

# Second Order Ordinary Difference Equations

①

## General Form (IVP)

$$\begin{aligned} a_2 x[k+2] + a_1 x[k+1] + a_0 x[k] &= f[k], & k=0, 1, 2, \dots \\ x[0] &= x_0 \\ x[1] &= x_1 \end{aligned}$$

## Canonical Form

$$\begin{aligned} x[k+2] + a_1 x[k+1] + a_0 x[k] &= f[k], & k=0, 1, 2, \dots \\ x[0] &= x_0 \\ x[1] &= x_1 \end{aligned}$$

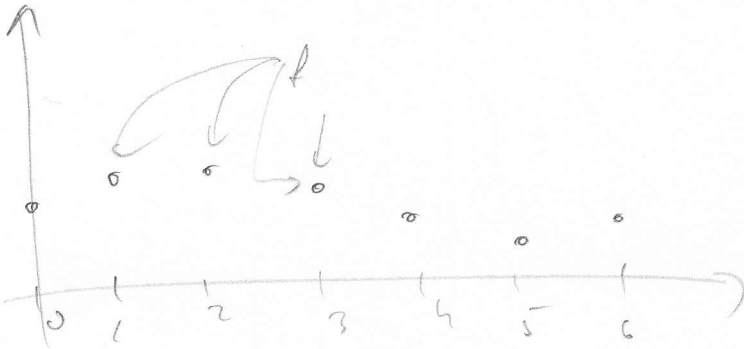
## Solution

- function  $h[k]$  that leads to identity when plugged into ODE and obeys i.c.

Existence: family of functions w. 2 parameters for ODE  $x_p[k]$

Uniqueness:  $x[k]$  solution to IVP is unique

# Plot of DT ODE



## Structure of Solution

$x_g[k]$  general solution has form

$$x_g[k] = x_h[k] + x_p[k]$$

-  $x_h[k]$  is homogeneous solution

solution to  $x[k+2] + a_1 x[k+1] + a_0 x[k] = 0$

2 free parameters

-  $x_p[k]$  is particular solution

one solution to  $x[k+2] + a_1 x[k+1] + a_0 x[k] = f[k]$

no parameters

## Linearity w.r.t. initial condition

Homogeneous IVP: with solution  $x_n[k]$ :

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = 0 \quad k \geq 0,$$

$$x[0] = x_0$$

$$x[1] = x_1$$

$x_{h_1}[k]$  solution to IVP with  $x_{h_1}[0] = x_{0_1}$ ,  $x_{h_1}[1] = x_1$ ,

$x_{h_2}[k]$  solution to IVP with  $x_{h_2}[0] = x_{0_2}$ ,  $x_{h_2}[1] = x_{1_2}$

if  $x_0 = \alpha_1 x_{0_1} + \alpha_2 x_{0_2}$

$$x_1 = \alpha_1 x_{1_1} + \alpha_2 x_{1_2}$$

then

$$x_n[k] = \alpha_1 x_{h_1}[k] + \alpha_2 x_{h_2}[k]$$

Linearity w.r.t. input

For ODE: particular solution  $x_p[k]$

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = f[k]$$

Setup:

ODE 1:

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = f_1[k]$$

ODE 2:

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = f_2[k]$$

If

$$f[k] = \alpha_1 f_1[k] + \alpha_2 f_2[k]$$

Then

$$x_p[k] = \alpha_1 x_{p_1}[k] + \alpha_2 x_{p_2}[k]$$

# Four Step solution

(5)

1) Homogeneous solution

- $x_h[k]$  :
- characteristic polynomial
  - root polynomial  $\rightarrow$  solve  $x_h[k]$
  - roots = eigenvalues, characteristic values, modes, natural frequencies

2) Particular solution

- kind of  $x_p[k]$
- guessing method
  - variation of constants
  - separation of variables

3) General solution

$$x_g[k] = x_h[k] + x_p[k]$$

4) Impose i.c.

