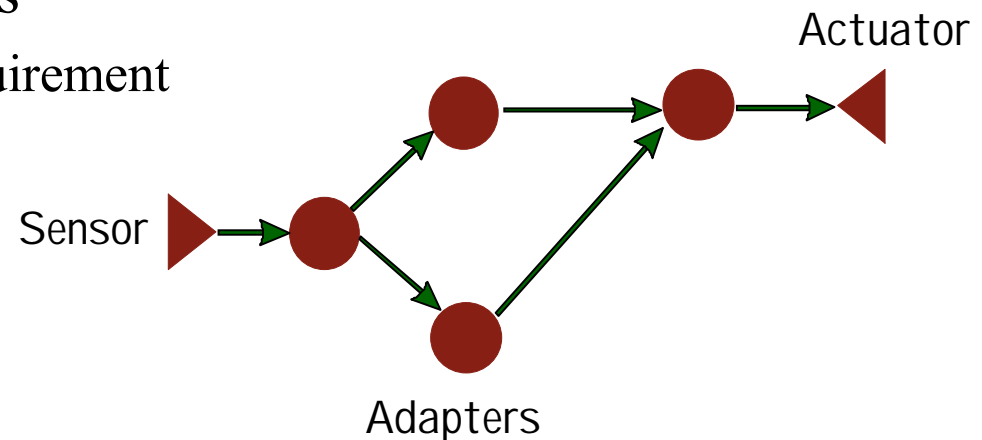
## ◆ Network

- Scalar resource (bandwidth)
- Broadcast, real-time
- Archetype: Control Area Network



CPU ROMRAMDIO AIO PIO

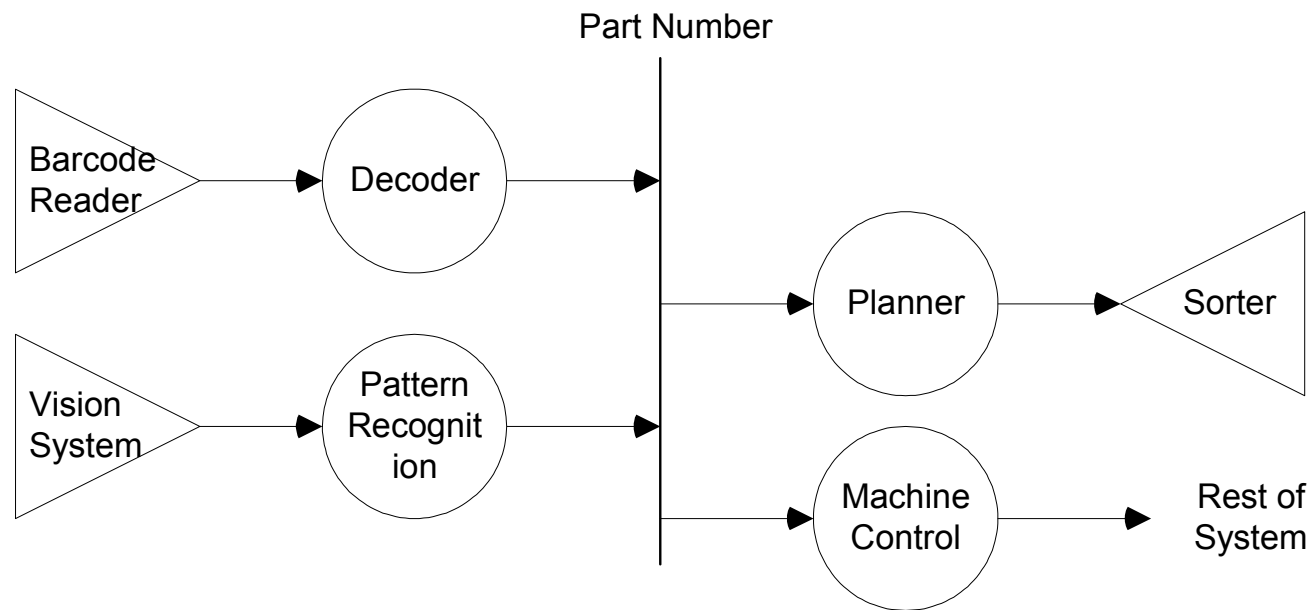
- ◆ **Adapter – RoSES terminology for a software object**
- ◆ **Configuration – collection of adapters**
- ◆ **Configurations form data flow graphs (DFGs)**
  - Vertices are adapters and transducers
    - Adapter requirements specified as a vector, same terms as PEs
    - Transducers are merely sources/sinks of data (don't consume PE resources)
  - Edges are communications
    - Labeled with dataflow requirement
  - Flow
    - from Sensor(s)
    - through 1+ adapters
    - to Actuator(s)



