A Note on 740 Next Semester

- If you like 447, 740 is the next course in sequence
- Tentative Time: Lect. MW 7:30-9:20pm, Rect. T 7:30pm
- Content:
  - Lectures: More advanced, with a different perspective
  - Recitations: Delving deeper into papers, advanced topics
  - Readings: Many fundamental and research readings; will do many reviews
  - Project: More open ended research project. Proposal → milestones → final poster and presentation
  - Exams: lighter and fewer
  - Homeworks: None
Where We Are in Lecture Schedule

- The memory hierarchy
- Caches, caches, more caches
- Virtualizing the memory hierarchy: Virtual Memory
- Main memory: DRAM
- Main memory control, scheduling
- Memory latency tolerance techniques
- Non-volatile memory

- Multiprocessors
- Coherence and consistency
- Interconnection networks
- Multi-core issues (e.g., heterogeneous multi-core)
Cache Coherence
Readings: Cache Coherence

- **Required**
  - Culler and Singh, *Parallel Computer Architecture*
    - Chapter 5.1 (pp 269 – 283), Chapter 5.3 (pp 291 – 305)
  - P&H, *Computer Organization and Design*
    - Chapter 5.8 (pp 534 – 538 in 4th and 4th revised eds.)

- **Recommended**
Review: Two Cache Coherence Methods

- How do we ensure that the proper caches are updated?

- **Snoopy Bus** [Goodman ISCA 1983, Papamarcos ISCA 1984]
  - Bus-based, **single point of serialization for all memory requests**
  - Processors observe other processors’ actions
    - E.g.: P1 makes “read-exclusive” request for A on bus, P0 sees this and invalidates its own copy of A

- **Directory** [Censier and Feautrier, IEEE ToC 1978]
  - **Single point of serialization per block**, distributed among nodes
  - Processors make explicit requests for blocks
  - Directory tracks which caches have each block
  - Directory coordinates invalidation and updates
    - E.g.: P1 asks directory for exclusive copy, directory asks P0 to invalidate, waits for ACK, then responds to P1
Directory Based Cache Coherence
Review: Directory Based Coherence

- **Idea:** A logically-central directory keeps track of where the copies of each cache block reside. Caches consult this directory to ensure coherence.

- **An example mechanism:**
  - For each cache block in memory, store $P+1$ bits in directory
    - One bit for each cache, indicating whether the block is in cache
    - Exclusive bit: indicates that a cache has the only copy of the block and can update it without notifying others
  - On a read: set the cache’s bit and arrange the supply of data
  - On a write: invalidate all caches that have the block and reset their bits
  - Have an “exclusive bit” associated with each block in each cache (so that the cache can update the exclusive block silently)
Directory Based Coherence Example (I)

Example directory based scheme

- \( P = 4 \)
- Exclusive bit
- \( P + 1 \) bits for block A
  - No cache has the block
  - \( P_1 \) takes a read miss to block A
    - \( \begin{array}{c}
    0 \ 0 \ 0 \ 0 \ 0 \\
    \end{array} \) \( \rightarrow \) \( \begin{array}{c}
    0 \ 1 \ 0 \ 0 \ 0 \ 0 \\
    \end{array} \)
  - \( P_3 \) takes a read miss
    - \( \begin{array}{c}
    0 \ 1 \ 0 \ 1 \ 0 \ 0 \ 0 \\
    \end{array} \)
3. P₂ takes a write miss
   → Invalidate P₁ & P₃'s cache
   → Write request: P₂ has the exclusive copy of the block now. Set the Exclusive bit
   → P₂ can now update the block without notifying any other processor or the directory
   → P₂ needs to have a bit in its cache indicating it can perform exclusive updates to that block
   → Private/exclusive bit per cache block

4. P₃ takes a write miss
   → Mem controller requests block from P₂
   → Mem controller gives block to P₃
   → P₂ invalidates its copy

5. P₂ takes a read miss
   → P₃ supplies it
Snoopy Cache Coherence
Snoopy Cache Coherence

**Idea:**
- All caches “snoop” all other caches’ read/write requests and keep the cache block coherent
- Each cache block has “coherence metadata” associated with it in the tag store of each cache