$$x_g[0] = x_0$$

$$x_g[1] = x_1$$

$\rightarrow$  Solve for the 2 parameters

# DT Homogeneous ODEs and IVP

(6)

Setup:

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = 0, \quad x[0] = x_0 \\ x[1] = x_1, \\ k=0, 1, \dots$$

Example 1

$$x[k+2] - 2x[k+1] + 2x[k] = 0, \quad k=0, 1, \dots \\ x[0] = 1 \\ x[1] = -1$$

Step 1 Homogeneous Solution

Ansatz:  $x_h[k] = \alpha \rho^k$

Substitute into ODE:

$$\alpha \rho^{k+2} - 2\alpha \rho^{k+1} + 2\alpha \rho^k = 0$$

$$\alpha \rho^k (\rho^2 - 2\rho + 2) = 0$$

$$\Delta(\rho) = \rho^2 - 2\rho + 2$$

$$\Rightarrow \rho_{1,2} = 1 \pm j$$

The two modes of the ODE:

$$(1+j)^k, (1-j)^k, \quad k=0,1,\dots$$

$$\Rightarrow \underline{x_h[k] = (c_1(1+j)^k + c_2(1-j)^k)}$$

Remark: get  $\Delta(z)$  by inspection:

$$x[k+2] \rightarrow z^2$$

$$x[k+1] \rightarrow z$$

$$x[k] \rightarrow z^0 = 1$$

Step 2 Particular solution

$$x_p[k] \equiv 0$$

Step 3 General solution

$$x_g[k] = x_p[k] + x_h[k] = x_h[k]$$

Step 4: IVP

Evaluate general solution at 0, 1:

$$x_g[0] = c_1 + c_2 = 1$$

$$x_g[1] = c_1(1+j) + c_2(1-j) = -1$$

$\Rightarrow$  order 2 linear system

Solve linear system:

$$C_1 = \frac{1}{2} + j$$

$$C_2 = \frac{1}{2} - j$$

$$\underline{x[k] = \left(\frac{1}{2} + j\right)(1+j)^k + \left(\frac{1}{2} - j\right)(1-j)^k}$$

However,  $x[k]$  is a real function.

$$\left(\left(\frac{1}{2} + j\right)(1+j)^k\right)^* = \left(\left(\frac{1}{2} - j\right)(1-j)^k\right)$$

by substituting for  $(\cdot)^*$

$$\Rightarrow \underline{x[k] = 2 \operatorname{Re}\left(\left(\frac{1}{2} + j\right)(1+j)^k\right)}$$

