



A New Framework for Evaluating Candidate Technologies for Future Energy Systems



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Outline

- ❑ Motivation
- ❑ Main approach
- ❑ Performance matrix as a function of technology choice
- ❑ Algorithm
- ❑ Illustration of concept
- ❑ Conclusion

Motivation

- ❑ Systematic comparison of candidate technologies for the changing electrical energy industry
- ❑ It is insufficient to invest into given technology without accessing its cumulative operational effects (efficiency, reliability, environmental impact...)

Main approach

- ❑ An “optimal” technology (type, capacity, location) is the technology whose cumulative operational benefit over time T equals to its capacity cost [5].
- ❑ This captures the inter-temporal dependence between short-term effects (operation) and long-term investments (planning).

Performance matrix ...

... as a Function of Technology Choice

$$\text{PMT(TC)} = \begin{aligned} & \text{Cumulative System Operational Cost} \\ & + \text{Capital Cost} \\ & - \text{Cumulative Benefit of Customers} \end{aligned}$$

Subject to: 1) decisions – driven dynamics
2) natural system dynamics and constraints

Example of ...

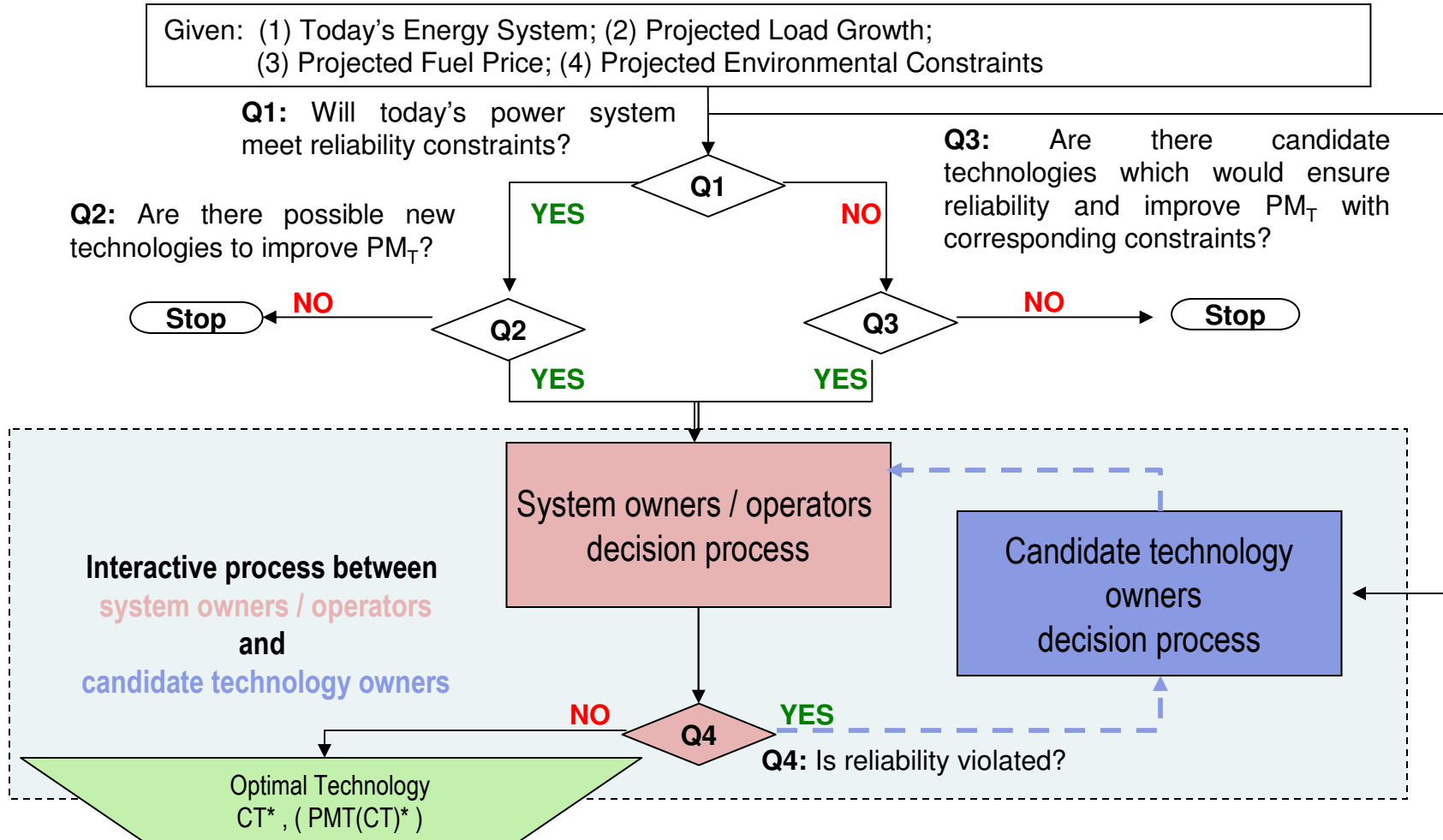
□ Candidate technologies

- Load management
- Software for optimal scheduling
- Reliability differentiate priority service
- Advanced generation control
- Filters for quality of supply
- Distributed generation
- Energy storage; V2G
- FACTS
- PMU

