

Second Order ODEs - Continuous Time

(7)

- More expressive than 1st order:
 - 1st order: RL and RC circuits (Decay, blowup)
 - 2nd order: RLC circuits (Decay, blowup, oscillation)
- Many systems with oscillation behavior can be modeled by 2nd order ODEs
 - ECE
 - MechE
 - population dynamics

General Form (IVP)

$$a_2 \frac{d^2 x(t)}{dt^2} + a_1 \frac{dx}{dt} + a_0 x(t) = f(t), \quad t \geq t_0$$

$x(t_0) = x_0$
 $\dot{x}(t_0) = \dot{x}_0$

Canonical Form (IVP)

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 x(t) = f(t), \quad t \geq t_0$$

$x(t_0) = x_0$
 $\dot{x}(t_0) = \dot{x}_0$

- Existence of general solution
 - Uniqueness of IVP
- general solution has 2 parameters

$\dot{x} = \frac{dx(t)}{dt}$	$\ddot{x} = \frac{d^2 x(t)}{dt^2}$
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Solution of ODE and IVP

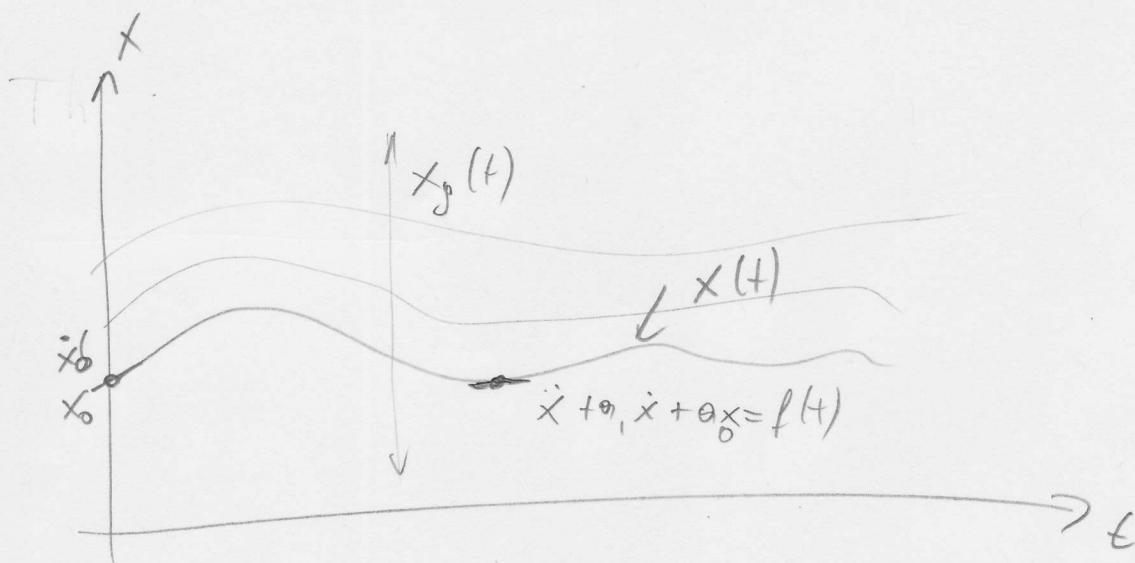
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Function $h(t)$ such that

- when applying LHS it is \equiv RHS for $t \geq 0$] ODE

- At $t=0$ $h(t) = x_0$ and $\dot{h}(t) = \dot{x}_0$] IVP

- Solution to ODE without i.c. is
general solution $x_g(t)$



Three properties

- Structure $x_g = x_h + x_p$

- Linearity w.r.t. initial conditions

- Linearity w.r.t. forcing term

Structure of Solution

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$x_g(t)$ general solution to $\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 x(t) = f(t)$

$$\Rightarrow \boxed{x_g(t) = x_h(t) + x_p(t)} \quad \text{with}$$

- $x_h(t)$ is homogeneous solution:

$x_h(t)$ general solution to $\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 x(t) = \underline{\underline{0}}$
2 free parameters

- $x_p(t)$ is particular solution:

one solution to $\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 x(t) = f(t)$

no parameter

- plug $x_g(t) = x_h(t) + x_p(t)$ into ODE

to show that this holds

Linearity w.r.t. initial condition

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Homogeneous IVP: with solution $x_h(t)$:

$$\frac{d^2x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 = 0, \quad t \geq 0, \quad x(0) = x_0, \quad \dot{x}(0) = \dot{x}_0$$