**Easy to implement if all caches share a common bus**
- Each cache broadcasts its read/write operations on the bus
- Good for small-scale multiprocessors
- What if you would like to have a 1000-node multiprocessor?
SNOOPY CACHE

Each Cache observes its own processor & the bus
- Changes the state of the cached block based on observed actions by processor & the bus

Processor actions to a block:
- PR (Proc. Read)
- RW (Proc. Write)

Bus actions to a block:
- BR (Bus Read)
- BW (Bus Write)

or BRx (Bus Read Exclusive)
A Simple Snoopy Cache Coherence Protocol

- Caches “snoop” (observe) each other’s write/read operations
- A simple protocol (VI protocol):
  - Write-through, no-write-allocate cache
  - Actions of the local processor on the cache block: PrRd, PrWr,
  - Actions that are broadcast on the bus for the block: BusRd, BusWr
Extending the Protocol

- What if you want write-back caches?
  - We want a “modified” state
A More Sophisticated Protocol: MSI

- Extend metadata per block to encode three states:
  - M(odified): cache line is the only cached copy and is dirty
  - S(hared): cache line is potentially one of several cached copies
  - I(nvalid): cache line is not present in this cache

- Read miss makes a Read request on bus, transitions to S
- Write miss makes a ReadEx request, transitions to M state
- When a processor snoops ReadEx from another writer, it must invalidate its own copy (if any)
- S→M upgrade can be made without re-reading data from memory (via Invalidations)
MSI State Machine
The Problem with MSI

- A block is in no cache to begin with
- Problem: On a read, the block immediately goes to “Shared” state although it may be the only copy to be cached (i.e., no other processor will cache it)

Why is this a problem?
- Suppose the cache that read the block wants to write to it at some point
- It needs to broadcast “invalidate” even though it has the only cached copy!
- If the cache knew it had the only cached copy in the system, it could have written to the block without notifying any other cache \(\rightarrow\) saves unnecessary broadcasts of invalidations
The Solution: MESI

- **Idea:** Add another state indicating that this is the only cached copy and it is clean.
  - *Exclusive state*

- Block is placed into the *exclusive* state if, during *BusRd*, no other cache had it
  - Wired-OR “shared” signal on bus can determine this: snooping caches assert the signal if they also have a copy

- Silent transition *Exclusive* $\rightarrow$ *Modified* is possible on write!

- MESI is also called the *Illinois protocol*
Illinois Protocol

States:
- M: Modified
  - Exclusive copy, modified
- E: Exclusive
  - "", clean
- S: Shared
  - Shared copy, clean
- I: Invalid

BI: Invalidate, but already have the data (do not supply it)
BRI: Invalidate, but also need the data (supply it)

Papenroth & Patel, ISCA 1984
MESI State Machine
MESI State Machine

[Culler/Singh96]
A transition from a single-owner state (Exclusive or Modified) to Shared is called a **downgrade**, because the transition takes away the owner's right to modify the data.

A transition from Shared to a single-owner state (Exclusive or Modified) is called an **upgrade**, because the transition grants the ability to the owner (the cache which contains the respective block) to write to the block.
MESI State Machine from Lab 8

- **Invalid**
  - Transitions to other states based on cache miss conditions.
  - Transitions to **Shared** when another cache has a write-miss.
  - Transitions to **Modified** when another cache has a read-miss.
  - Transitions to **Exclusive** when another cache has a write-miss.

- **Shared**
  - Transitions to other states based on cache miss conditions.
  - Transitions to **Shared** when another cache has a write-miss.
  - Transitions to **Exclusive** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Modified**
  - Transitions to other states based on cache miss conditions.
  - Transitions to **Shared** when another cache has a write-miss.
  - Transitions to **Invalid** when another cache has a read-miss.
  - Transitions to **Exclusive** when another cache has a write-miss.

- **Exclusive**
  - Transitions to other states based on cache miss conditions.
  - Transitions to **Shared** when another cache has a read-miss.
  - Transitions to **Invalid** when another cache has a write-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Write** (mark dirty)
  - Transitions to **Invalid** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Write** (upgrade and inval. others)
  - Transitions to **Shared** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Other cache has read-miss (downgrade)**
  - Transitions to **Invalid** when another cache has a write-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Other cache has write-miss (invalidate)**
  - Transitions to **Invalid** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Cache miss (1 requester)**
  - Transitions to **Invalid** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.

