

Recent Advances in the Mechanics of MEMS Acoustic Emission Sensors

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Abstract

Resonant sensors for acoustic emission detection have been designed and fabricated as MEMS capacitive transducers with resonant frequencies between 100 and 500 kHz. We report four recent advances in our understanding of their mechanics and in the implications of those advances for improved sensitivity. One advance involves a successful laboratory method to seal and evacuate the MEMS device within its ceramic package, thereby operating in a coarse vacuum and reducing or eliminating squeeze film and radiation damping effects; we present characterization measurements showing an approximate fourfold increase in quality factor Q . A second advance is a summary of our theoretical analysis of noise sources for a resonant, capacitive MEMS transducer; we report that Brownian noise associated with the impact of air molecules is the major source. A third advance is the use of a grillage of beams, rather than a perforated plate, as the moving plate in the spring-mass system; we present characterization measurements showing a significant reduction in damping and therefore a higher Q . The fourth advance is a finger-type mechanism to sense in-plane motion; we show characterization measurements confirming the resonant behavior of that device and showing that the in-plane device has a much higher Q than comparable out-of-plane devices.

Keywords: Damping; in-plane motion; MEMS; sensor innovation.

Introduction

Our research group has developed a series of MEMS devices to function as resonant transducers sensitive to out-of-plane motion. Their mechanics and their use as acoustic emission sensors are most completely described in a paper by Ozevin *et al.* [1]. The transducers are fabricated in the PolyMUMPS surface micromachining process as spring-mass systems to form capacitors in which the moving plate is an elastic structure in polysilicon with a thickness of 2 μm . We typically place on each chip a suite of transducers at different frequencies in the range up to 500 kHz, placing four transducers on a 5 x 5 mm chip or a larger number of transducers on a 10 x 10 mm chip.

Figure 1a shows a completed four-channel AE sensor system [2, 3]. It consists of a MEMS chip, nominally 5 x 5 mm, containing four independent transducers with resonant frequencies in the range between 126 and 500 kHz. The chip is mounted in a Spectrum Semiconductor Materials, CPG06856 pin-grid array ceramic package, 26 x 26 mm, chosen because it provides a smooth bottom surface for coupling to structural plates. The ceramic package engages a bottom PC board and Sullins 2.0 mm connectors engage a bottom PC board containing four amplifier circuits, as shown in Figure 1a, each with a nominal gain of 100 V/V. The whole system (apart from the cable connector) is contained in a volume of 35 x 35 x 30 mm.

Vacuum Sealing of a Perforated Plate Transducer

Among various mechanisms limiting the sensitivity of such transducers, the damping effect of air is very significant. Damping occurs both from acoustic radiation into the air and from squeeze-film damping as air is forced through the gap between the moving plate and the stationary plate. The effectiveness of a resonant transducer is related to its sharpness of resonance, or (equivalently) to its dynamic magnification, and is commonly calculated as the quality factor Q . Operation in coarse vacuum would reduce the damping effects and increase Q , and we report a practical laboratory method for sealing and evacuating the chip in its ceramic package.

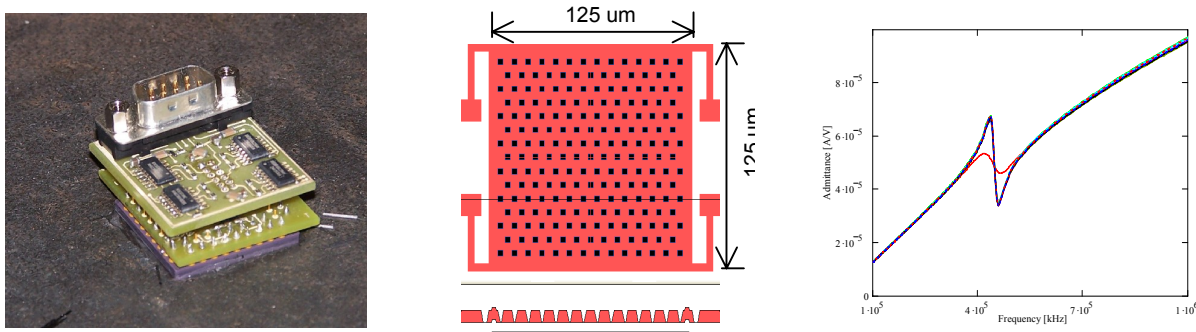


Figure 1a. Four-channel AE sensor system in 35 x 35 x 30 mm volume

1b. CAD layout and section of one unit

1c. Admittance at resonance, $f \sim 447$ kHz, $Q \sim 5.5$ (atmospheric), $Q \sim 19.7$ (evacuated)