$x_{h_1}(t)$ solution to IVP with $x(0) = x_{0_1}, \dot{x}(0) = \dot{x}_{0_1}$

$x_{h_2}(t)$ solution to IVP with $x(0) = x_{0_2}, \dot{x}(0) = \dot{x}_{0_2}$

if $x_0 = \alpha_1 x_{0_1} + \alpha_2 x_{0_2}$

$$\dot{x}_0 = \alpha_1 \dot{x}_{0_1} + \alpha_2 \dot{x}_{0_2}$$

then

$$x_h(t) = \alpha_1 x_{h_1}(t) + \alpha_2 x_{h_2}(t)$$

Linearity w.r.t. input

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For ODE: with particular solution $x_p(t)$

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 = \underline{f(t)}$$

With

For ODE: with particular solution $x_{p_1}(t)$

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 = \underline{f_1(t)}$$

For ODE: with particular solution $x_{p_2}(t)$

$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 = \underline{f_2(t)}$$

if

$$f(t) = \alpha_1 f_1(t) + \alpha_2 f_2(t)$$

Then

$$x_p(t) = \alpha_1 x_{p_1}(t) + \alpha_2 x_{p_2}(t)$$

Four step solution

1) Homogeneous solution

$x_h(t) \rightarrow$ characteristic polynomial
(ODE \rightarrow algebraic problem)

root polynomial \rightarrow solve x_n
roots = eigen values, characteristic values
modes, 'natural frequencies

2) Particular solution

find a $x_p(t) \rightarrow$ guessing method
variation of constants
separation of variables

3) General solution

$$x_g(t) = x_h(t) + x_p(t)$$

4) Impose i.c. (Solve IVP)

$$\begin{aligned} x_g(0) &= x_0 \\ \dot{x}_g(0) &= \dot{x}_0 \end{aligned} \rightarrow \text{solve for the 2 parameter}$$

Homogeneous ODEs and IVP

Solup

$$\ddot{x} + a_1 \dot{x} + a_0 = 0, \quad t \geq 0, \quad x(0) = x_0, \quad \dot{x}(0) = \dot{x}_0$$

$$\Rightarrow x_p(t) \equiv 0$$

Second Order ODEs have 2 characteristic roots

- 2 real (distinct only in this course)
- 2 conjugate complex

Solution to characteristic polynomial

Example 1

$$\frac{d^2 x(t)}{dt^2} + 3 \frac{dx(t)}{dt} + 2x(t) = 0, \quad t \geq 0$$

$$x(0) = 0$$

$$\dot{x}(0) = 1$$

Step 1 Homogeneous Solution

Ansatz: $x_h(t) = \alpha e^{\lambda t}$

$$\Rightarrow \dot{x}(t) = \alpha \lambda e^{\lambda t}$$

$$\ddot{x}(t) = \alpha \lambda^2 e^{\lambda t}$$

Substitute into ODE:

$$\alpha e^{\lambda t} (\lambda^2 + 3\lambda + 2) = 0$$

- assume $\alpha \neq 0$

$$\Rightarrow \lambda^2 + 3\lambda + 2 = 0$$

characteristic equation

Characteristic Polynomial

$$\Delta(\lambda) = \lambda^2 + 3\lambda + 2$$

Obtain from ODE:

$$\frac{d^2}{dt^2} \rightarrow \lambda^2$$

$$\frac{d}{dt} \rightarrow \lambda$$

Solution: solve quadratic equation

$$\lambda_{1,2} = \frac{-3 \pm \sqrt{9-8}}{2} = \begin{cases} -2 \\ -1 \end{cases}$$