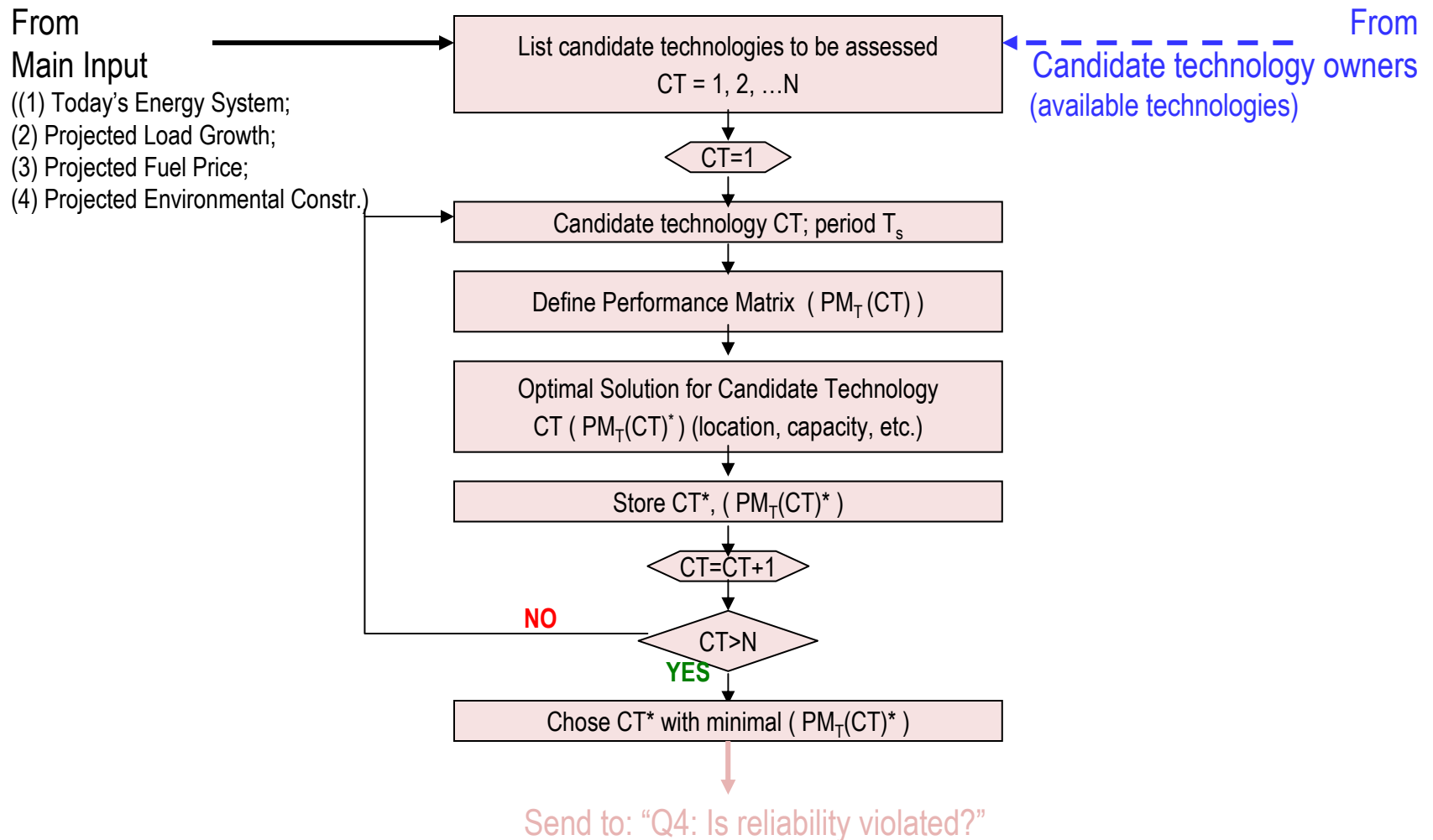
□ Efficiency measures

- Delivery losses
- Reserve requirements
- Environmental effects
- Harmonics

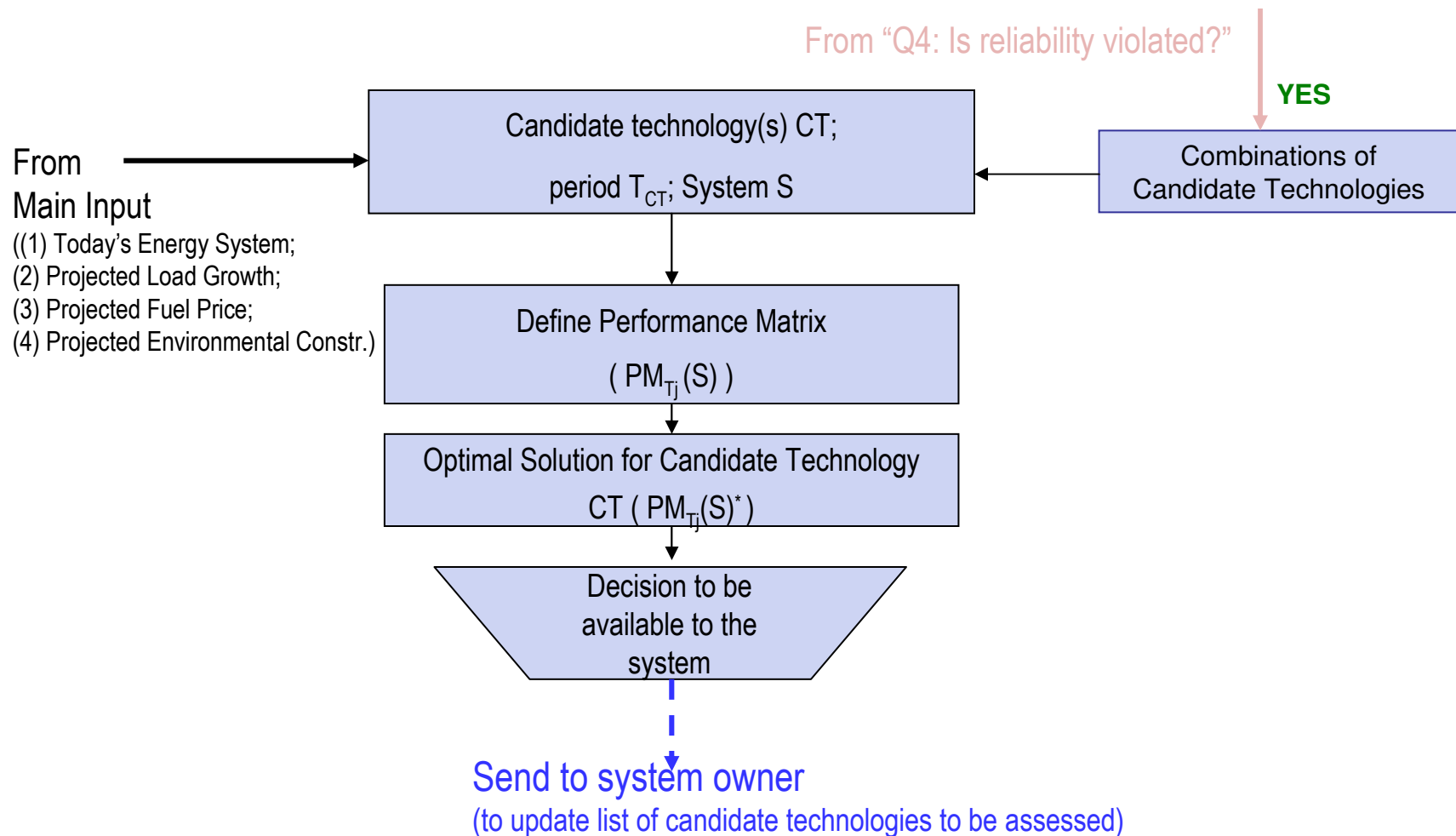
Algorithm



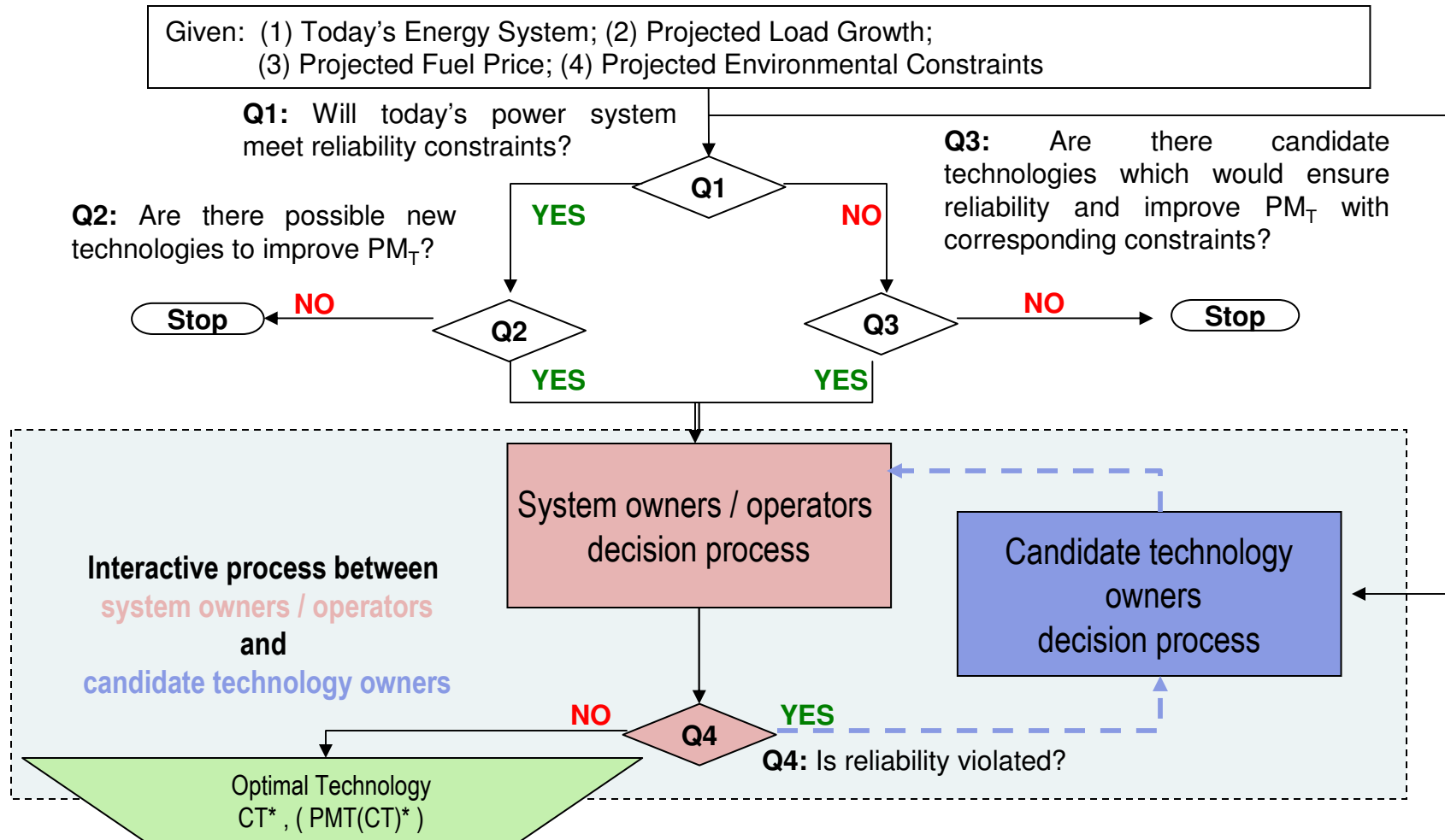
System owners decision process



Candidate technology owners decision



Algorithm



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Illustration of concept

- Distribution system planning
- Motivation: New technologies and customer demand types
- The main idea: Capture the inter-temporal dependence between short-term effect and long-term investments