- convert to polar for multiplication/exponentiation

$$\frac{1}{2} + j = \frac{\sqrt{5}}{2} e^{j63.43^\circ}$$

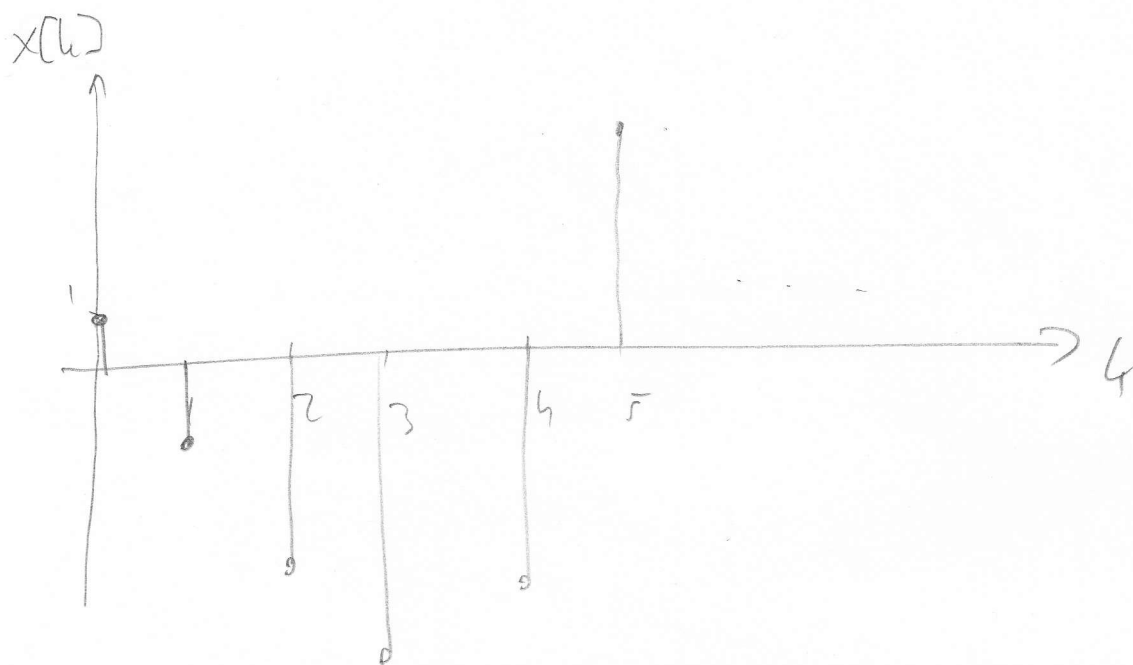
$$1 + j = \sqrt{2} e^{j\frac{\pi}{4}}$$

$$\Rightarrow x[k] = 2 \operatorname{Re}\left(\frac{\sqrt{5}}{2} e^{j63.43^\circ} \sqrt{2} e^{j\frac{4\pi}{4}}\right)$$

$$\underline{\underline{x[k] = \sqrt{10} \cos\left(\frac{4\pi}{4} + 63.43^\circ\right)}}$$



Remark:  $|p_1| = |p_2| > 1 \Rightarrow$  unstable



# General Case / Summary

(10)

$$x[k+2] + a_1 x[k+1] + a_0 x[k] = 0, \quad k=0, 1, 2, \dots$$
$$x[0] = x_0$$
$$x[1] = x_1$$

## Step 1 Homogeneous solution

Characteristic polynomial

$$\Delta(p) = p^2 + a_1 p + a_0$$

$$\Rightarrow p_{1,2} = \frac{-a_1 \pm \sqrt{a_1^2 - 4a_0}}{2}$$

here,  
 $p_1 \neq p_2$

modes:  $x_{h1}[k] = \alpha_1 p_1^k, \quad x_{h2}[k] = \alpha_2 p_2^k$

$$\Rightarrow \underline{x_h[k] = c_1 p_1^k + c_2 p_2^k}, \quad k=0, 1, 2, \dots$$

two free parameters

Step 2: particular solution  $x_p[k] \equiv 0$

Step 3: general solution  $x_g[k] = x_h[k]$

Step 4: IVP  
evaluate  $x_h[k]$  at 0 and 1  $\Rightarrow$  linear system

$$c_1 + c_2 = x_0$$

$$p_1 c_1 + p_2 c_2 = x_1 \quad \Rightarrow \quad c_1, c_2$$

$\Rightarrow$  find real representations (lots of algebra)

## Closed Form Solution

(11)

$$x[k] = C_1 |p_1|^k \cos(\Omega_1 k - C_2)$$

for  $p_1 = |p_1| e^{j\Omega_1}$  we get

$$C_1 = \frac{\sqrt{(x_1 - |p_1| \cos(\Omega_1) \cdot x_0)^2 + (|p_1| \sin(\Omega_1) \cdot x_0)^2}}{|p_1| \sin \Omega_1}$$

$$C_2 = \tan^{-1} \left( \frac{x_1 - |p_1| \cos(\Omega_1) \cdot x_0}{|p_1| \sin(\Omega_1) \cdot x_0} \right)$$

Note: Use of Heaviside function

we often use  $u[k] = \begin{cases} 0, & k = -1, -2, \dots \\ 1, & k = 0, 1, \dots \end{cases}$

to capture the  $k = 0, 1, 2, \dots$  constraint

e.g.  $x[k] = (C_1 p_1^k + C_2 p_2^k) u[k]$