- **Cache miss (> 1 requester)**
  - Transitions to **Invalid** when another cache has a read-miss.
  - Transitions to **Modified** when another cache has a write-miss.
Intel Pentium Pro

Slide credit: Yale Patt
Snoopy Invalidation Tradeoffs

- Should a downgrade from M go to S or I?
  - S: if data is likely to be reused (before it is written to by another processor)
  - I: if data is likely to be not reused (before it is written to by another processor)

- Cache-to-cache transfer
  - On a BusRd, should data come from another cache or memory?
    - Another cache
      - May be faster, if memory is slow or highly contended
    - Memory
      - Simpler: no need to wait to see if another cache has the data first
      - Less contention at the other caches
      - Requires writeback on M downgrade

- Writeback on Modified->Shared: necessary?
  - One possibility: Owner (O) state (MOESI protocol)
    - One cache owns the latest data (memory is not updated)
    - Memory writeback happens when all caches evict copies
The Problem with MESI

- **Observation:** Shared state requires the data to be clean
  - i.e., all caches that have the block have the up-to-date copy and so does the memory

- **Problem:** Need to write the block to memory when BusRd happens when the block is in Modified state

- **Why is this a problem?**
  - Memory can be updated unnecessarily → some other processor may want to write to the block again
Improving on MESI

- Idea 1: Do not transition from M→S on a BusRd. Invalidate the copy and supply the modified block to the requesting processor directly without updating memory.

- Idea 2: Transition from M→S, but designate one cache as the owner (O), who will write the block back when it is evicted.
  - Now “Shared” means “Shared and potentially dirty”
  - This is a version of the MOESI protocol.
Tradeoffs in Sophisticated Cache Coherence Protocols

- The protocol can be optimized with more states and prediction mechanisms to
  + Reduce unnecessary invalidates and transfers of blocks

- However, more states and optimizations
  -- Are more difficult to design and verify (lead to more cases to take care of, race conditions)
  -- Provide diminishing returns
Revisiting Two Cache Coherence Methods

- How do we ensure that the proper caches are updated?

- **Snoopy Bus** [Goodman ISCA 1983, Papamarcos+ ISCA 1984]
  - Bus-based, single point of serialization for all memory requests
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- **Directory** [Censier and Feautrier, IEEE ToC 1978]
  - Single point of serialization per block, distributed among nodes
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**Snoopy Cache vs. Directory Coherence**

- **Snoopy Cache**
  - Miss latency (critical path) is short: request $\rightarrow$ bus transaction to mem.
  - Global serialization is easy: bus provides this already (arbitration)
  - Simple: can adapt bus-based uniprocessors easily
  - Relies on broadcast messages to be seen by all caches (in same order):
    - single point of serialization (bus): *not scalable*
    - need a virtual bus (or a totally-ordered interconnect)

- **Directory**
  - Adds indirection to miss latency (critical path): request $\rightarrow$ dir. $\rightarrow$ mem.
  - Requires extra storage space to track sharer sets
    - Can be approximate (false positives are OK for correctness)
  - Protocols and race conditions are more complex (for high-performance)
  - Does not require broadcast to all caches
  - Exactly as scalable as interconnect and directory storage
    *much more scalable than bus*
Revisiting Directory-Based Cache Coherence
Remember: Directory Based Coherence

- **Idea:** A logically-central directory keeps track of where the copies of each cache block reside. Caches consult this directory to ensure coherence.

- **An example mechanism:**
  - For each cache block in memory, store P+1 bits in directory
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  - On a read: set the cache’s bit and arrange the supply of data
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  - Have an “exclusive bit” associated with each block in each cache
Remember: Directory Based Coherence

Example directory based scheme

$p+1$ bits: for block $A$

$P_1$ takes a read miss to block $A$

$P_3$ takes a read miss

No cache has the block
Directory-Based Protocols

- Required when scaling past the capacity of a single bus
- Distributed, *but*:
  - Coherence still requires single point of serialization (for write serialization)
  - Serialization location can be different for every block (striped across nodes)

- We can reason about the protocol for a single block: one *server* (directory node), many *clients* (private caches)