- Approach: Find the “optimal” technology

$$\begin{aligned}
 & \text{Cumulative over time} \quad \text{Benefit to the Customers} \\
 PM_T(TC) = & \max_{P_l^t, P_d^t, x_l, b_l, r_l} \pi = \sum_{t=1}^T \left[\rho^{t-1} \cdot \left(\sum_{i=1}^n (N_i^t \cdot a_i^t + b_i^t \cdot P_{di}^t) \cdot T^t - \right. \right. \\
 & \text{System Operational Cost} \quad \left. \left. \sum_{l=1}^m (a_l^t (x_l^t + x_l^t) + d_l^t (P_l^t + P_l^t) + c_l^t ((P_l^t)^2 + (P_l^t)^2)) \cdot l_l \cdot T^t - \right. \right. \\
 & \left. \left. \text{Capital Investments} \quad \left. \left. \sum_{l=1}^{m_{\text{new}}} C_{\text{buiLine}} \cdot b_l^t \cdot l_l \cdot P_l^{\text{max}} - \sum_{l=1}^{m_{\text{old}}} C_{\text{reiLine}} \cdot r_l^t \cdot l_l \cdot \Delta P_l^{\text{max}} \right) \right] \right]
 \end{aligned}$$

Subject to: 1) decisions – driven dynamics
 2) natural system dynamics and constraints

Illustration of concept (cont.)

- Different technologies and different scenarios
 - “Classical” approach – addition of new lines,
 - “With CDG” approach – addition of new lines and **controllable distributed generators**,
 - “With DLC” approach – addition of new lines and direct **load control**,
 - “With DLC and CDG” approach – addition of new lines, direct **load control** and **controllable distributed generators**,
 - “With DLC and DG” approach – addition of new lines, direct **load control** and **uncontrollable distributed generators** that will always produce P_{max} .

Illustration of concept (cont.)

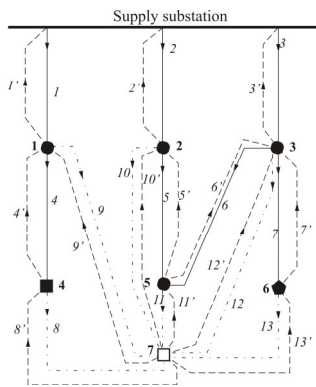


Fig 1 - Test network

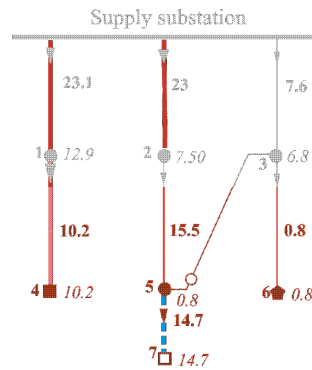


Fig 2 - "Classical Approach"