$$\Rightarrow x_{n_1}(t) = \alpha_1 e^{-2t}$$

$$x_{n_2}(t) = \alpha_2 e^{-t}$$

both homogeneous solutions \Rightarrow linearity gives general solution

$$\underline{x_n(t) = C_1 e^{-2t} + C_2 e^{-t} \quad t \geq 0}$$

Step 2: particular solution

$$x_p(t) \equiv 0$$

Step 3: general solution

$$x_g(t) = x_n(t) = c_1 e^{-2t} + c_2 e^{-t}, \quad t \geq 0$$

Step 4: IVP

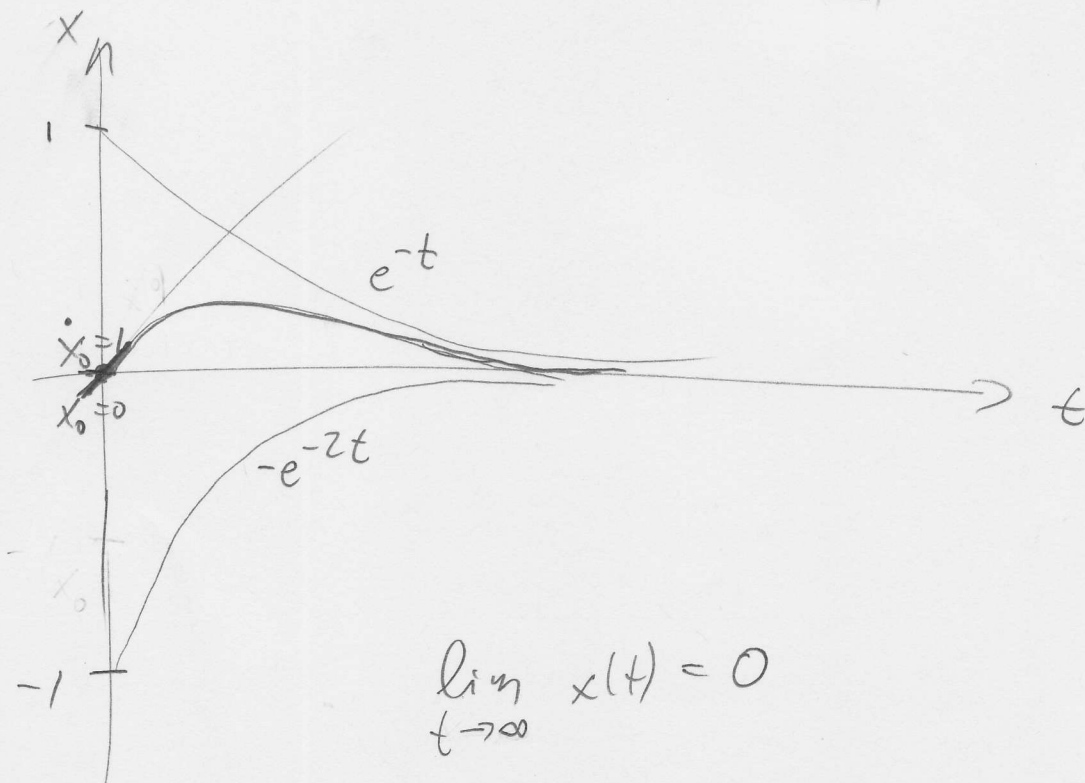
$$x(0) = c_1 + c_2 = 0$$

$$\dot{x}(0) = -2c_1 - c_2 = 1$$

$$\Rightarrow c_1 = -1$$

$$c_2 = 1$$

$$\Rightarrow \boxed{x(t) = -e^{-2t} + e^{-t}, \quad t \geq 0}$$



Example: Conjugate Complex natural frequencies

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$$\frac{d^2 x(t)}{dt^2} + 2 \frac{dx(t)}{dt} + 2 = 0, \quad t \geq 0, \quad x(0) = 2$$
$$\dot{x}(0) = -1$$

Step 1: Homogeneous Solution

$$\Delta(\lambda) = \lambda^2 + 2\lambda + 2$$

$$\Rightarrow \lambda_{1,2} = -1 \pm j$$

$$x_{h_1}(t) = c_1 e^{-(1-j)t}, \quad x_{h_2}(t) = c_2 e^{-(1+j)t}$$

$$x_h(t) = c_1 e^{-(1-j)t} + c_2 e^{-(1+j)t}, \quad t \geq 0$$

Step 2: Particular solution: $x_p(t) \equiv 0$

Step 3: general solution: $x_p(t) = x_h(t)$

Step 4: IVP

$$x(0) = c_1 + c_2 = 2$$

$$\dot{x}(0) = (-1+j)c_1 + (-1-j)c_2 = -1$$

$$\Rightarrow c_1 = 1 - \frac{1}{2}j$$

$$c_2 = 1 + \frac{1}{2}j$$

$$x_h(t) = \left(1 - \frac{1}{2}j\right) e^{-(1-j)t} + \left(1 + \frac{1}{2}j\right) e^{-(1+j)t}$$

