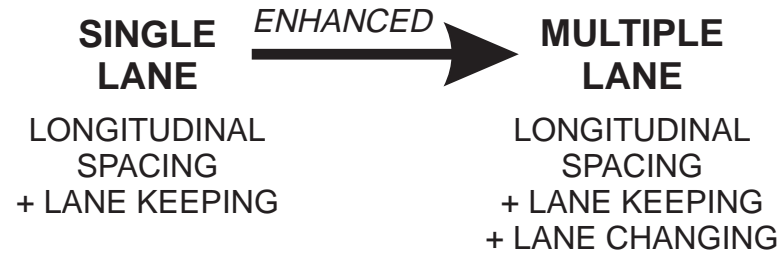
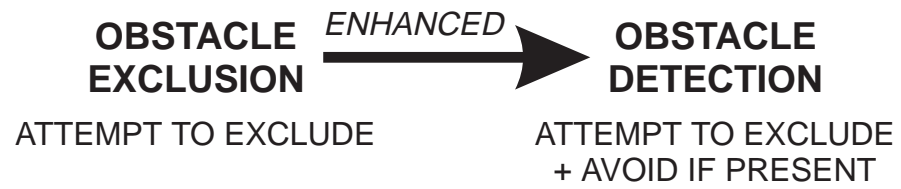




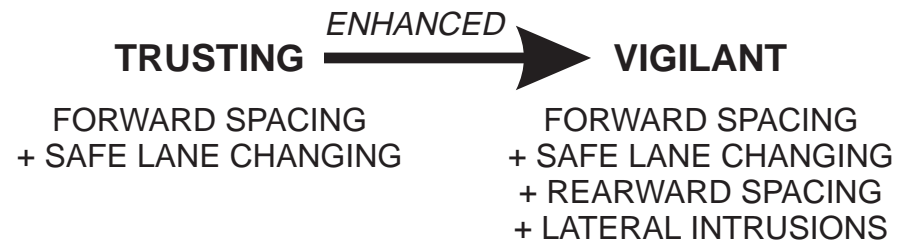
Koopman & Bayouth, Figure 1.



Koopman & Bayouth, Figure 2.



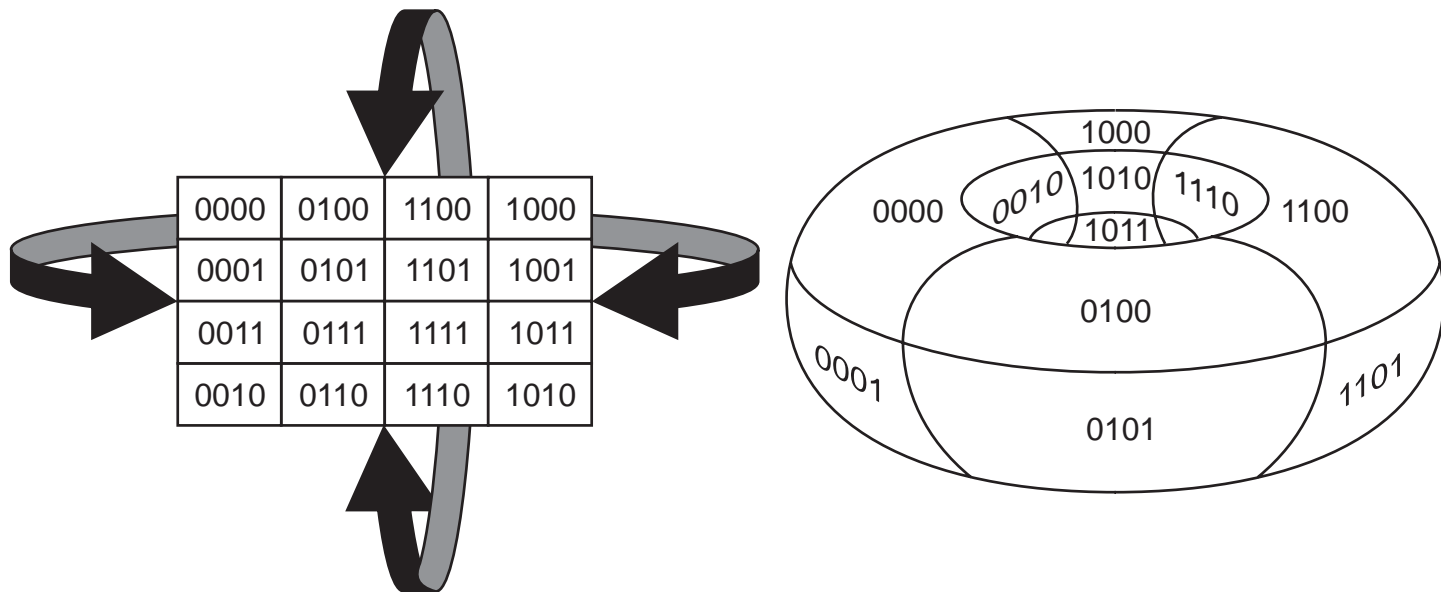
Koopman & Bayouth, Figure 3.



Koopman & Bayouth, Figure 4.

	0=BASELINE	1=ENHANCED
ENTITY SIZE	FREE AGENT	PLATOON
NUMBER OF AUTOMATED LANES	SINGLE LANE	MULTIPLE LANE
OBSTACLE STRATEGY	OBSTACLE EXCLUSION	OBSTACLE DETECTION
SYSTEM VIGILANCE	TRUSTING	VIGILANT

Koopman & Bayouth, Figure 5.



Koopman & Bayouth, Figure 6.


		FREE AGENT 0xxx		PLATOON 1xxx	
		SINGLE LANE x0xx	MULTIPLE LANES x1xx	MULTIPLE LANES x1xx	SINGLE LANE x0xx
OBSTACLE EXCLUSION xx0x	TRUSTING xxx0	0000 <i>"BASELINE CAPABILITIES"</i>	0100	1100 <i>"DEDICATED LANES"</i>	1000
	VIGILANT xxx1	0001	0101	1101	1001
OBSTACLE AVOIDANCE xx1x	VIGILANT xxx1	0011	0111 <i>"MIXED TRAFFIC"</i>	1111 <i>"ENHANCED CAPABILITIES"</i>	1011
	TRUSTING xxx0	0010	0110	1110	1010


➤ Possible deployment path A


➤ Possible deployment path B

Koopman & Bayouth, Figure 7.

		FREE AGENT 0xxx		PLATOON 1xxx	
		SINGLE LANE x0xx	MULTIPLE LANES x1xx	MULTIPLE LANES x1xx	SINGLE LANE x0xx
OBSTACLE EXCLUSION xx0x	TRUSTING xxx0	0000 <i>"BASELINE CAPABILITIES"</i>	0100	1100	1000
	VIGILANT xxx1	0001 ↓ M	0101 ↓	1101	1001
OBSTACLE AVOIDANCE xx1x	VIGILANT xxx1	0011 ⇒	0111 <i>"MIXED TRAFFIC"</i>	1111 <i>"ENHANCED CAPABILITIES"</i>	1011
	TRUSTING xxx0	0010	0110	1110	1010

 Hypothetically non-viable configuration

 Example planned deployment path

 Example alternate deployment path

Koopman & Bayouth, Figure 8.