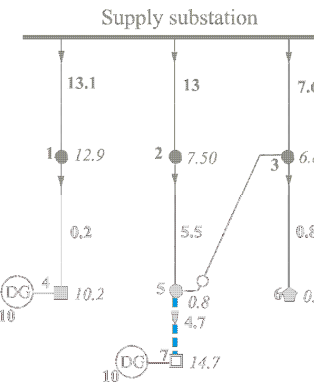


Fig 3 - With Controllable Distributed Generation

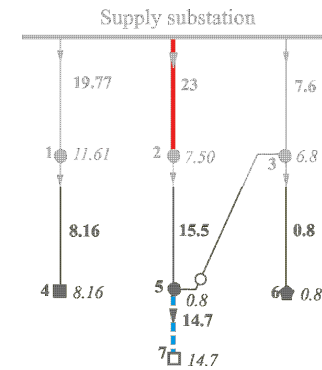


Fig 4 - With Direct Load Control

- Customer types:
- commercial
 - industry
 - ⊙ household
 - normal-open switch
 - ▼ power flow
- old line
 - - - new line
 — reinforced line
- ⊙ DG distributed generator
 ⊙ DG uncontrollable distributed generator

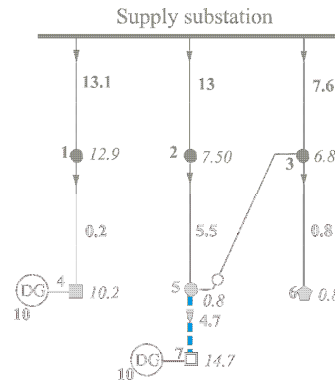


Fig 5 - With Direct Load Control and Controllable Distributed Generation

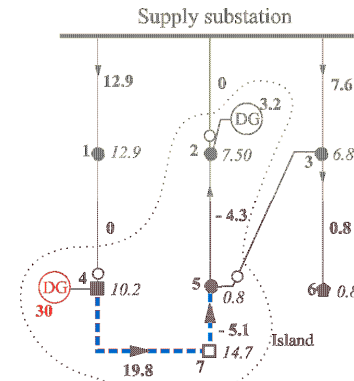


Fig 6 - With Direct Load Control and Uncontrollable Distributed Generation

Illustration of concept (cont.)

	“Classical”	With CDG	With DLC	With DLC and CDG	With DLC and UDG
Build new line	Yes Line:11 Year:5	Yes Line:11 Year:5	Yes Line:11 Year:5	Yes Line:11 Year:5	Yes Line:11 Year: 1 Line: 8 Year: 1
Replacement	Yes Line:2 Year:6 Line:1 Year:9 Lline:4 Year:10	No	Yes Line:2 Year:8	No	No
Load reduction	No	No	Yes	No	No
Bi-directional power flow	No	Yes	No	Yes	Yes
Performance Matrix	Minimal Costs \$ 4,064,024	Minimal Cost \$ 875,605	Maximal Social Welfare \$ 19,865,187	Maximal Social Welfare \$ 21,857,525	Maximal Social Welfare \$ 18,490,074

Conclusions

- ❑ New technologies require new paradigms of planning and operations
- ❑ Systematic comparison and evaluation of both old technologies and new candidate technologies is needed
- ❑ It is insufficient to invest into technology without accessing its cumulative operational effects

References:

- 1) M. Prica, and M. Ilić, “A New Framework for Evaluating Candidate Technologies for Future Energy Systems,” working paper
- 2) M. Prica and M. Ilić, “Optimal Distribution Service Pricing for Investment Planning,” *Proceedings of the IEEE General Power Meeting*, Tampa, FL, 2007
- 3) M. Prica and M. Ilić, “Peak-Load Pricing Based Planning for Distribution Networks Under Change,” *Proceedings of the IEEE General Power Meeting*, Montreal CA, June 2006
- 4) J.P. Leotard “Transmission Pricing and Incentives for Investments under Uncertainty in the Deregulated Power Industry”, Ms thesis, MIT, February 1999.

Thank you!

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Questions?