- ◆ **Product Family Architecture (PFA)**
  - Structured view of all possible configurations
- ◆ **PFA graph – specifies capability of entire product/model line**
  - Merge DFGs for all configurations
    - Last year's models
    - High to low end models
    - Etc....
  - PFA Graph is a supergraph of all configuration DFGs



- ◆ **Merge DFGs with choice elements**
  - Data can flow from any one of the inputs
- ◆ **Specialization: data element**
  - Network message type
- ◆ **Ex: Conveyer belt part identification**



# What's a Feature?

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- ◆ **Required as a means to make optimization choices**
  - I tried “Data path through PFA graph”
    - Rejected: Too restrictive
- ◆ **“Use of a particular adapter”**
  - Dependencies communicated via PFA graph
    - Other adapters automatically selected as “glue”
- ◆ **Feature is given utility value**
- ◆ **Similar features require organization**
  - Class-based Feature Model

- ◆ **Collect similar features into *classes***
- ◆ **Only one feature from each class useful**
  - Do you want multiple transmission control algorithms running concurrently?
- ◆ **Some classes may be *critical***
  - A valid feature set includes a feature from all critical classes

$$Utility_{FeatureSet} = \sum_c^{Classes} Utility(Feature_c)$$

## ◆ Goal: Choose a *Feature Set*

- Maximize utility
  - Try highest utility feature set first  
(In general case it won't fit in H/W)

## ◆ Use a combinatorial algorithm

- Start with highest utility feature from each feature class
- Number of feature classes/features is small

# Phase 2: Adapter Selection

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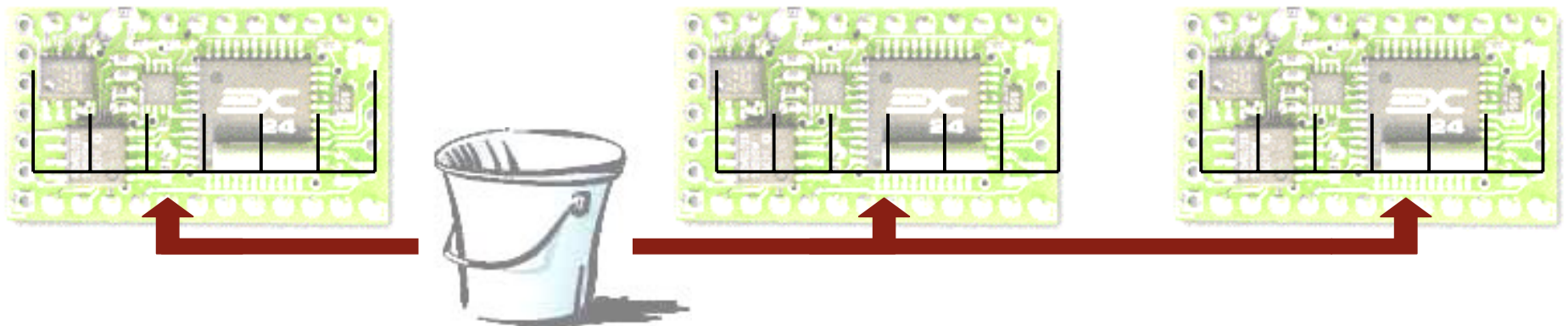
- ◆ **Goal: Choose adapter set to implement the feature set**
  - Prune PFA graph of “dead” adapters
  - Discover paths through features of interest
  - Select paths based on what policies?
    - Heuristic analysis experiment
  - Adapters from selected paths form *Adapter Set*

# Phase 3: Adapter Allocation



## ◆ Goal: Map adapter set to PEs, network

- Well-worn research area
- Bin-packing problem (NP complete)
  - Attack as list processing heuristic
    - » Sort adapters into list (by what criteria?)
    - » Start with largest, packing onto a PE (chosen how?)
    - » Success if list gets emptied





- ◆ **When Phase  $n+1$  fails, Phase  $n$  tries again**
- ◆ **What info does Phase  $n$  need to make intelligent choices for next attempt?**
  - Type of allocation failure (network or PE overflow)
  - How far processing proceeded
  - State of algorithm at failure point
  - ...
- ◆ **Phase 2 failures provide info for phase 1 to make larger moves in search space**



## ◆ Universal Feature Model

- Composability of features, with complex interaction, without combinatorial explosion
- Class based model is sufficiently expressive for most real systems

## ◆ Validity Checks

- System dependent
- User supplied validity check of resulting allocation

## ◆ Scheduling

- Tough. Would obscure proposed work
- Hack: oversize system and apply RMA, or treat as validity failure

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