- Directory receives *Read* and *ReadEx* requests, and sends *Invl* requests: invalidation is explicit (as opposed to snoopy buses)
Directory: Data Structures

- Required to support invalidation and cache block requests
- Key operation to support is *set inclusion test*
  - False positives are OK: want to know which caches *may* contain a copy of a block, and spurious invalidations are ignored
  - False positive rate determines performance
- Most accurate (and expensive): full bit-vector
- Compressed representation, linked list, Bloom filters are all possible
Directory: Basic Operations

- Follow *semantics* of snoop-based system
  - but with explicit request, reply messages

- Directory:
  - Receives *Read, ReadEx, Upgrade* requests from nodes
  - Sends *Inval/Downgrade* messages to sharers if needed
  - Forwards request to memory if needed
  - Replies to requestor and updates sharing state

- Protocol design is flexible
  - Exact forwarding paths depend on implementation
  - For example, do cache-to-cache transfer?
MESI Directory Transaction: Read

P0 acquires an address for reading:

1. Read

2. DatEx (DatShr)
RdEx with Former Owner

1. RdEx

P0

Home

2. Invl

Owner

3a. Rev

3b. DatEx
Contestion Resolution (for Write)

1a. RdEx
4. Invl
5a. Rev

2a. DatEx

3. RdEx

1b. RdEx

5b. DatEx

P0

Home

P1
Issues with Contention Resolution

- Need to escape race conditions by:
  - NACKing requests to busy (pending invalidate) entries
    - Original requestor retries
  - OR, queuing requests and granting in sequence
  - (Or some combination thereof)

- Fairness
  - Which requestor should be preferred in a conflict?
  - Interconnect delivery order, and distance, both matter

- Ping-pong is a higher-level issue
  - With solutions like combining trees (for locks/barriers) and better shared-data-structure design
Scaling the Directory: Some Questions

- How large is the directory?
- How can we reduce the access latency to the directory?
- How can we scale the system to thousands of nodes?

- Can we get the best of snooping and directory protocols?
  - Heterogeneity
  - E.g., token coherence [Martin+, ISCA 2003]
Advancing Coherence
Motivation: Three Desirable Attributes

- Low-latency cache-to-cache misses
- No bus-like interconnect
- Bandwidth efficient

Dictated by workload and technology trends
Workload Trends

• Commercial workloads
  – Many cache-to-cache misses
  – Clusters of small multiprocessors

• Goals:
  – Direct cache-to-cache misses
    (2 hops, not 3 hops)
  – Moderate scalability

Workload trends → snooping protocols
Workload Trends

Low-latency cache-to-cache misses

No bus-like interconnect

Bandwidth efficient
Workload Trends △ Snooping Protocols

- Low-latency cache-to-cache misses
  - Yes: direct request/response
- No bus-like interconnect
  - No: requires a “virtual bus”
- Bandwidth efficient
  - No: broadcast always
Technology Trends

• High-speed point-to-point links
  – No (multi-drop) busses

• Increasing design integration
  – “Glueless” multiprocessors
  – Improve cost & latency

• Desire: low-latency interconnect
  – Avoid “virtual bus” ordering
  – Enabled by directory protocols

Technology trends → unordered interconnects
Technology Trends

Low-latency cache-to-cache misses

No bus-like interconnect → Bandwidth efficient
Technology Trends: Directory Protocols

- Low-latency cache-to-cache misses
  - (No: indirection through directory)

- No bus-like interconnect
  - (Yes: no ordering required)

- Bandwidth efficient
  - (Yes: avoids broadcast)
Goal: All Three Attributes

Low-latency cache-to-cache misses

No bus-like interconnect

Bandwidth efficient

Step#1

Step#2
Token Coherence: Key Insight

• Goal of invalidation-based coherence
  – Invariant: many readers -or- single writer
  – Enforced by globally coordinated actions

  Key insight

• Enforce this invariant directly using tokens
  – Fixed number of tokens per block
  – One token to read, all tokens to write

• Guarantees safety in all cases
  – Global invariant enforced with only local rules
  – Independent of races, request ordering, etc.
A Case for
Asymmetry Everywhere

Onur Mutlu,
"Asymmetry Everywhere (with Automatic Resource Management)"
Position paper