We know $x_n(t)$ is real valued

Use conjugation identities:

$$c_1^* \cdot c_2^* = (c_1 c_2)^*$$

$$c_1 + c_1^* = 2 \operatorname{Re}(c_1)$$

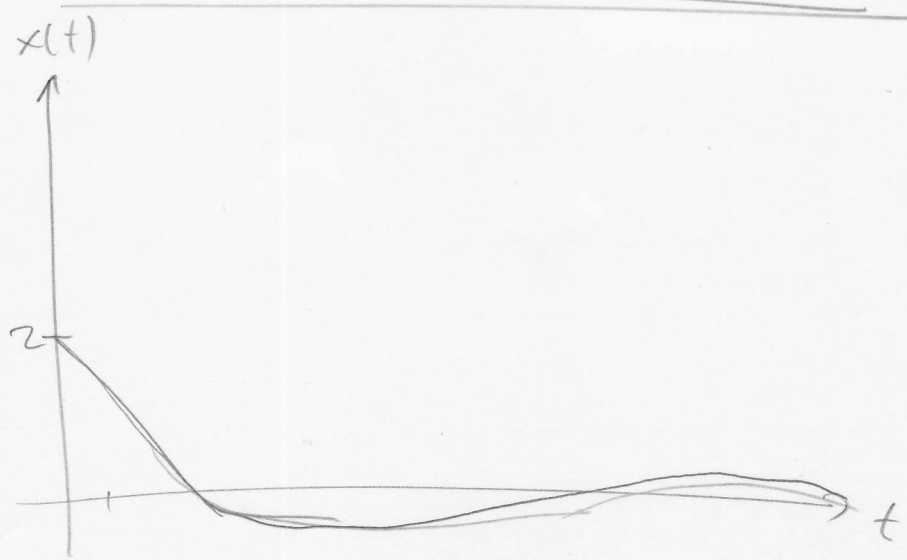
$$\Rightarrow x_n = 2 \operatorname{Re} \left((1 - \frac{1}{2}j) e^{-(1-j)t} \right)$$

Compute polar form of c_1 :

$$\begin{aligned} c_1 &= 1 - \frac{1}{2}j = |1 - \frac{1}{2}j| e^{j\theta} = \frac{\sqrt{5}}{2} e^{j \tan^{-1}(-\frac{1}{2})} \\ &= \frac{\sqrt{5}}{2} e^{-j 26.56^\circ} \end{aligned}$$

IVP solution:

$$\begin{aligned} x(t) &= 2 \operatorname{Re}(c_1 e^{-(1-j)t}) \\ &= 2 \operatorname{Re} \left(\frac{\sqrt{5}}{2} e^{-j 26.56^\circ} e^{-t} e^{jt} \right) = \sqrt{5} e^{-t} \operatorname{Re}(e^{j(-26.56^\circ)}) \stackrel{\text{Euler's Formula}}{=} \\ &= \sqrt{5} e^{-t} \cos(t - 26.56^\circ), \quad t \geq 0 \end{aligned}$$



General Case / Summary

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$$\frac{d^2 x(t)}{dt^2} + a_1 \frac{dx(t)}{dt} + a_0 x(t) = 0, \quad t \geq 0$$
$$x(0) = x_0$$
$$\dot{x}(0) = \dot{x}_0$$

Step 1: Homogeneous solution

Characteristic Polynomial:

$$\Delta(\lambda) = \lambda^2 + a_1 \lambda + a_0$$

$$\lambda_{1,2} = \frac{-a_1 \pm \sqrt{a_1^2 - 4a_0}}{2}$$

$$a_1^2 - 4a_0 > 0$$

$$\Rightarrow x_h(t) = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$$

Step 2: Particular solution : $x_p(t) \equiv 0$

Step 3: general solution : $x_g(t) = x_h(t)$

Step 4: IVP

$$c_1 + c_2 = x_0$$

$$\lambda_1 c_1 + \lambda_2 c_2 = \dot{x}_0$$

\Rightarrow solve equation

\Rightarrow find real representation (lots of algebra)

Closed Form Solution of IVP

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Use $\lambda_1 = \sigma_1 + j\omega_1$

$$x(t) = \frac{\sqrt{(\dot{x}_0 - \sigma_1 x_0)^2 + \omega_1^2 x_0^2}}{\omega_1} e^{\sigma_1 t} \cos\left(\omega_1 t - \underbrace{\tan^{-1} \frac{\dot{x}_0 - \sigma_1 x_0}{\omega_1 x_0}}_{\text{const}}\right)$$