Figure 1b is the CAD layout and section of a single unit, showing a perforated square plate (125 μm on a side, with 3.5 μm square etch holes on a triangular grid with 8 μm between holes) suspended by four flexural springs, with a gap of 1.25 μm between the plate and the underlying stationary electrode. FEM simulation was used in selecting the flexural spring length to achieve target design frequencies between 126 and 500 kHz. Each transducer consists of 144 units (a 12 x 12 array) to obtain a target design capacitance near 14 pF. Figure 1c shows the admittance plot for the transducer with nominal design frequency of 500 kHz, and resonance is observed near 447 kHz. The admittance plot depicts the sharpness of resonance before and after the process of sealing and evacuation. The broader resonance in Figure 1c is the admittance plot at atmospheric pressure, corresponding to a Q of 5.5.

For the different transducers (different resonant frequencies) the admittance measurements at atmospheric pressure showed Q factors ranging from 2.4 to 5.5, and the measured Q generally increased with transducer frequency, as predicted. In an attempt to make the transducers more sensitive we next developed a laboratory method to seal and evacuate the device within its package. The CPG06856 ceramic package product has an accompanying lid, plated with nickel and gold. In our method, a hole is drilled in the solder seal lid, the perimeter of the lid is soldered to the CPG06856 package, and a small amount of solder is dropped around the hole. The package is then moved to a vacuum chamber, within which a soldering iron can translate on a vertical axis. After the chamber is evacuated, the soldering iron is energized and the solder around the hole is melted, sealing the hole in the lid. After the solder cools, the package is removed from the vacuum chamber. This method has proven reliable and the resulting seal appears to be durable.

The sharper resonance in Figure 1c is a coincident set of numerous admittance plots repeated over a period of 28 days, showing no loss of vacuum, and corresponding to a Q of 19.7. The

increase observed in Q , approximately fourfold, is helpful in increasing the expected sensitivity of the transducer. However, it immediately raises the question, what factor is limiting the Q ? Internal damping in polysilicon is too low to explain the observed Q , which would correspond to 2.5% of critical damping. In our opinion, the observed Q is limited by other influences, such as imperfect coherence in the response of the 144 units that comprise the transducer. The 12 x 12 array occupies an area less than 2 mm square, which is small compared to the ultrasonic wavelength in steel at the frequencies (below 500 kHz) of our transducers, and therefore it is reasonable to expect that an arriving mechanical excitation will uniformly drive the units in the array. It is more likely that the 144 units do not have identical resonant frequencies. For example, the stiffness of the anchors, assumed to be rigid, will differ from the perimeter of the array to the interior, creating one source for slight deviations in the resonant frequencies. The effect of imperfect coherence would be a “spreading” of the aggregated peak, which is equivalent (in terms of our admittance test) to higher damping.

Noise Analysis

We recently developed a theoretical analysis of noise sources [4] in the electromechanical behavior of a resonant, capacitive-type transducer. We determine that Brownian noise from impact excitation of the moving plate by air molecules, as examined by Gabrielson [5], is the mechanism of primary interest. Summarizing those findings here, we report the RMS amplitude of the current resulting from such agitation to be

$$i_{RMS} = \frac{V_{DC} C_0}{g} \sqrt{4k_B T} \cdot \left[\sqrt{m\omega_0} \int f(\omega, Q) d\omega \right]$$

where V_{DC} is the DC bias voltage, g is the gap between the capacitor plates, C_0 is the capacitance at rest, k_B is the Boltzmann constant, T is the temperature ($^{\circ}\text{K}$), ω_0 is the circular resonant frequency, and m is the mass of the spring-supported plate. The term in square brackets, with its integral, captures the dynamic response of the resonator to air molecule impact, and therefore depends upon the quality factor Q , together with the influence of amplifier bandwidth; the reader is referred elsewhere [4] for the derivation and details. For a strongly peaked resonator, with suitable amplifier bandwidth, the term in square brackets tends to a result that is independent of Q . Recent measurements over a wide range of design resonant frequencies (from 126 to 500 kHz) show reasonable comparison between the predicted and measured noise level [4].

Grillage Transducer for Out-of-Plane Motions

We report on a new transducer mechanism, fabricated in 2007, an out-of-plane sensor with a design frequency of 250 kHz. The design features a moving plate constructed as a grillage rather than as a perforated plate with periodically spaced etch holes. We show characterization measurements suggesting two advantages to the grillage geometry. Capacitance measurements and FEM simulations show the grillage to approximate a whole plate in its electrical behavior, and admittance measurements show the grillage to have higher Q (lower damping) than a comparable perforated plate.

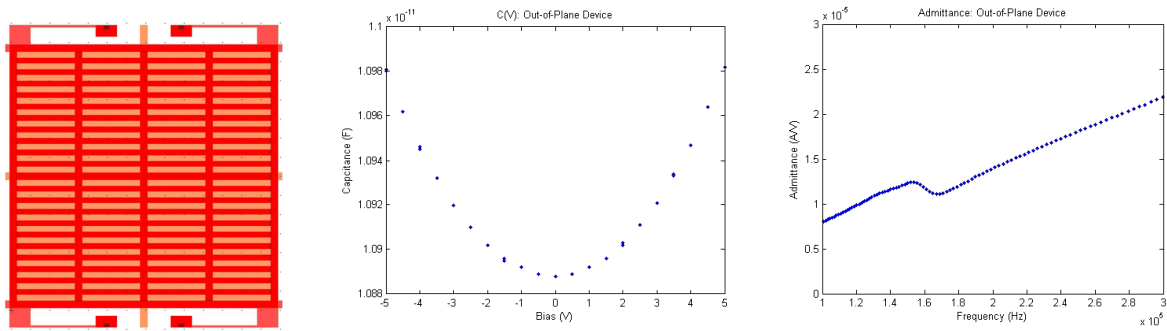


Figure 2a. CAD layout of grillage unit for out-of-plane sensing
 2b. C-V plot, $C_0 \sim 10.9$ pF
 2c. Admittance at resonance, $f \sim 160$ kHz, $Q \sim 6.7$

Figure 2a is the CAD layout of a single unit, showing a grillage (outside dimensions $138 \times 140 \mu\text{m}$) supported by four flexural springs; the beams forming the grillage are $3 \mu\text{m}$ in width, with a clear spacing of $3 \mu\text{m}$ between beams, and a gap of $1.25 \mu\text{m}$ between the grillage and the underlying stationary electrode. FEM simulation was used in selecting the flexural spring length to achieve the target design frequency of 250 kHz. The transducer consists of 72 units (a 9×8 array) to obtain a target design capacitance, C_0 , of 5.8 pF, calculated based upon the net area of the grillage. Figure 2b shows the C-V plot, referring to the capacitance as a function of applied DC voltage. A capacitive spring-mass system should show an increase in capacitance with applied DC voltage, because the electrostatic attraction force will deflect the system, reduce the gap, and thereby increase the capacitance. The C-V plot confirms the expected behavior of the transducer, but it indicates a C_0 near 10.9 pF. Subsequent FEM simulations show that the capacitance closely approximates that of the gross area of a whole plate rather than the net area of a grillage; in other words, the “cutouts” between grillage beams do not diminish the capacitance. Figure 2c shows the admittance plot in the vicinity of resonance, which is observed to occur near 160 kHz. (The difference between predicted and observed frequency is not of great concern, and is attributed to support flexibility and to fabrication deviations in the spring thickness.) Figure 2c depicts the sharpness of resonance, from which a Q near 6.7 is extracted. A comparable perforated plate transducer (as depicted in Figure 1b) with a resonant frequency of 182 kHz displayed a Q near 2.0 , and therefore the grillage geometry represents substantial improvement. (Considering squeeze-film and radiation damping in air, by theory Q will increase with frequency, and therefore comparisons must be taken between transducers at comparable resonant frequencies.) Compared to a perforated plate, we predicted that the grillage geometry would decrease the damping by permitting freer venting of the air beneath the grillage, thus reducing the squeeze film damping; we interpret these results as evidence qualitatively confirming that prediction.

Finger Transducer for In-Plane Motions

Finally, we report on another new 2007 transducer, designed to sense in-plane motion. It is a finger-type (comb-type) capacitive transducer with a design frequency of 250 kHz. The predicted Q is much higher (predicted damping is much lower) than for out-of-plane sensors, because in-plane motion mostly produces only a direct shearing of air in the gap, rather than a squeeze-film or radiation actuation of the air. At the same time, squeeze-film damping in the out-of-plane direction is used beneficially to isolate the desired in-plane mechanical response from the unwanted out-of-plane response.

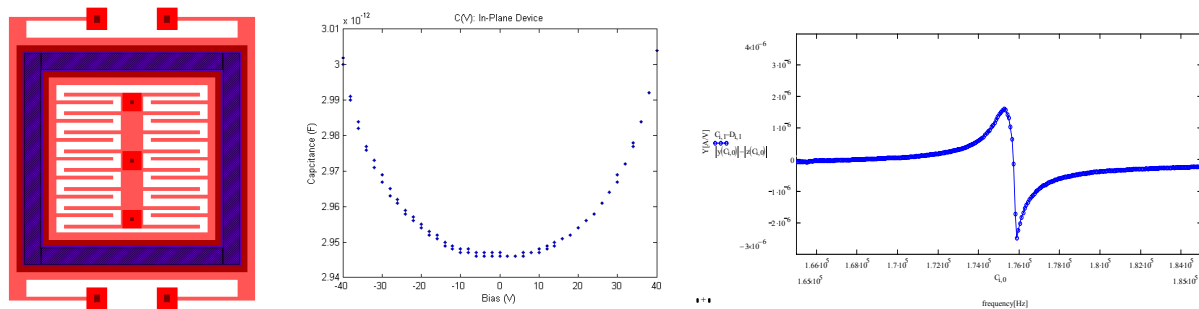


Figure 3a. CAD layout of finger-type transducer to sense in-plane motion in the y-direction
 3b. C-V plot, $C_0 \sim 2.95$ pF
 3c. Admittance at resonance, $f \sim 176$ kHz, $Q \sim 197$

Figure 3a is the CAD layout of a single unit ($128 \times 132 \mu\text{m}$) showing a stationary central spine with projecting fingers, which form capacitors in relation to fingers that project from a frame supported by four flexural springs and oriented to sense motion in the y-direction; the pitch between fingers is unsymmetrical in order to effect a change in capacitance during motion. Again, FEM simulation was used in selecting the flexural spring length to achieve the target design frequency of 250 kHz, and to calculate the predicted capacitance C_0 , which is significantly and beneficially influenced by the effects of fringe capacitance. The transducer consists of 532 units (a 19×28 array) to obtain a target design capacitance, C_0 , of 3.1 pF. Figure 3b shows the C-V plot, confirming the expected behavior of the transducer with a measured C_0 near 2.95 pF. Figure 3c shows the admittance plot in the vicinity of resonance, which is observed to occur near 176 kHz, and the sharp resonance corresponds to a Q near 197. The characterization measurements confirm the design characteristics outlined above, and suggest that the transducer may provide a practical approach to sensing in-plane particle displacements. In principle, the transducer can be fabricated on one MEMS chip together with a similar transducer orthogonal to it, along with a third transducer sensitive to out-of-plane motion, creating a sensor system responding to the three-dimensional components of particle motion.

Summary

We have described four recent advances in our understanding of the mechanics of capacitive MEMS transducers resonant in the range between 100 and 500 kHz. We seek to improve the sensitivity of these transducers as acoustic emission sensors, and the advances provide insights for those improvements. Among other factors, damping and noise limit transducer sensitivity, and all four advances guide us to better sensitivity. We have shown an effective laboratory approach for sealing and evacuating a device, thereby reducing the squeeze film and radiation damping effects of air. Characterization experiments show an approximate fourfold increase in quality factor Q . We have also summarized our recent theoretical analysis of noise, identifying the effective floor to result from Brownian motion and the impact of air molecules with the resonator, confirmed by our measurements. We have reported a significant reduction in squeeze film damping, in air, when using a grillage of beams as the moving plate rather than a perforated plate with periodically spaced etch holes. Finally, we have reported our first characterization measurements of a new transducer designed to sense in-plane motion. Those results confirm its design characteristics, and show it to be minimally damped (in air) because the in-plane motion mostly produces a shearing of an air volume rather than a squeeze film or radiation excitation of the air volume.

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